CRITERIA FOR THE OSCILLATION OF SECOND ORDER NONLINEAR DYNAMIC INCLUSIONS WITH DISTRIBUTED DEVIATING ARGUMENTS

SAID R. GRACE^1 AND TAHER S. $\mathrm{HASSAN}^{2,3}$

¹Department of Engineering Mathematics, Faculty of Engineering Cairo University, Giza 12221, Egypt *E-mail:* srgrace@eng.cu.edu.eg

²Department of Mathematics, Faculty of Science, University of Hail Hail, 2440, KSA ³Department of Mathematics, Faculty of Science, Mansoura University Mansoura, 35516, Egypt *E-mail:* tshassan@mans.edu.eg

ABSTRACT. In this paper we investigate some new criteria for the oscillation of second order nonlinear inclusions with distributed arguments on time scales. We establish the case of strongly superlinear and the case strongly sublinear subject to various conditions.

AMS (MOS) Subject Classification. 34C10, 34C15, 34N05, 34K11, 39A10.

1. INTRODUCTION

In this paper we consider the second order nonlinear inclusions with distributed arguments

$$\left(r\left(t\right)x^{\Delta}\left(t\right)\right)^{\Delta} \in \int_{a}^{b} q(t,\tau)F\left(t,x^{\sigma}\left(g\left(t,\tau\right)\right)\right)\Delta\tau, \quad \text{for a.e. } t \ge t_{0} \in \mathbb{T}, \quad (1.1)$$

on an arbitrary time scale $\mathbb{T} \subseteq \mathbb{R}$ with $\sup \mathbb{T} = \infty$ and 0 < a < b. Whenever, we write $t \geq t_1$, we mean $t \in [t_1, \infty) \cap \mathbb{T} = [t_1, \infty)_{\mathbb{T}}$. We assume that:

(i) $r: \mathbb{T} \to \mathbb{R}^+ = (0, \infty)$ is a single real-valued, rd-continuous function and

$$\int^{\infty} \frac{\Delta s}{r(s)} < \infty; \tag{1.2}$$

- (ii) $q: \mathbb{T} \times [a, b] \to \mathbb{R}^+$ is a rd-continuous function;
- (iii) $g: \mathbb{T} \times [a, b] \to \mathbb{T}$ is a decreasing with respect to second variable and $g(t, \tau) \to \infty$ as $t \to \infty, \tau \in [a, b]$;
- (iv) $F : [t_0, \infty)_{\mathbb{T}} \times \mathbb{R} \to 2^{\mathbb{R}}$ is a multifunction $(2^{\mathbb{R}}$ denotes the family of nonempty subsets of \mathbb{R}).

We note that the usual standard notation in inclusion theory is used here, e.g.

$$|F(t, u)| := \sup \{ |v| : v \in F(t, u) \}$$

and

$$F(t, u) > 0$$
 means $w > 0$ for each $w \in F(t, u)$

In this paper by a solution to inclusion (1.1), we mean a function $x \in C_{rd}$ with $rx^{\Delta} \in C_{rd}$ and $(rx^{\Delta})^{\Delta} \in L^{1}_{loc}[t_{0}, \infty)_{\mathbb{T}}$, where C_{rd} is the space of right-dense continuous functions. We assume throughout that inclusion (1.1) possesses such solutions. We recall that a solution of inclusion (1.1) is said to be nonoscillatory if there exists a $t_{1} \in \mathbb{T}$ such that $x(t) x^{\sigma}(t) > 0$ for all $t \in [t_{1}, \infty)_{\mathbb{T}}$, where the forward jump operator $\sigma(t) := \inf \{s \in \mathbb{T} : s > t\}$, otherwise, it is said to be oscillatory. Inclusion (1.1) is said to be oscillatory if all its solutions are oscillatory.

Recently there has been an increasing interest in the study of theory of inclusions and inparticular the oscillation of differential inclusion

$$(r(t) x'(t))' \in F(t, x(t)), \quad \text{for a.e. } t \ge t_0,$$
 (1.3)

where

$$\int^{\infty} \frac{ds}{r(s)} = \infty.$$
(1.4)

In [1, 2, 3, 4, 5, 14], Agarwal *et al* initiated such a study. In this paper, we proceed further in this direction to establish new criteria for the oscillation of inclusion (1.1) with distributed deviating arguments. For the oscillation of second order nonlinear dynamic equations, we refer to [10, 9, 16, 17, 18, 19, 20, 21, 11, 13, 12, 6, 22, 23, 24] and the references cited therein. The obtained results are new for the continuous case i.e., $\mathbb{T} = \mathbb{R}$ as well as the discrete case i.e., $\mathbb{T} = \mathbb{Z}$.

2. MAIN RESULTS

We shall employ the following two lemmas.

Lemma 2.1 ([15]). Suppose that $|x|^{\Delta}$ is of one sign on $[t_0, \infty)_{\mathbb{T}}$, $\lambda > 0$, and $\lambda \neq 1$. Then

$$\frac{|x|^{\Delta}}{(|x|^{\sigma})^{\lambda}} \le \frac{\left(|x|^{1-\lambda}\right)^{\Delta}}{1-\lambda} \le \frac{|x|^{\Delta}}{|x|^{\lambda}} \qquad on \ [t_0,\infty)_{\mathbb{T}}.$$
(2.1)

We let

$$A(t) := \int_{t}^{\infty} \frac{\Delta s}{r(s)} \quad \text{for } t \in [t_0, \infty)_{\mathbb{T}}.$$

Lemma 2.2 ([15]). Assume that condition (1.2) holds. Suppose x solves (1.1) and is of one sign on $[t_0, \infty)_{\mathbb{T}}$. Then either

$$|x|^{\Delta} \ge 0 \qquad on \ [t_0, \infty)_{\mathbb{T}}, \qquad (2.2)$$

or there exists $t_1 \ge t_0$ such that

$$|x|^{\Delta} \le 0 \qquad on \ [t_1, \infty)_{\mathbb{T}}. \tag{2.3}$$

Moreover, let

$$\bar{c} := \left\{ |x(t_0)| + r(t_0) \left| x^{\Delta}(t_0) \right| |A(t_0)| \right\} \operatorname{sgn} x(t_0),$$

and

$$\hat{c} := \begin{cases} \frac{x(t_0)}{A(t_0)}, & \text{if } (2.2) \text{ holds} \\ r(t_1) |x^{\Delta}(t_1)| & \text{sgn } x(t_0), & \text{if } (2.3) \text{ holds}. \end{cases}$$

Then

$$|x| \le |\bar{c}| \qquad on \ [t_0, \infty)_{\mathbb{T}} \ where \ \bar{c} \ x > 0, \tag{2.4}$$

and

 $|x| \ge |\hat{c}A| \qquad on \ [t_0, \infty)_{\mathbb{T}} \ where \ \hat{c} \ Ax > 0.$ (2.5)

The following result is concerned with the oscillatory behaviour of inclusion (1.1) when F is strongly superlinear, i.e., F satisfies condition (2.7) below.

Theorem 2.3. Let

$$\begin{cases} F(t,x) < 0, & \text{for } (t,x) \in [t_0,\infty)_{\mathbb{T}} \times \mathbb{R}^+ \\ F(t,x) > 0, & \text{for } (t,x) \in [t_0,\infty)_{\mathbb{T}} \times \mathbb{R}^- \end{cases}$$
(2.6)

and assume there exists a constant $\lambda > 1$ such that the following condition is satisfied: there exists $f : [t_0, \infty)_{\mathbb{T}} \times \mathbb{R} \to \mathbb{R}$ with

$$\begin{array}{ll} (a) & xf(t,x) > 0 \ for \ a. \ e. \ t \ge t_0 \ and \ x \ne 0; \\ (b) & |f(t,x)|/|x|^{\lambda} \ is \ nondecreasing \ in \ |x| \ for \ a. \ e. \ t \ge t_0; \\ (c) & \begin{cases} |F(t,x)| \ge f(t,x), & for \ (t,x) \in [t_0,\infty)_{\mathbb{T}} \times \mathbb{R}^+; \\ |F(t,x)| \ge -f(t,x), & for \ (t,x) \in [t_0,\infty)_{\mathbb{T}} \times \mathbb{R}^-. \end{cases} \end{array}$$

If

$$\bar{g}(t) := g(t, a) \le t, \qquad \text{for } t \in [t_0, \infty)_{\mathbb{T}}, \qquad (2.8)$$

and

$$\int_{t_0}^{\infty} Q(s) \left| f\left(s, \hat{c} A^{\sigma}(s)\right) \right| \Delta s = \infty,$$
(2.9)

for all nonzero constant \hat{c} and

$$Q(t) := \int_{a}^{b} q(t,\tau) \,\Delta\tau, \qquad (2.10)$$

then inclusion (1.1) is oscillatory.

Proof. Let x be a nonoscillatory solution of inclusion (1.1) on $[t_0, \infty)_{\mathbb{T}}$. Suppose x(t) > 0 and $x(g(t, \tau)) > 0$ for $t \ge t_0$ and $a \le \tau \le b$. Let

$$\begin{cases} y(t) := \left(r(t) x^{\Delta}(t) \right)^{\Delta} \text{ with } y(t) \in \int_{a}^{b} q(t,\tau) F(t, x^{\sigma}(g(t,\tau))) \Delta \tau \\ \text{and} \\ y \in L_{loc}^{1}[t_{0}, \infty)_{\mathbb{T}}. \end{cases}$$

$$(2.11)$$

From (2.6), we have

$$(r(t) x^{\Delta}(t))^{\Delta} \le 0, \quad \text{for a.e. } t \ge t_0.$$

By Lemma 2.2, either (2.2) or (2.3) holds. From (2.7), inclusion (1.1) becomes

$$\left(r\left(t\right)x^{\Delta}\left(t\right)\right)^{\Delta} + \int_{a}^{b} q(t,\tau)f\left(t,x^{\sigma}\left(g\left(t,\tau\right)\right)\right)\Delta\tau \le 0, \quad \text{for a.e. } t \ge t_{0}. \quad (2.12)$$

In the case of (2.2), we use condition (iii) and the fact that x is increasing on $[t_0, \infty)_{\mathbb{T}}$, we find for sufficiently large $t_1 \in [t_0, \infty)_{\mathbb{T}}$

$$x^{\sigma}(g(t,\tau)) \ge x(t_0), \quad \text{for } t \ge t_1 \text{ and } \tau \in [a,b].$$

Using (2.7), see that

$$\frac{f\left(t, x^{\sigma}\left(g\left(t, \tau\right)\right)\right)}{\left(x^{\sigma}\left(g\left(t, \tau\right)\right)\right)^{\lambda}} \geq \frac{f\left(t, x\left(t_{0}\right)\right)}{\left(x\left(t_{0}\right)\right)^{\lambda}},$$

which implies

$$f(t, x^{\sigma}(g(t, \tau))) \ge \frac{f(t, x(t_0))}{(x(t_0))^{\lambda}} (x^{\sigma}(g(t, \tau)))^{\lambda} \ge f(t, x(t_0)), \text{ for } t \ge t_1 \text{ and } \tau \in [a, b]$$

Then from (2.12), we have

$$\left(r\left(t\right)x^{\Delta}\left(t\right)\right)^{\Delta} + f\left(t, x\left(t_{0}\right)\right) \int_{a}^{b} q(t, \tau) \Delta \tau \leq 0,$$

or

$$(r(t) x^{\Delta}(t))^{\Delta} + Q(t) f(t, x(t_0)) \le 0, \quad \text{for } t \ge t_1.$$
 (2.13)

Integrate (2.13) from t_1 to t, we see that

$$0 \le r(t) x^{\Delta}(t) \le r(t_1) x^{\Delta}(t_1) - \int_{t_1}^t Q(s) f(s, x(t_0)) \Delta s,$$

or

$$\int_{t_1}^t Q(s) f(s, x(t_0)) \ \Delta s \le r(t_1) x^{\Delta}(t_1) < \infty,$$

which yields

$$\int_{t_1}^{\infty} Q(s) f(s, \hat{c} A^{\sigma}(s)) \Delta s < \infty,$$

a contradiction to condition (2.9).

In the case of (2.3), we use condition (iii) and the fact that x is decreasing on $[t_0, \infty)_{\mathbb{T}}$, we get

$$x^{\sigma}(g(t,\tau)) \ge x^{\sigma}(g(t,a)), \quad \text{for } t \ge t_0 \text{ and } \tau \in [a,b].$$

Using (2.7), see that

$$\frac{f\left(t, x^{\sigma}\left(g\left(t, \tau\right)\right)\right)}{\left(x^{\sigma}\left(g\left(t, \tau\right)\right)\right)^{\lambda}} \geq \frac{f\left(t, x^{\sigma}\left(g\left(t, a\right)\right)\right)}{\left(x^{\sigma}\left(g\left(t, a\right)\right)\right)^{\lambda}},$$

which implies, for $t \ge t_0$ and $\tau \in [a, b]$

$$f(t, x^{\sigma}(g(t,\tau))) \ge f(t, x^{\sigma}(g(t,a))) \left(\frac{x^{\sigma}(g(t,\tau))}{x^{\sigma}(g(t,a))}\right)^{\lambda} \ge f(t, x^{\sigma}(g(t,a))). \quad (2.14)$$

Combining (2.12) and (2.14) we get

$$\left(r\left(t\right)x^{\Delta}\left(t\right)\right)^{\Delta} + \left(\int_{a}^{b}q(t,\tau)\Delta\tau\right)f\left(t,x^{\sigma}\left(g\left(t,a\right)\right)\right) \le 0,$$
(2.15)

or

$$\left(r\left(t\right)x^{\Delta}\left(t\right)\right)^{\Delta} + Q\left(t\right)f\left(t,x^{\sigma}\left(\bar{g}\left(t\right)\right)\right) \le 0, \quad \text{for } t \ge t_{0}.$$

$$(2.16)$$

In view (2.5) and (2.7), one can easily see that

$$\frac{f\left(t, x^{\sigma}\left(\bar{g}\left(t\right)\right)\right)}{\left(x^{\sigma}\left(\bar{g}\left(t\right)\right)\right)^{\lambda}} \ge \frac{f\left(t, x^{\sigma}\left(t\right)\right)}{\left(x^{\sigma}\left(t\right)\right)^{\lambda}} \ge \frac{f\left(t, \hat{c} \ A^{\sigma}\left(t\right)\right)}{\left(\hat{c} \ A^{\sigma}\left(t\right)\right)^{\lambda}}, \quad \text{for } t \ge t_{0}.$$
(2.17)

Let $u, v, t \in \mathbb{T}$ with $u, v, t \ge t_0$. Let $s \in \mathbb{T}$ with $s \ge t_0$. Integrate (2.16) from v to s and divide the resulting inequality by r(s). Now, integrate the resulting equation from u to t, we obtain

$$x(t) \le x(u) + r(v) x^{\Delta}(v) \int_{u}^{t} \frac{\Delta s}{r(s)} - \int_{u}^{t} \frac{1}{r(s)} \int_{v}^{s} Q(\tau) f(\tau, x^{\sigma}(\bar{g}(\tau))) \Delta \tau \Delta s.$$
(2.18)

Using (2.18) with $t \ge u \ge t_1 = v$, we have

$$x(u) \geq x(t) - r(t_1) x^{\Delta}(t_1) \int_u^t \frac{\Delta s}{r(s)} + \int_u^t \frac{1}{r(s)} \int_{t_1}^s Q(\tau) f(\tau, x^{\sigma}(\bar{g}(\tau))) \Delta \tau \Delta s$$

$$\geq -r(t_1) x^{\Delta}(t_1) \int_u^t \frac{\Delta s}{r(s)} + \int_u^t \frac{1}{r(s)} \int_{t_1}^s Q(\tau) f(\tau, x^{\sigma}(\bar{g}(\tau))) \Delta \tau \Delta s$$

$$\geq -r(t_1) x^{\Delta}(t_1) \int_u^t \frac{\Delta s}{r(s)} + \int_u^t \frac{\Delta s}{r(s)} \int_{t_1}^u Q(\tau) f(\tau, x^{\sigma}(\bar{g}(\tau))) \Delta \tau. \quad (2.19)$$

Using (2.17) in (2.19), we get

$$\begin{aligned} x\left(u\right) &\geq bA\left(u\right) + A\left(u\right) \int_{t_{1}}^{u} Q\left(\tau\right) f\left(\tau, x^{\sigma}\left(\bar{g}\left(\tau\right)\right)\right) \Delta\tau \\ &\geq bA\left(u\right) + A\left(u\right) \int_{t_{1}}^{u} Q\left(\tau\right) \frac{f\left(\tau, \hat{c} \ A^{\sigma}\left(\tau\right)\right)}{\left(\hat{c} \ A^{\sigma}\left(\tau\right)\right)^{\lambda}} \left(x^{\sigma}\left(\bar{g}\left(\tau\right)\right)\right)^{\lambda} \Delta\tau \\ &\geq bA\left(u\right) + A\left(u\right) \int_{t_{1}}^{u} Q\left(\tau\right) \frac{f\left(\tau, \hat{c} \ A^{\sigma}\left(\tau\right)\right)}{\left(\hat{c} \ A^{\sigma}\left(\tau\right)\right)^{\lambda}} \left(x^{\sigma}\left(\tau\right)\right)^{\lambda} \Delta\tau, \end{aligned}$$

where $b := -r(t_1) x^{\Delta}(t_1) > 0$. Let

$$w(u) := b + \hat{c}^{-\lambda} \int_{t_1}^u Q(\tau) f(\tau, \hat{c} A^{\sigma}(\tau)) \left(\frac{x^{\sigma}(\tau)}{A^{\sigma}(\tau)}\right)^{\lambda} \Delta \tau.$$

Therefore

$$w\left(u\right) \le \frac{x\left(u\right)}{A\left(u\right)}$$

and hence

$$w(u) \ge b + \hat{c}^{-\lambda} \int_{t_1}^u Q(\tau) f(\tau, \hat{c} A^{\sigma}(\tau)) (w^{\sigma}(\tau))^{\lambda} \Delta \tau,$$

or

$$w^{\Delta}(u) \ge \hat{c}^{-\lambda}Q(u) f(\tau, \hat{c} A^{\sigma}(u)) (w^{\sigma}(u))^{\lambda}.$$

Using the first inequality of (2.1) in the above inequality, we obtain

$$\hat{c}^{-\lambda}Q\left(u\right)f\left(\tau,\hat{c}\;A^{\sigma}\left(u\right)\right) \leq \frac{w^{\Delta}\left(u\right)}{\left(w^{\sigma}\left(u\right)\right)^{\lambda}} \leq \frac{\left(w^{1-\lambda}\left(u\right)\right)^{\Delta}}{1-\lambda}.$$

Integrating this inequality from t_1 to $t \ge t_1$, we have

$$w^{1-\lambda}(t_1) \geq w^{1-\lambda}(t) + \frac{\lambda - 1}{\hat{c}^{\lambda}} \int_{t_1}^t Q(\tau) f(\tau, \hat{c} A^{\sigma}(\tau)) \Delta \tau$$

$$\geq \frac{\lambda - 1}{\hat{c}^{\lambda}} \int_{t_1}^t Q(\tau) f(\tau, \hat{c} A^{\sigma}(\tau)) \Delta \tau,$$

which contradicts condition (2.9). A parallel argument holds when x(t) is negative. This completes the proof.

Next, we present the following result which is concerned with the case when F is strongly sublinear, i.e., F satisfies condition (2.20) below.

Theorem 2.4. Let (2.6) and (2.8) hold and assume that there exists a constant λ , $0 < \lambda < 1$ such that the following condition holds: there exists $f : [t_0, \infty)_{\mathbb{T}} \times \mathbb{R} \to \mathbb{R}$ with

$$\begin{cases} (a) \quad xf(t,x) > 0 \text{ for a. e. } t \geq t_0 \text{ and } x \neq 0; \\ (b) \quad |f(t,x)| \text{ is nondecreasing in } |x| \text{ for a. e. } t \geq t_0; \\ (c) \quad |f(t,x)|/|x|^{\lambda} \text{ is nonincreasing in } |x| \text{ for a. e. } t \geq t_0; \\ (d) \quad \begin{cases} |F(t,x)| \geq f(t,x), & \text{for } (t,x) \in [t_0,\infty)_{\mathbb{T}} \times \mathbb{R}^+; \\ |F(t,x)| \geq -f(t,x), & \text{for } (t,x) \in [t_0,\infty)_{\mathbb{T}} \times \mathbb{R}^-. \end{cases} \end{cases}$$
(2.20)

If

$$\sigma\left(g\left(t,a\right)\right) \le t, \qquad \text{for } t \in [t_0,\infty)_{\mathbb{T}}, \qquad (2.21)$$

and

$$\int_{t_0}^{\infty} \frac{1}{r(s)} \int_{t_0}^{s} Q(u) \left| f(u, \bar{c}) \right| \Delta u \ \Delta s = \infty,$$
(2.22)

for all nonzero constant \bar{c} and Q is defined by (2.10), then inclusion (1.1) is oscillatory.

Proof. Let x be a nonoscillatory solution of inclusion (1.1) on $[t_0, \infty)_{\mathbb{T}}$. Suppose x(t) > 0 and $x(g(t, \tau)) > 0$ for $t \ge t_0$ and $a \le \tau \le b$. By Lemma 2.2, either (2.2) or (2.3) holds.

In the case of (2.2), as shown in the proof of Theorem 2.3, we find for sufficiently large $t_1 \in [t_0, \infty)_{\mathbb{T}}$

$$x^{\sigma}(g(t,\tau)) \ge x(t_0), \quad \text{for } t \ge t_1 \text{ and } \tau \in [a,b],$$

and thus by integrating (2.12) twice from t_1 to t and using (b) of (2.20), one can easily find

$$\begin{aligned} x(t) &\leq x(t_{1}) + r(t_{1}) x^{\Delta}(t_{1}) \int_{t_{1}}^{t} \frac{\Delta s}{r(s)} \\ &- \int_{t_{1}}^{t} \frac{1}{r(s)} \int_{t_{1}}^{s} \int_{a}^{b} q(u,\tau) f(u,x^{\sigma}(g(u,\tau))) \Delta \tau \Delta u \Delta s \\ &\leq x(t_{1}) + r(t_{1}) x^{\Delta}(t_{1}) \int_{t_{1}}^{t} \frac{\Delta s}{r(s)} - \int_{t_{1}}^{t} \frac{1}{r(s)} \int_{t_{1}}^{s} Q(u) f(u,x(t_{0})) \Delta u \Delta s, \end{aligned}$$

a contradiction to condition (2.22). In the case of (2.3), using (iii), (b) of (2.20) and (2.21) in (2.12), we have

$$(r(t) x^{\Delta}(t))^{\Delta} + Q(t) f(t, x(t)) \le 0, \quad \text{for } t \ge t_1 \ge t_0.$$
 (2.23)

Now, using (2.4) and (c) of (2.20), we find

$$\frac{f(t, x(t))}{x^{\lambda}(t)} \ge \frac{f(t, \bar{c})}{\bar{c}^{\lambda}}, \quad \text{for } t \ge t_2 \ge t_1.$$
(2.24)

Integrating (2.23) from t_2 to t and using the fact that $x^{\Delta} < 0$ on $[t_2, \infty)_{\mathbb{T}}$, we get

$$-x^{\Delta}(t) \geq -\frac{r(t_2) x^{\Delta}(t_2)}{r(t)} + \frac{1}{r(t)} \int_{t_2}^t Q(s) f(s, x(s)) \Delta s$$

$$\geq \frac{(\bar{c})^{-\lambda}}{r(t)} \int_{t_2}^t Q(s) f(s, \bar{c}) x^{\lambda}(s) \Delta s$$

$$\geq \left(\frac{(\bar{c})^{-\lambda}}{r(t)} \int_{t_2}^t Q(s) f(s, \bar{c}) \Delta s\right) x^{\lambda}(t), \quad \text{for } t \geq t_2,$$

or

$$\frac{\left(\bar{c}\right)^{-\lambda}}{r\left(t\right)}\int_{t_{2}}^{t}Q\left(s\right)f\left(s,\bar{c}\right)\Delta s \leq -\frac{x^{\Delta}\left(t\right)}{x^{\lambda}\left(t\right)}$$

and by the second inequality of (2.1), we have

$$\frac{\left(\bar{c}\right)^{-\lambda}}{r\left(t\right)}\int_{t_{2}}^{t}Q\left(s\right)f\left(s,\bar{c}\right)\Delta s \leq -\frac{x^{\Delta}\left(t\right)}{x^{\lambda}\left(t\right)} \leq -\frac{\left(x^{1-\lambda}\left(t\right)\right)^{\Delta}}{1-\lambda}.$$

Integrating this inequality from t_2 to $t \ge t_2$, we obtain

$$x^{1-\lambda}(t_2) \geq x^{1-\lambda}(t) + \frac{1-\lambda}{(\bar{c})^{\lambda}} \int_{t_2}^t \frac{1}{r(s)} \int_{t_2}^s Q(\tau) f(\tau, \bar{c}) \Delta \tau \Delta s$$
$$\geq \frac{1-\lambda}{(\bar{c})^{\lambda}} \int_{t_2}^t \frac{1}{r(s)} \int_{t_2}^s Q(\tau) f(\tau, \bar{c}) \Delta \tau \Delta s,$$

which contradicts condition (2.22). This completes the proof.

Next, we present the following result.

Theorem 2.5. Let conditions (i)-(iv) and (2.6) hold and assume that there exists $f: [t_0,\infty)_{\mathbb{T}} \times \mathbb{R} \to \mathbb{R}$ with

$$\begin{cases}
(a) \quad xf(t,x) > 0 \text{ for } a. e. \ t \ge t_0 \text{ and } x \ne 0; \\
(b) \quad |f(t,x)| \text{ is nondecreasing in } |x| \text{ for } a. e. \ t \ge t_0; \\
(c) \quad \begin{cases}
|F(t,x)| \ge f(t,x), & \text{for } (t,x) \in [t_0,\infty)_{\mathbb{T}} \times \mathbb{R}^+; \\
|F(t,x)| \ge -f(t,x), & \text{for } (t,x) \in [t_0,\infty)_{\mathbb{T}} \times \mathbb{R}^-.
\end{cases}$$
(2.25)

If

$$g(t,\tau) \le t, \quad \text{for } t \ge t_0 \text{ and } \tau \in [a,b],$$
 (2.26)

and

$$\int_{t_0}^{\infty} \frac{1}{r(s)} \int_{t_0}^{s} Q(u) \left| f\left(u, \hat{c} A^{\sigma}\left(u\right)\right) \right| \Delta u \Delta s = \infty,$$
(2.27)

for all nonzero constant \hat{c} and Q is defined by (2.10), then inclusion (1.1) is oscillatory.

Proof. Let x be a nonoscillatory solution of inclusion (1.1) on $[t_0, \infty)_{\mathbb{T}}$, Say x(t) > 0and $x(g(t,\tau)) > 0$ for $t \ge t_0$ and $a \le \tau \le b$. A parallel argument holds when x(t) is negative. By Lemma 2.2, either (2.2) or (2.3) holds.

The case (2.2) is similar to that of Theorem 2.2 and hence is omitted. For the case (2.3), using (2.5), (2.6), (2.25) and (2.26), we get

$$f(t, x^{\sigma}(g(t, \tau))) \ge f(t, x^{\sigma}(t)) \ge f(t, \hat{c} A^{\sigma}(t)), \quad \text{for } t \ge t_1 \ge t_0 \text{ and } \tau \in [a, b].$$
(2.28)

Integrating (2.12) twice from t_1 to t and using (2.28), we have

$$x(t) \le x(t_1) + r(t_1) x^{\Delta}(t_1) \int_{t_1}^t \frac{\Delta s}{r(s)} - \int_{t_1}^t \frac{1}{r(s)} \int_{t_1}^s Q(u) f(u, \hat{c} A^{\sigma}(u)) \Delta u \Delta s,$$

nich contradicts condition (2.27) and completes the proof.

which contradicts condition (2.27) and completes the proof.

From the above results we can obtain some oscillation criteria for inclusion (1.1)on different types of time scales. If $\mathbb{T} = \mathbb{R}$, then $\sigma(t) = t$ and $x^{\Delta} = x'$ and (1.1) becomes the differential inclusion

$$(r(t) x'(t))' \in \int_{a}^{b} q(t,\tau) F(t, x(g(t,\tau))) d\tau, \quad \text{for all } t \ge t_{0}.$$
 (2.29)

and for the oscillation of (2.29) we have.

Theorem 2.6. Let conditions (i)–(iv) hold, (2.6) hold and $\int_{-\infty}^{\infty} \frac{ds}{r(s)} < \infty$. Inclusion (2.29) is oscillatory of one of the following conditions holds:

(I) $\lambda > 1$, conditions (2.7) and (2.8) hold and for all nonzero constant \hat{c} ,

$$\int_{t_0}^{\infty} Q(s) \left| f(s, \hat{c}A(s)) \right| ds = \infty.$$

(II) $0 < \lambda < 1$, conditions (2.20) and (2.21) hold and for all nonzero constant \bar{c} ,

$$\int^{\infty} \frac{1}{r(s)} \int_{t_0}^{s} Q(u) \left| f(u, \bar{c}) \right| du \, ds = \infty.$$

(III) Conditions (2.25) and (2.26) hold and for all nonzero constant \hat{c} ,

$$\int^{\infty} \frac{1}{r(s)} \int_{t_0}^{s} Q(u) \left| f(u, \hat{c}A(u)) \right| du \, ds = \infty,$$

where

$$Q(u) := \int_{a}^{b} q(u,\tau) d\tau.$$

If $\mathbb{T} = \mathbb{Z}$, then $\sigma(t) = t + 1$ and $x^{\Delta}(t) = \Delta x(t) = x(t+1) - x(t)$ and (1.1) becomes the difference inclusion

$$\Delta\left(r\left(t\right)\Delta x\left(t\right)\right) \in \sum_{\tau=a}^{b-1} q\left(t,\tau\right) F\left(t,x^{\sigma}\left(g\left(t,\tau\right)\right)\right), \quad \text{for all } t \ge t_{0}, \quad (2.30)$$

and for oscillation result for (2.30) we obtain.

Theorem 2.7. Let conditions (i)–(iv) hold, (2.6) hold and $\sum_{r=1}^{\infty} \frac{1}{r(s)} < \infty$. Inclusion (2.30) is oscillatory of one of the following conditions holds:

(I) $\lambda > 1$, conditions (2.7) and (2.8) hold and for all nonzero constant \hat{c} ,

$$\sum_{n=1}^{\infty} Q(s) \left| f(s, \hat{c}A(s+1)) \right| = \infty;$$

(II) $0 < \lambda < 1$, conditions (2.20) and (2.21) hold and for all nonzero constant \bar{c} ,

$$\sum_{n=1}^{\infty} \frac{1}{r(s)} \sum_{u=t_0}^{s-1} Q(u) \left| f(u, \bar{c}) \right| = \infty;$$

(III) Conditions (2.25) and (2.26) hold and for all nonzero constant \hat{c} ,

$$\sum_{n=1}^{\infty} \frac{1}{r(s)} \sum_{u=t_0}^{s-1} Q(u) |f(u, \hat{c}A(u+1))| = \infty,$$

where

$$Q(u) := \sum_{\tau=a}^{b-1} q(u,\tau).$$

We may employ other types of time scales, e.g., $\mathbb{T} = \mathbb{R}$ with h > 0, $\mathbb{T} = q^{\mathbb{N}_0}$ with q > 1, $\mathbb{T} = \mathbb{N}_0^2$ and others, see [7]. The details are left to the readers.

ACKNOWLEDGMENTS

The authors would like to sincerely thank the reviewer for carefully reading the paper and for valuable comments.

REFERENCES

- R. P. Agarwal, S. R. Grace and D. O'Regan, On nonoscillatory solutions of differential inclusions, *Proc. Amer. Math. Soc.* 131 (2003), 129–140.
- [2] R. P. Agarwal, S. R. Grace and D. O'Regan, Oscillation criteria for sublinear and superlinear second order differential inclusions, *Mem. Diff. Eqns. Math. Physic.* 28 (2008), 1–12.
- [3] R. P. Agarwal, S. R. Grace and D. O'Regan, Oscillation theorems for second order differential inclusions, Int. J. Dynamic Sys. Diff. Eqns. 1 (2007), 85–88.
- [4] R. P. Agarwal, S. R. Grace and D. O'Regan, Some nonoscillation criteria for inclusions, J. Aust. Math. Soc. 80 (2006), 1–12.
- [5] R. P. Agarwal, S. R. Grace and D. O'Regan, Oscillation criteria for second order differential inclusions, Adv. Stud. Contem. Math. 16 (2008), 47–56.
- [6] R. P. Agarwal, M. Bohner and S. H. Saker, Oscillation of second order delay dynamic equation, Canadian Appl. Math. Quart. 13 (2005), 1–17.
- [7] M. Bohner and A. Peterson, Dynamic Equations on Time Scales: An Introduction with Applications, Birkhäuser, Boston, 2001.
- [8] M. Bohner and A. Peterson, editors, Advances in Dynamic Equations on Time Scales, Birkhäuser, Boston, 2003.
- [9] M. Bohner and T. S. Hassan, Oscillation and boundedness of solutions to first and second order forced functional dynamic equations with mixed nonlinearities, *Appl. Anal. Discrete Math.* 59 (2009), 242–252.
- [10] T. Candan, Oscillation of second order nonlinear neutral dynamic equations on time scales with distributed deviating arguments, *Comput. Math. Appl.* 62 (2011), 471–491.
- [11] L. Erbe, T. S. Hassan and A. Peterson, Oscillation of second order functional dynamic equations, Int. J. Difference Equ. 5 (2010), 1–19.
- [12] L. Erbe, T. S. Hassan, A. Peterson and S. H. Saker, Oscillation criteria for half-linear delay dynamic equations on time scales, *Nonlinear Dyn. Syst. Theory* 9 (2009), 51–68.
- [13] L. Erbe, T. S. Hassan, A. Peterson and S. H. Saker, Oscillation criteria for sublinear half-linear delay dynamic equations on time scales, *Int. J. Difference Equ.* 3 (2008), 227–245.
- [14] S. R. Grace, R. P. Agarwal and D. O'Regan, A selection of oscillation criteria for second order differential inclusions, *Appl. Math. Letters* 22 (2009), 153–158.
- [15] S. R. Grace, R. P. Agarwal, M. Bohner and D. O'Regan, Oscillation of second-order strongly superlinear and strongly sublinear dynamic equations, *Commun. Nonlinear Sci. Numer. Simul.* 14 (2009), 3463–3471.
- [16] T. S. Hassan, Oscillation criteria for half-linear dynamic equations on time scales, J. Math. Anal. Appl. 345 (2008), 176–185.
- [17] T. S. Hassan, Kamenev-type oscillation criteria for second order nonlinear dynamic equations on time scales, *Appl. Math. Comput.* **217** (2011), 5285–5297.

- [18] T. S. Hassan, Oscillation criteria for second order nonlinear dynamic equations, Adv. Difference Equ. 2012, 2012:171, 1–13.
- [19] T. S. Hassan, L. Erbe and A. Peterson, Oscillation of second order superlinear dynamic equations with damping on time scales, *Comput. Math. Appl.* 59 (2010), 550–558.
- [20] T. S. Hassan, L. Erbe and A. Peterson, Oscillation criteria for second order sublinear dynamic equations with damping term, J. Difference Equ. Appl. 17 (2011), 505–523.
- [21] T. S. Hassan and Q. Kong, Interval criteria for forced oscillation of differential equations with \$p\$-Laplacian and nonlinearities given by Riemann-Stieltjes integrals. J. Korean Math. Soc. 49 (2012), 1017–1030.
- [22] Y. Şahiner, Oscillation of second-order delay differential equations on time scales, Nonlinear Anal. 63 (2005), 1073–1080.
- [23] S. H. Saker, Oscillation criteria of second-order half-linear dynamic equations on time scales, J. Comp. Appl. Math. 177 (2005), 375–387.
- [24] C. Tuncay, Oscillation criteria for second order nonlinear neutral dynamic equations with distributed deviating arguments on time scales, Adv. Difference Equ. 2013, 2013:112, 1–8.