

**EXISTENCE RESULTS TO $-\Delta_p u = V(x)f(u)$ IN A
BOUNDED DOMAIN OF \mathbb{R}^d**

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1. INTRODUCTION

In this paper we shall investigate the existence of weak solutions of the Dirichlet p -Laplacian problem:

$$\begin{cases} -\Delta_p u &= V(x)f(u) \text{ in } \Omega \\ u &= 0 \text{ on } \partial\Omega, \end{cases}$$

where Ω is a bounded smooth open set of \mathbb{R}^d and $p > 1$. We will exhibit a sufficient condition on the norm of the positive function V which belong to a certain space depending on the position of p and d . The map f considered here is supposed continuous, positive and non decreasing. The case $p = 2$ was treated in [12]. Along this investigation we will use some regularity results (see [10] or [19]) and estimations (see [14]) for the potential to replace the lack of linearity. The proof in the case $p = 2$ can be seen as a direct approach using estimations for the Green function. We will show also a kind of sharpness of our estimations for certain class of functions V .

There are two different cases to distinguish for the study of this problem:

- The case where $f(0) > 0$, the trivial solution is eliminated. We will show the existence of a positive solution using the topological degree theory applied to the operator $T_V : C_0(\overline{\Omega}) \rightarrow C_0(\overline{\Omega})$. This operator is defined by $T_V(v) = u$ if and only if u satisfies

$$\begin{cases} -\Delta_p u &= V(x)f(v) \text{ in } \Omega \\ u &= 0 \text{ on } \partial\Omega. \end{cases}$$

- The second case where $f(0) = 0$, we shall find a way to eliminate the trivial solution. Therefore we will use a classical minimization technic and we will show that the energy of the solution is negative, so the problem have a non trivial solution.

2. MAIN RESULTS

Let us consider the Dirichlet problem

$$\begin{cases} -\Delta_p u &= V(x)f(u) \text{ in } \Omega \\ u &= 0 \text{ on } \partial\Omega \end{cases} \tag{P}$$

where Ω is a bounded smooth open set of \mathbb{R}^d and V is a positive function which belong to a certain space depending on the value of $1 < p < \infty$. The non linearity f is a nondecreasing continuous positive function.

We will denote

$$E = \begin{cases} L^q(\Omega), q > \frac{d}{p}, \text{ if } p < d \\ L^1(\text{Log}(L)^\beta)(\Omega), \beta > d - 1, \text{ if } p = d \\ L^q(\Omega), q \geq 1 \text{ if } p > d \end{cases}$$

and $\| \cdot \|_E$ the corresponding norm.

The main result of this paper can be stated as follows.

Theorem 2.1. *Let $1 < p < \infty$, if $V \in E$, then there exists a constant $c = c(d, p, \Omega)$ such that, if $f(0) > 0$ and V satisfies*

$$\|V\|_E < c \sup_{\alpha > 0} \frac{\alpha^{p-1}}{f(\alpha)} \tag{2.1}$$

then (P) have at least one positive bounded solution u . Furthermore, this solution is stable i.e. $d(I - T_V, \mathcal{M}, 0) = 1$ where \mathcal{M} is a set to be pointed out later in the proof.

Theorem 2.2. *Under the same assumptions of Theorem 2.1, if we suppose furthermore that $(\lambda^{-\gamma}V(\frac{x}{\lambda}))_{\lambda > 0}$ converges weakly in measure to a positive Radon measure μ when $\lambda \rightarrow \infty$ for a constant $\gamma > p$ and that 0 is an isolated zero of f , then (P) have at least one positive solution.*

As an example for such function V one can think about a $-\gamma$ -homogeneous function, or a combination of an approximation of the identity and an homogeneous function such that $(\lambda^{-\gamma}V(\frac{x}{\lambda}))_{\lambda > 0}$ converges to a Dirac.

Now if Ω' is an open set contained in Ω , we denote $\lambda_1(\Omega', \psi)$ the first eigenvalue of the p -Laplace operator in the set Ω' with weight function ψ , i.e

$$\lambda_1(\Omega', \psi) = \inf \left\{ \int_{\Omega'} |\nabla u|^p ; \int_{\Omega'} |u|^p \psi = 1, u \in H_0^1(\Omega') \right\}.$$

So we can state the following theorem.

Theorem 2.3. *Assume that $\tilde{V} = \frac{V}{\|V\|_E} \in \mathcal{H}_\psi(\Omega') = \{v \in E; v > \psi \text{ on } \Omega'\}$, where $\psi \in E$ is a positive function, then there exist $\lambda^* \in [0, +\infty]$ such that:*

- i) if $\|V\|_E < \lambda^*$, problem (P) have at least one positive solution.*
- ii) if $\|V\|_E > \lambda^*$, problem (P) have no positive solution.*

Moreover, we have the following estimation :

$$c(p, d, \Omega) \sup_{\alpha > 0} \frac{\alpha^{p-1}}{f(\alpha)} \leq \lambda^* \leq \lambda_1(\Omega', \psi) \sup_{\alpha > 0} \frac{\alpha^{p-1}}{f(\alpha)}.$$

Corollary 2.4. Assume that $\tilde{V} = \frac{V}{\|V\|_E} \in \mathcal{H}_\delta(\Omega) = \{v \in E; v > \delta\}$, then there exist $\lambda^* \in [0, +\infty]$ such that :

i) if $\|V\|_E < \lambda^*$, problem (P) have at least one positive solution.

ii) if $\|V\|_E > \lambda^*$, problem (P) have no positive solution.

Moreover, we have the following estimation :

$$c(p, d, \Omega) \sup_{\alpha > 0} \frac{\alpha^{p-1}}{f(\alpha)} \leq \lambda^* \leq \frac{\lambda_1}{\delta} \sup_{\alpha > 0} \frac{\alpha^{p-1}}{f(\alpha)}.$$

3. PRELIMINARY RESULTS

Lemma 3.1. Let $u_1, u_2 \in W_0^{1,p}(\Omega)$, there exist a constant c_p such that

$$\langle -\Delta_p u_1 - (-\Delta_p u_2), u_1 - u_2 \rangle \geq \begin{cases} c_p |\nabla u_1 - \nabla u_2|^p, & \text{if } p \geq 2 \\ c_p \frac{|\nabla u_1 - \nabla u_2|^2}{(|\nabla u_1| + |\nabla u_2|)^{2-p}}, & \text{if } 1 < p < 2 \end{cases}$$

Consider the problem

$$\begin{cases} -\Delta_p u = f(x, u) \text{ in } \Omega \\ u = 0 \text{ on } \partial\Omega, \end{cases} \tag{3.1}$$

where $f : \Omega \times \mathbb{R} \rightarrow \mathbb{R}$ is a Carathéodory function.

Definition 3.2. We say that \bar{U} is a super-solution of (3.1) if $\bar{U} \in W_0^{1,p}(\Omega) \cap L^\infty(\Omega)$ and

$$\begin{cases} -\Delta_p \bar{U} \geq f(x, \bar{U}) \text{ in } \Omega \\ \bar{U} \geq 0 \text{ on } \partial\Omega. \end{cases}$$

Respectively, we say that \underline{U} is a sub-solution of (3.1) if $\underline{U} \in W_0^{1,p}(\Omega) \cap L^\infty(\Omega)$ and

$$\begin{cases} -\Delta_p \underline{U} \leq f(x, \underline{U}) \text{ in } \Omega \\ \underline{U} \leq 0 \text{ on } \partial\Omega. \end{cases}$$

Theorem 3.3 ([7]). Let us assume the following conditions :

i) The problem (3.1) have a sub-solution \underline{U} and a super-solution \bar{U} such that $\underline{U} \leq \bar{U}$.

ii) There exist $K \in L^q(\Omega)$, $q > (p^*)'$, such that

$$|f(x, s)| \leq K(x), \text{ a.e. } x \in \Omega, \forall s : \underline{U}(x) \leq s \leq \bar{U}(x).$$

Then (3.1) have at least one solution between \underline{U} and \bar{U} .

Let us define the Orlicz-Zygmund space $L^s \text{Log}^\beta L$, $1 \leq s, \beta \in \mathbb{R}$.

Definition 3.4. Let f be a measurable function in Ω , we say that

$$f \in L^s \text{Log}^\beta L(\Omega) \text{ if } \int_\Omega |f|^s \log^\beta(e + |f|) < +\infty.$$

This space is equipped with the Luxemburg norm defined by

$$\|f\|_{L^s \text{Log}^\beta L} = \inf \left\{ \lambda > 0; \int_\Omega \frac{|f|^s}{|\lambda|^s} \log^\beta \left(e + \frac{|f|}{|\lambda|} \right) \leq 1 \right\}$$

Remark that for $\beta \geq 0$, $L^s \text{Log}^\beta L(\Omega) \subset L^s(\Omega)$ and if we note

$$[f]_{\alpha,s} = \int_\Omega |f|^s \log^\beta \left(e + \frac{|f|}{\|f\|_{L^s}} \right),$$

then

$$\|f\|_{L^s \text{Log}^\beta L} \leq [f]_{\alpha,s} \leq 2 \|f\|_{L^s \text{Log}^\beta L}.$$

4. PROOF OF THEOREMS

4.1. Proof of Theorem 2.1. STEP 1: Boundedness results.

We start with the case $p < d$.

Lemma 4.1 ([1]). *Let $u \in W_0^1(\Omega)$ and $f \in W^{-1,r}(\Omega)$ where $r > \frac{d}{p-1}$ and $p < d$, such that*

$$\begin{cases} -\Delta_p u = f & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega \end{cases} \tag{4.1a}$$

then $u \in L^\infty(\Omega)$, furthermore if we take F such that $f = \text{div}F$ then

$$\|u\|_{L^\infty(\Omega)} \leq c(p, d, \Omega) \|F\|_{L^r}^{\frac{1}{p-1}}.$$

Before proving this lemma we will use the following result, introduced by Stampacchia for the study of the regularity of elliptic equation in [17].

Lemma 4.2 ([12]). *Let $\varphi : [k_0, +\infty[\rightarrow \mathbb{R}_+$ be non decreasing function, such that if $k_0 \leq k < h$ then $\varphi(h) \leq \frac{c}{(h-k)^\alpha} \varphi(k)^\beta$, where c, α and β are given positive constants. If $\beta > 1$, then $\varphi(k_0 + l) = 0$ where*

$$l^\alpha = c [\varphi(k_0)]^{\beta-1} 2^{\frac{\alpha\beta}{\beta-\alpha}}.$$

Proof. To proof these theorem we will use the classical Stampacchia approach.

Since $f \in W^{-1,r}(\Omega)$, there exist $F \in L^r(\Omega)$ such that $f = \text{div}F$ and then we have

$$\int_\Omega |\nabla u|^{p-2} \nabla u \nabla v = \int_\Omega F \cdot \nabla v, \quad \forall v \in W_0^{1,p}(\Omega). \tag{4.2}$$

So if we take for $k > 0$ the following test function

$$v = \text{sign}(u - k)(|u| - k)^+ = \begin{cases} u - k & \text{if } u > k \\ 0 & \text{if } -k \leq u \leq k \\ u + k & \text{if } -k > u. \end{cases}$$

(4.2) become

$$\int_{A(k)} |\nabla v|^p = \int_{\Omega} F \cdot \nabla v,$$

where $A(k) = \{|u| > k\}$. Using Hölder inequality, we have

$$\int_{\Omega} F \cdot \nabla v \leq \text{mes}(A(k))^{1-\frac{1}{p}-\frac{1}{r}} \left(\int_{A(k)} |F|^q \right)^{\frac{1}{r}} \left(\int_{A(k)} |\nabla v|^p \right)^{\frac{1}{r}}.$$

So that

$$\left(\int_{A(k)} |\nabla v|^p \right)^{1-\frac{1}{p}} \leq \text{mes}(A(k))^{1-\frac{1}{p}-\frac{1}{r}} \left(\int_{A(k)} |F|^r \right)^{\frac{1}{r}}.$$

Using Sobolev embeddings, there exist $C > 0$ such that

$$C \left(\int_{A(k)} |\nabla v|^{p^*} \right)^{\frac{p}{p^*}} \leq \text{mes}(A(k))^{1-\frac{1}{p}-\frac{1}{r}} \left(\int_{A(k)} |F|^r \right)^{\frac{1}{r}}$$

note that if $0 < k < h$ then $A(h) \subset A(k)$ and that implies

$$\text{mes}(A(h))^{\frac{1}{p^*}}(h-k) = \left(\int_{A(h)} (h-k)^{p^*} \right)^{\frac{1}{p^*}} \leq \left(\int_{A(h)} |v|^{p^*} \right)^{\frac{1}{p^*}} \leq \left(\int_{A(k)} |v|^{p^*} \right)^{\frac{1}{p^*}}$$

finally we have

$$\text{mes}(A(h)) \leq \frac{\|F\|_{L^r}^{\frac{p^*}{p-1}}}{C^{\frac{p^*}{p}}(h-k)^{p^*}} \text{mes}(A(k))^{p^*(\frac{1}{p}-\frac{1}{(p-1)r})}$$

and using the fact that $r > \frac{d}{p-1}$, we have $p^*(\frac{1}{p}-\frac{1}{(p-1)r}) > 1$ so we apply the Stampacchia's lemma to $\varphi(h) = \text{mes}(A(h))$ to obtain

$$\|u\|_{\infty} \leq c \frac{\|F\|_{L^r}^{\frac{1}{p-1}}}{C^{\frac{1}{p}}} \text{mes}(\Omega)^{(\frac{1}{p}-\frac{1}{(p-1)r})-\frac{1}{p^*}}.$$

□

The case $d = p$ is more different than the previous.

The Orlicz-Zygmund spaces are defined using the function $P_{\beta} : \mathbb{R}^+ \rightarrow \mathbb{R}$ such that $P_{\beta}(t) = t \log(e + s^{\beta})$.

Lemma 4.3. *If $c > 1$ then for s small enough,*

$$sP_{\beta}^{-1} \left(\frac{1}{s} \right) \leq \frac{c}{(\log(e + \frac{1}{s}))^{\beta}}.$$

Proof. It is easy to show that

$$\lim_{x \rightarrow +\infty} \frac{1}{x} P_\beta \left(\frac{cx}{(\log(e+x))^\beta} \right) = c > 1,$$

and so the lemma is proved. □

Now we can state a result similar to Lemma 4.1

Lemma 4.4 ([4]). *Let $u \in W_0^{1,d}(\Omega)$ satisfying $-\Delta_d u = f$, assume that $f \in L^1(\log L)^\beta(\Omega)$, where $\beta > d - 1$ then $u \in L^\infty(\Omega)$. More precisely*

$$\|u\|_{L^\infty} \leq C(\Omega, d) \left(\|f\|_{L^1(\log L)^\beta(\Omega)} \right)^{\frac{1}{d-1}}.$$

Proof. We know that

$$\int_\Omega |\nabla u|^{d-2} \nabla u \nabla v = \int_\Omega f v$$

for every test function $v \in W^{1,d}(\Omega)$. We define for $k > 0$,

$$T_k(s) = \begin{cases} s & \text{if } |s| < k \\ k \frac{s}{|s|} & \text{if } |s| \geq k \end{cases}$$

and for $\varepsilon > 0$ we take $v_\varepsilon = \frac{1}{\varepsilon} (T_{k+\varepsilon}(u) - T_k(u))$. Since Ω is bounded, $v_\varepsilon \in W_0^{1,1}(\Omega)$ and by the Sobolev imbedding we obtain

$$C_d \|v_\varepsilon\|_{L^{\frac{d}{d-1}}} \leq \|\nabla v_\varepsilon\|_{L^1} = \frac{1}{\varepsilon} \int_{\{k < |u| < k+\varepsilon\}} |\nabla u|.$$

We define $F_\varepsilon(t) = \min(t^+, 1)$, so

$$C_d \|F_\varepsilon(|u| - k)\|_{L^{\frac{d}{d-1}}} \leq \frac{1}{\varepsilon} \int_{\{k < |u| < k+\varepsilon\}} |\nabla u|.$$

In the other side, we have for $s > 1$,

$$\varphi(k + \varepsilon) = \int_{\{|u| > k+\varepsilon\}} \leq \int_\Omega |F_\varepsilon(|u| - k)|^s$$

where $\varphi(k) = \text{mes } \{|u| > k\}$. And for $s = \frac{d}{d-1}$ we have

$$\varphi(k + \varepsilon) \leq \left(\frac{1}{\varepsilon} \int_{\{k < |u| < k+\varepsilon\}} |\nabla u| \right)^{\frac{d}{d-1}}.$$

By Hölder's inequality we have

$$\begin{aligned} \varphi(k + \varepsilon) &\leq \left(\frac{1}{\varepsilon} \int_{\{k < |u| < k+\varepsilon\}} |\nabla u|^d \right)^{\frac{1}{d-1}} \left(\frac{\text{mes } (\{k < |u| < k + \varepsilon\})}{\varepsilon} \right) \\ &\leq \left(\frac{1}{\varepsilon} \int_{\{k < |u| < k+\varepsilon\}} |\nabla u|^d \right)^{\frac{1}{d-1}} \left(\frac{\varphi(k) - \varphi(k + \varepsilon)}{\varepsilon} \right). \end{aligned}$$

Finally we note

$$\Phi_{k,\varepsilon}(s) = \begin{cases} 0, & \text{if } 0 \leq s \leq k \\ s - k, & \text{if } k \leq s \leq k + \varepsilon \\ \varepsilon, & \text{if } s \geq k + \varepsilon, \end{cases}$$

so we have

$$\int_{\{k < |u| < k + \varepsilon\}} |\nabla u|^n = \langle -\Delta_n u, \Phi_{k,\varepsilon}(u) \rangle \leq \int_{\Omega} f \Phi_{k,\varepsilon}(u) \leq \varepsilon \int_{\{|u| > k\}} |f|.$$

But we know that in the dual space we have

$$\|\chi_E\|_{(L^1(\log L)^\beta(\Omega))^*} \leq \text{mes}(E) P_\beta^{-1}\left(\frac{1}{\text{mes}(E)}\right),$$

then if we use Lemma 4.2 we obtain

$$\int_{\{|u| > k\}} |f| \leq \|f\|_{L^1(\log L)^\beta(\Omega)} \frac{c}{\left(\log\left(1 + \frac{1}{\varphi(k)}\right)\right)^\beta}.$$

Thus

$$\varphi(k + \varepsilon) \leq C \|f\|_{L^1(\log L)^\beta(\Omega)}^{\frac{1}{d-1}} \frac{1}{\left(\log\left(1 + \frac{1}{\varphi(k)}\right)\right)^{\frac{\beta}{d-1}}} \left(\frac{\varphi(k) - \varphi(k + \varepsilon)}{\varepsilon}\right),$$

then

$$\varphi(k) \leq -C \|f\|_{L^1(\log L)^\beta(\Omega)}^{\frac{1}{d-1}} \frac{1}{\left(\log\left(1 + \frac{1}{\varphi(k)}\right)\right)^{\frac{\beta}{d-1}}} \varphi'(k),$$

so

$$1 \leq -C \|f\|_{L^1(\log L)^\beta(\Omega)}^{\frac{1}{d-1}} \frac{1}{\left(\log\left(1 + \frac{1}{\varphi(k)}\right)\right)^{\frac{\beta}{d-1}}} \frac{\varphi'(k)}{\varphi(k)}.$$

After integration we obtain

$$\frac{1}{\gamma} \left[\frac{1}{\left(\log\left(\frac{1}{\text{mes}\Omega}\right)\right)^\gamma} - \frac{1}{\left(\log\left(\frac{1}{\varphi(t)}\right)\right)^\gamma} \right] \geq t \left[C \|f\|_{L^1(\log L)^\beta(\Omega)}^{\frac{1}{d-1}} \right]^{-1},$$

where $\gamma = \frac{\beta}{d-1} - 1$. Then

$$\frac{1}{\left(\log\left(\frac{1}{\text{mes}\Omega}\right)\right)^\gamma} - \gamma t \left[C \|f\|_{L^1(\log L)^\beta(\Omega)}^{\frac{1}{d-1}} \right]^{-1} \geq \frac{1}{\left(\log\left(\frac{1}{\varphi(t)}\right)\right)^\gamma}$$

and consequently we have the existence of t_0 such that $\varphi(t_0) = 0$ and moreover

$$\|u\|_{L^\infty} \leq C(\Omega, d) \left(\|f\|_{L^1(\log L)^\beta(\Omega)} \right)^{\frac{1}{n-1}}. \quad \square$$

The case $p > d$ is a trivial case. It is a direct consequence from the Sobolev embedding.

Lemma 4.5. *Let $u \in W_0^{1,p}(\Omega)$ and $f \in L^1(\Omega)$ such that*

$$\begin{cases} -\Delta_p u = f & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega. \end{cases} \tag{4.3a}$$

Then $u \in L^\infty(\Omega)$, furthermore there exists $c = c(d, \Omega, p)$ such that

$$\|u\|_{L^\infty} \leq c \|f\|_{L^1}^{\frac{1}{p-1}}.$$

Remark 4.6. i) The spaces used in this proof are in some way optimal if $d > 2$, in fact we can show that the problem

$$\begin{cases} -\Delta_p u = f & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega \end{cases} \tag{4.4}$$

have a non bounded solution if $f \in L^1(\log L)^{d-1}(\Omega)$. We consider the function

$$f(r) = r^{-d} |\log(r)|^{-d} |\log |\log r||^{-\alpha}.$$

We have, if $\alpha > 1$, $f \in L^1(\log L)^{d-1}(\Omega)$ where Ω is a small ball, and $f \notin L^1(\log L)^\beta(\Omega)$ for all $\beta > d - 1$. And we can show that the corresponding solution of (4.4) is not bounded if $\alpha \leq d - 1$.

ii) In the case $p = d = 2$, we can use the Hardy spaces and we can show the optimality of these spaces (see [12]).

The coming two steps are common for all cases of p .

STEP 2: The super-solution.

Let $\alpha > 0$ and \bar{U} the solution of

$$\begin{cases} -\Delta_p u = V(x)f(\alpha) & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega. \end{cases}$$

Since $V \in E$, we have, using Lemma 4.1, 4.4 or 4.5,

$$\|\bar{U}\|_{L^\infty(\Omega)} \leq c(p, d, \Omega) \|V\|_E^{\frac{1}{p-1}} f(\alpha)^{\frac{1}{p-1}}.$$

So if

$$\|V\|_{L^q} < c \sup_{\alpha > 0} \frac{\alpha^{p-1}}{f(\alpha)},$$

then there exist $\alpha > 0$ such that $\|\bar{U}\|_{L^\infty(\Omega)} \leq \alpha$, and consequently, \bar{U} is a super-solution of (P).

STEP 3: Existence and stability.

Let us define

$$\tilde{f}(s) = \begin{cases} f(\bar{U}) & \text{if } s \geq \bar{U} \\ f(s) & \text{if } 0 \leq s \leq \bar{U} \\ f(0) & \text{if } 0 \geq s. \end{cases}$$

We note $\tilde{T}_V : C_0(\Omega) \rightarrow C_0(\Omega)$ the operator defined by $\tilde{T}_V(v) = u$ if and only if

$$\begin{cases} -\Delta_p u &= V(x)\tilde{f}(v) \text{ in } \Omega \\ u &= 0 \text{ on } \partial\Omega. \end{cases}$$

We know that \tilde{T}_V is a compact operator and if $v \in C_0(\Omega)$ then

$$\tilde{T}_V(v) \in B\left(0, c(p, n, \Omega) \|V\|_E^{\frac{1}{p-1}} \tilde{f}(\|\bar{U}\|_\infty)^{\frac{1}{p-1}}\right).$$

So \tilde{T}_V is uniformly bounded. This imply the existence of an $R_0 > 0$ such that

$$\forall R > R_0, d(I - \tilde{T}_V, B(0, R), 0) = 1,$$

where d denote the topological degree in $C_0(\Omega)$. In fact, let us consider the homotopy

$$H(\cdot, t) = I - t\tilde{T}_V, \forall t \in [0, 1].$$

This homotopy is admissible for R sufficiently large. Because if there exists $u \in C_0(\Omega)$ such that $\|u\|_\infty = R$ and $u = t\tilde{T}_V(u)$, then $R = \|u\|_\infty = t\|\tilde{T}_V(u)\| \leq R_0$ which is impossible. So it follow that

$$d(H(\cdot, 1), B(0, R), 0) = d(H(\cdot, 0), B(0, R), 0) = d(I, B(0, R), 0) = 1.$$

Consider now, the operator T_V defined by $T_V(v) = u$ iff

$$\begin{cases} -\Delta_p u &= V(x)f(v) \text{ in } \Omega \\ u &= 0 \text{ on } \partial\Omega. \end{cases}$$

We have the fact that $T_V = \tilde{T}_V$ in $M_R = B(0, R) \cap \{v \in C_0(\Omega); 0 < v < \bar{U}\}$. It is easy to show that $0 \notin (I - T_V)(\partial M_R)$. We conclude that

$$\forall R > R_0, d(I - T_V, B(0, R) \cap M_R, 0) = d(I - \tilde{T}_V, B(0, R), 0) = 1.$$

Remark 4.7. We can also obtain the existence of a minimal solution using the monotone iteration method of Theorem 3.3, but we lose the relative result of stability obtained by the degree theory (for further results concerning the degree theory we can see for example [11]).

4.2. Proof of Theorem 2. Here we have $f(0) = 0$, so we must find a solution different from the trivial one.

We consider then the function f_K defined by

$$f_K(s) = \begin{cases} f(s) & \text{if } 0 \leq s \leq K \\ f(K) & \text{if } s \geq K. \end{cases}$$

We expand V by zero outside Ω . In this case, f_K is a continuous bounded function. Since there exists an $0 < s_0 < K$ such that $f(s_0) > 0$, we have $F(s_0) > 0$ where $F(s) = \int_0^s f_K(t)dt$. So we consider the energy functional E defined on $W_0^{1,p}(\Omega)$ by

$$E(u) = \frac{1}{p} \int_\Omega |\nabla u|^p - \int_\Omega VF(u).$$

Without loss of generality, we can suppose that $0 \in \Omega$. Let $\varphi \in D(\Omega)$ such that: $\varphi \geq 0$, $\varphi = s_0$ in $B(0, \frac{R}{2})$ and 0 outside $B(0, R)$. We define also the scaled function $\varphi_\lambda(x) = \varphi(\lambda x)$. After all these definitions we can start the proof.

It is easy to check that E is bounded from below on $W_0^{1,p}(\Omega)$ and $E(0) = 0$.

$$\begin{aligned} E(\varphi_\lambda) &= \frac{1}{p} \int_\Omega |\nabla \varphi_\lambda|^p - \int_\Omega F(\varphi(\lambda x))V(x)dx \\ &= \frac{\lambda^{p-d}}{p} \int_\Omega |\nabla \varphi|^p - \int_{B(0, \frac{R}{\lambda})} F(\varphi(\lambda x))V(x)dx \\ &= \frac{\lambda^{p-d}}{p} \int_\Omega |\nabla \varphi|^p - \lambda^{-d} \int_{B(0,R)} F(\varphi(x))V\left(\frac{x}{\lambda}\right)dx \\ &= \lambda^{-d} \left(\frac{\lambda^p}{p} \int_\Omega |\nabla \varphi|^p - \lambda^\gamma \int_{B(0,R)} F(\varphi(x))\lambda^{-\gamma}V\left(\frac{x}{\lambda}\right)dx \right). \end{aligned}$$

Since $(\lambda^{-\gamma}V(\frac{x}{\lambda}))_\lambda$ converge weakly in measure to $\mu > 0$. We have

$$E(\varphi_\lambda) \underset{\infty}{\sim} -\lambda^{\gamma-d} \int_{B(0,R)} F(\varphi(x))d\mu(x).$$

We deduce that $\inf_{u \in W_0^{1,p}(\Omega)} E(u) < 0$. It follows by usual minimization technics that E have a critical point u_1 with negative energy, which correspond to a non trivial solution of

$$\begin{cases} -\Delta_p u &= V(x)f_K(u) \text{ in } \Omega \\ u &= 0 \text{ on } \partial\Omega. \end{cases}$$

Using the same a priori estimates as in the previous proof, we have

$$\|u\|_{L^\infty} \leq c(\Omega, d, p)f(K)^{\frac{1}{1-p}} \|V\|_E^{\frac{1}{1-p}}.$$

Since V satisfies (2.1), there exists K such that

$$\|u\|_{L^\infty} \leq c(\Omega, d, p)f(K)^{\frac{1}{1-p}} \|V\|_E^{\frac{1}{1-p}} \leq K.$$

It follows that u is a solution of (P).

5. NONEXISTENCE RESULTS

In this section we will proof Theorem 2.3 and Corollary 2.4. So we suppose that Ω is a bounded domain of \mathbb{R}^d .

Let us remind an interesting result concerning the first eigenvalue of the p -Laplace operator defined by:

$$\lambda_1(\Omega) = \inf \left\{ \int_\Omega |\nabla u|^p; u \in W_0^{1,p}(\Omega), \int_\Omega |u|^p = 1 \right\}.$$

We can define also the first eigenvalue with weight $V \geq 0$ and $V \in L^q(\Omega)$, where $q > \frac{d}{p}$ if $p \leq d$ and $q = 1$ if $p > d$, by

$$\lambda_1(\Omega, V) = \inf \left\{ \int_{\Omega} |\nabla u|^p; u \in W_0^{1,p}(\Omega), \int_{\Omega} V |u|^p = 1 \right\}.$$

We know, (see [8] or [4]), that this minimum is achieved in a function φ_1 that satisfies the Euler equation:

$$\begin{cases} -\Delta_p \varphi_1 &= \lambda_1 V |\varphi_1|^{p-2} \varphi_1 \text{ in } \Omega \\ \varphi_1 &= 0 \text{ in } \partial\Omega \end{cases}$$

and have the following result:

Theorem 5.1 ([6]). *Let $V : \Omega \rightarrow \mathbb{R}$ be a given function such that $V^+ \neq 0$. Assume that $V \in L^q(\Omega)$, where $q > \frac{d}{p}$ if $p \leq d$ and $q = 1$ if $p > d$, then $\lambda_1(\Omega, V)$ is simple, isolated, and the corresponding eigenfunction is positive and belong to $C^{1,\alpha}(\Omega)$ for some $\alpha \in]0, 1[$.*

Remark 5.2. The signification of “ $\lambda_1(\Omega, V)$ is simple” is that any other eigenfunction ψ with fixed sign is of the form $\psi = \beta\varphi_1$.

We consider for $0 \leq h \in L^q(\Omega)$, where $q > \frac{d}{p}$ if $p \leq d$ and $q = 1$ if $p > n$, the set

$$\mathcal{H}_h(\Omega) = \{V \in E; V > h\}.$$

Using this result we will show that for $\|V\|_E$ sufficiently large, the problem (P) have no solution if $\tilde{V} = \frac{V}{\|V\|_E} \in \mathcal{H}_\psi(\Omega)$. In fact suppose that (P) has a positive solution u for every V . Let $\tilde{V} = \frac{V}{\|V\|_E}$ and φ_1 the first eigenfunction associated to

$$\begin{cases} -\Delta_p \varphi_1 &= \lambda_1 h |\varphi_1|^{p-2} \varphi_1 \text{ in } \Omega \\ \varphi_1 &= 0 \text{ on } \partial\Omega. \end{cases}$$

Since $\varphi_1 > 0$ and $\frac{\partial \varphi_1}{\partial \nu} < 0$, there exist $t > 0$ such that $\Psi = t\varphi_1 < u$ in Ω . Assume that

$$\lambda = \|V\|_E > \lambda_1(\Omega, h) \sup_{\alpha > 0} \frac{\alpha^{p-1}}{f(\alpha)},$$

then for $\varepsilon > 0$ sufficiently small and $\lambda_\varepsilon = \lambda_1 + \varepsilon$ we have

$$-\Delta_p \Psi = \lambda_1 h |\Psi|^{p-2} \Psi \leq \lambda_\varepsilon h |\Psi|^{p-2} \Psi \leq \lambda_\varepsilon \tilde{V} |u|^{p-2} u \leq \lambda \tilde{V} f(u) = -\Delta_p u.$$

So the problem

$$\begin{cases} -\Delta_p v &= \lambda_\varepsilon |v|^{p-2} v \text{ on } \Omega \\ v &= 0 \text{ in } \partial\Omega \end{cases} \tag{5.1}$$

have a sub and super-solution. Using Theorem 3.3 the problem (5.1) have a positive solution and this is a contradiction because λ_1 is isolated. Then we have the existence of a constant $\lambda^* = \lambda^*(p, d, \Omega) > 0$ such that: If $\|V\|_E < \lambda^*$, the problem (P) have at

least one positive solution; If $\|V\|_E > \lambda^*$, the problem (P) have no positive solution. Moreover

$$c(p, d, \Omega) \sup_{\alpha>0} \frac{\alpha^{p-1}}{f(\alpha)} \leq \lambda^* \leq \lambda_1(\Omega, h) \sup_{\alpha>0} \frac{\alpha^{p-1}}{f(\alpha)},$$

and that shows the sharpness of our estimation.

We can also define for a subdomain $\tilde{\Omega} \subset \Omega$ the set $\mathcal{H}_h(\tilde{\Omega}) = \{V \in E; V > h \text{ in } \tilde{\Omega}\}$. Then we have

$$c(p, d, \Omega) \sup_{\alpha>0} \frac{\alpha^{p-1}}{f(\alpha)} \leq \lambda^* \leq \lambda_1(\tilde{\Omega}, h) \sup_{\alpha>0} \frac{\alpha^{p-1}}{f(\alpha)}.$$

The proof is the same, since we will consider the restriction of our problem to $\tilde{\Omega}$.

Remark 5.3. We can see also that if we assume that $\tilde{V} = \frac{V}{\|V\|_E} \in \mathcal{H}_\delta(\Omega') = \{v \in E; v > \delta \text{ on } \Omega'\}$, then we get the existence of $\lambda^* \in [0, +\infty]$ such that:

- i) if $\|V\|_E < \lambda^*$, problem (P) have at least one positive solution.
- ii) if $\|V\|_E > \lambda^*$, problem (P) have no positive solution.

Moreover, we have the following estimation:

$$c(p, d, \Omega) \sup_{\alpha>0} \frac{\alpha^{p-1}}{f(\alpha)} \leq \lambda^* \leq \frac{\lambda_1(\Omega')}{\delta} \sup_{\alpha>0} \frac{\alpha^{p-1}}{f(\alpha)}.$$

6. OTHER EXISTENCE RESULTS

Now we are going to weaken the hypothesis of monotonicity of f .

Proposition 6.1. *Assume that f is an absolutely continuous function, then $f = \bar{f} + \underline{f}$, where \bar{f} is a continuous nondecreasing function and \underline{f} is a nonincreasing function.*

Let us define the set

$$D_f^+(I) = \left\{ \begin{array}{l} g : I \longrightarrow \mathbb{R}; g \text{ is nondecreasing, } g(0) = f(0) \text{ and} \\ \text{there exists a nonincreasing function } h : I \longrightarrow \mathbb{R} \text{ such that } f = g + h \end{array} \right\}.$$

Theorem 6.2. *Assume that $f : \mathbb{R} \longrightarrow \mathbb{R}^+$ is an absolutely continuous function such that $f(0) > 0$. If $V \in E$ and*

$$\|V\|_E < c(p, d, \Omega) \sup_{g \in D_f^+(\mathbb{R}^+)} \sup_{\alpha>0} \frac{\alpha^{p-1}}{g(\alpha)},$$

then (P) have at least one positive solution.

Proof. We know that 0 is a subsolution of (P), so our propose is to find a supersolution. But since f is absolutely continuous, $f \leq g$ for every $g \in D_f^+(\mathbb{R}^+)$, and using Theorem 2.1 the problem

$$\begin{cases} -\Delta_p u = V(x)g(u) \text{ in } \Omega \\ u = 0 \text{ on } \partial\Omega \end{cases}$$

have at least one positive solution. So this solution is a supersolution of (P) and that achieve the proof using Theorem 3.3. □

Theorem 6.3. *Assume that $f : \mathbb{R} \rightarrow \mathbb{R}^+$ is a continuous function such that $f(0) > 0$. If $V \in E$ and*

$$\|V\|_E < c(p, d, \Omega) \sup_{\alpha > 0} \inf_{\gamma \in [0, \alpha]} \frac{\alpha^{p-1}}{f(\gamma)},$$

then (P) have at least one positive solution.

Proof. Let $T_V : C_0(\Omega) \rightarrow C_0(\Omega)$ the operator defined by $T_V(v) = u$, if

$$\begin{cases} -\Delta_p u = V(x)f(v) \text{ in } \Omega \\ u = 0 \text{ on } \partial\Omega. \end{cases}$$

If $v \in B(0, \alpha)$, for some $\alpha > 0$, using the previous a priori estimates, we get

$$\|T_V(v)\|_\infty \leq C(p, d, \Omega) \|Vf(v)\|_E^{\frac{1}{p-1}} \leq C(p, d, \Omega) \left(\|V\|_E \sup_{\gamma \in [0, \alpha]} f(\gamma) \right)^{\frac{1}{p-1}}.$$

So if $\|V\|_E < c(p, d, \Omega) \inf_{\gamma \in [0, \alpha]} \frac{\alpha^{p-1}}{f(\gamma)}$, then T_V applies the ball $B(0, \alpha)$ to it self. Now using the fact that if $v \in C_0(\Omega)$ then $T_V(v) \in C^{1,\nu}(\Omega)$ (Di Benedetto, Tolksdorf). We obtain the compacty of the operator T_V . So by the Schauder fixed point theorem, T_V have a fixed point u , which correspond to a solution of (P). □

Remark 6.4. The previous result is a generalization of Theorem 2.1. But remark that we loose the result of stability obtained by the degree theory.

7. AN EXTENSION TO THE WHOLE SPACE

Let us define the set

$$\mathcal{H} = \{ \psi : \mathbb{R}^+ \rightarrow \mathbb{R}; \psi \text{ is measurable,}$$

$$(N(\psi))^{\frac{1}{p-1}} = \int_0^{+\infty} \frac{1}{s^{d-1}} \left(\int_0^s t^{d-1} |\psi(t)| dt \right)^{\frac{1}{p-1}} ds < \infty \},$$

and consider the problem

$$\begin{cases} -\Delta_p u = \psi \text{ in } \mathbb{R}^d \\ \lim_{|x| \rightarrow +\infty} u(x) = 0. \end{cases} \tag{7.1a}$$

Proposition 7.1. *If f is a positive radial function such that $\psi(x) = \tilde{\psi}(|x|)$ where $\tilde{\psi} \in \mathcal{H}$, then problem (7.1a) has a positive bounded solution u_ψ given by*

$$u_\psi(x) = \int_{|x|}^{+\infty} \frac{1}{s^{d-1}} \left(\int_0^s t^{d-1} \tilde{\psi}(t) dt \right)^{\frac{1}{p-1}} ds.$$

In particular $\|u\|_\infty \leq (N(\tilde{\psi}))^{\frac{1}{p-1}}$.

Proof. Simple calculation. □

If V is a measurable function, we define

$$\mathcal{L}_V = \{ \psi \in \mathcal{H}; |V(x)| \leq \psi(|x|), \text{ a.e in } \mathbb{R}^d \},$$

and

$$h(V) = \inf_{\psi \in \mathcal{L}_V} N(\psi).$$

Theorem 7.2. *Let us consider a positive measurable function $V \in L^1(\mathbb{R}^d)$ such that $h(V) < \infty$. If*

$$h(V) < \sup_{\alpha > 0} \frac{\alpha^{p-1}}{f(\alpha)},$$

the problem

$$\begin{cases} -\Delta_p u = V(x)f(u) \text{ in } \mathbb{R}^d \\ \lim_{|x| \rightarrow +\infty} u(x) = 0 \end{cases} \tag{7.2}$$

where $f : \mathbb{R}_+ \rightarrow \mathbb{R}_+^*$ is a continuous nondecreasing function, have at least one positive solution.

Proof. Consider the problem

$$\begin{cases} -\Delta_p u = V(x) \text{ in } \mathbb{R}^d \\ \lim_{|x| \rightarrow +\infty} u(x) = 0 \end{cases} \tag{7.3}$$

Like the proof of Theorem 2.1 we need 3 steps:

STEP 1: Boundedness.

Let us consider the approximation problem

$$\begin{cases} -\Delta_p u_k = V_k(x) \text{ in } B(0, k) \\ u_k(x) = 0 \text{ if } |x| = k, \end{cases}$$

where $V_k(x) = \min(V(x), k)\chi_{B(0,k)}$. It is clear that such solution u_k exists. Furthermore, using the weak comparison theorem and Proposition 7.1, the sequence (u_k) is uniformly bounded in $L^\infty(\mathbb{R}^d)$ by $h(V)$. It follows that

$$\int_{\mathbb{R}^d} |\nabla u_k|^p \leq \|V\|_{L^1} h(V),$$

and we deduce the boundedness of (u_k) in $W^{1,p}(\mathbb{R}^d)$. So there exist a subsequence which will be denoted (u_k) and $u \in W^{1,p}(\mathbb{R}^d)$ such that

$$\begin{cases} u_k \rightarrow u \text{ a.e on } \mathbb{R}^d \\ u_k \rightarrow u \text{ in } L^q_{loc}(\mathbb{R}^d), p \leq q < p^* \\ u_k \rightharpoonup u \text{ in } W^{1,p}(\mathbb{R}^d) \end{cases}$$

$$\langle -\Delta_p u_k, u_k - u \rangle = \int_{\mathbb{R}^d} |\nabla u_k|^{p-2} \nabla u_k (\nabla u_k - \nabla u) = \int_{\mathbb{R}^d} V_k (u_k - u) \leq \int_{\mathbb{R}^d} V (u_k - u).$$

Since $u_k \rightharpoonup u$ in $L^\infty(\Omega)$ weak-*, we have the convergence of $u_k \rightarrow u$ in $W^{1,p}(\mathbb{R}^d)$. Thus we obtain the desired solution of (7.3) such that $\|u\|_{L^\infty} \leq h(V)$.

STEP 2: Super-solution.

Since $h(V) < \sup_{\alpha>0} \frac{\alpha^{p-1}}{f(\alpha)}$, we have the existence of

$$\psi \in \mathcal{H} \text{ such that } V(x) \leq \psi(|x|) \text{ and } N(\psi) < \sup_{\alpha>0} \frac{\alpha^{p-1}}{f(\alpha)}.$$

So, $\bar{u} = \int_{|x|}^{+\infty} \frac{1}{s^{d-1}} \left(\int_0^s t^{d-1} \psi(t) dt \right)^{\frac{1}{p-1}} ds$, is a super-solution of (7.2).

STEP 3: Monotone iteration.

Now we consider the sequence $(u_k)_k$ defined by $u_0 = \bar{u}$ and

$$\begin{cases} -\Delta_p u_{k+1} = V(x) f(u_k) \\ \lim_{|x| \rightarrow +\infty} u_{k+1} = 0. \end{cases}$$

By the maximum principle, we have the fact that the sequence $(u_k)_k$ non increasing and $0 < u_k \leq \bar{u}$. Using the same arguments of the first step, we obtain the convergence of u_k in $W^{1,p}(\mathbb{R}^d)$. \square

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