A COMPUTATIONAL METHOD FOR THE QUENCHING TIME FOR A PARABOLIC PROBLEM DUE TO A CONCENTRATED NONLINEAR SOURCE IN AN INFINITE STRIP

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ABSTRACT. An upper bound of the quenching time t_q for a semilinear parabolic initial-boundary value problem with a concentrated nonlinear source in an N-dimensional infinite strip is given. A computational method is devised to compute t_q under different conditions.

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1. INTRODUCTION

Let a point $(x_1, x_2, \ldots, x_{N-1}, x_N)$ in the *N*-dimensional Euclidean space \mathbb{R}^N be denoted by (x, \tilde{x}) where *x* stands for x_1 , *L* and *b* be positive numbers such that b < L, $S = (-L, L) \times \mathbb{R}^{N-1}$, $s = (-b, b) \times \mathbb{R}^{N-1}$, $\partial S = \{(x, \tilde{x}) : x \in \{-L, L\}, \text{ and } \tilde{x} \in \mathbb{R}^{N-1}\}$, and $\partial s = \{(x, \tilde{x}) : x \in \{-b, b\}, \text{ and } \tilde{x} \in \mathbb{R}^{N-1}\}$. Let $\nu(x, \tilde{x})$ denote the unit outward normal at $(x, \tilde{x}) \in \partial s$, and $\chi_s(x, \tilde{x})$ denote a function which is 1 for |x| > b, and 0 for |x| < b. Since the Dirac delta function is the derivative of the Heaviside function, it follows that $\partial \chi_s(x, \tilde{x}) / \partial \nu$ yields a Dirac delta function at each point on x = |b|, and is zero everywhere else (cf. Chan and Tragoonsirisak [1]), and hence we have a concentrated source on ∂s . Recently, Chan and Tragoonsirisak [2], [3] studied the following problem with a concentrated nonlinear source on ∂s :

(1.1)
$$\begin{cases} u_t - \Delta u = \alpha \frac{\partial \chi_s(x, \tilde{x})}{\partial \nu} f(u) \text{ in } S \times (0, T], \\ u(x, 0) = 0 \text{ on } \bar{S}, u(x, t) = 0 \text{ on } \partial S \times (0, T], \end{cases}$$

where α and T are positive real numbers, \overline{S} is the closure of S, f is a given function such that $\lim_{u\to c^-} f(u) = \infty$ for some positive constant c, and f(u) and its derivatives f'(u) and f''(u) are positive for $0 \le u < c$. Let $H = \partial/\partial t - \partial^2/\partial x^2$, D = (0, L),

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 $\overline{D} = [0, L]$, and $\Omega = D \times (0, T]$. Due to symmetry, the problem (1.1) is equivalent to the following one-dimensional problem:

(1.2)
$$\begin{cases} Hu = \alpha \delta (x - b) f(u) \text{ in } \Omega, \\ u(x, 0) = 0 \text{ on } \bar{D}, u_x(0, t) = u(L, t) = 0 \text{ for } 0 < t \le T, \end{cases}$$

where $\delta(x-b)$ is the Dirac delta function. A solution u is said to quench if there exists an extended real number $t_q \in (0, \infty]$ such that

$$\sup\left\{u(x,t):x\in\bar{D}\right\}\to c^{-} \text{ as } t\to t_q.$$

If $t_q < \infty$, then *u* is said to quench in a finite time. If $t_q = \infty$, then *u* quenches in infinite time. Green's function $g(x, t; \xi, \tau)$ corresponding to the problem (1.2) is given by

$$g(x,t;\xi,\tau) = \frac{2}{L} \sum_{n=1}^{\infty} \left(\cos\frac{(2n-1)\pi x}{2L} \right) \left(\cos\frac{(2n-1)\pi\xi}{2L} \right) \exp\left(-\frac{(2n-1)^2\pi^2(t-\tau)}{4L^2} \right)$$

(cf. Chan and Tragoonsirisak [2]). For ease of reference, let us summarize the main results of Chan and Tragoonsirisak [2] in the following theorem.

Theorem 1.1. (a) For $(x, t; \xi, \tau) \in (\overline{D} \times (\tau, T]) \times (\overline{D} \times [0, T))$, $g(x, t; \xi, \tau)$ is continuous.

- (b) For $x, \xi \in D$ and $0 \le \tau < t \le T$, $g(x, t; \xi, \tau)$ is positive.
- (c) If $r(t) \in C([0,T])$, then $\int_0^t g(x,t;b,\tau)r(\tau)d\tau$ is continuous for $x \in \overline{D}$ and $t \in [0,T]$.
- (d) There exists some t_q such that for $0 \le t < t_q$, the nonlinear integral equation

(1.3)
$$u(x,t) = \alpha \int_0^t g(x,t;b,\tau) f(u(b,\tau)) d\tau$$

has a unique continuous nonnegative solution u. This solution u is the unique solution of the problem (1.2), and is a strictly increasing function of t in D. For any $t \in (0, t_q)$, u(x, t) attains its absolute maximum at (b, t) on the region $\overline{D} \times [0, t]$. If t_q is finite, then at t_q , u quenches at x = b only.

In this paper, we give a method to compute the quenching time t_q . In Section 2, we show how to find an upper bound for t_q . In Section 3, a computational method is devised to find t_q by making use of the several criteria given by Chan and Tragoonsirisak [3] for quenching to occur.

2. UPPER BOUND

To find the upper bound of the quenching time t_q , let

(2.1)
$$w(t) = \int_0^L \phi(x) u(x,t) dx,$$

where $\phi(x)$ denotes the eigenfunction corresponding to the fundamental eigenvalue λ_1 of the eigenvalue problem:

(2.2)
$$\begin{cases} \phi'' = -\lambda_1 \phi \text{ in } D, \\ \phi'(0) = \phi(L) = 0, \end{cases}$$

such that

(2.3)
$$\int_0^L \phi(x) \, dx = 1.$$

By a direct computation, we obtain

(2.4)
$$\lambda_1 = \frac{\pi^2}{4L^2},$$

(2.5)
$$\phi(x) = \frac{\pi}{2L} \cos\left(\frac{\pi x}{2L}\right).$$

Our next result gives an upper bound for the quenching time.

Theorem 2.1. If

(2.6)
$$\alpha \ \phi(b) - \lambda_1 \sup_{0 < w < c} \left(\frac{w}{f(w)} \right) > 0,$$

then

(2.7)
$$t_q \leq \frac{1}{\alpha \ \phi(b) - \lambda_1 \sup_{0 < w < c} \left(\frac{w}{f(w)}\right)} \int_0^c \frac{dw}{f(w)}$$

Proof. Let us multiply the differential equation in (1.2) by $\phi(x)$ and integrate over x from 0 to L. We have

$$\int_{0}^{L} u_{t}(x,t) \phi(x) dx - \int_{0}^{L} u_{xx}(x,t) \phi(x) dx = \int_{0}^{L} \alpha \delta(x-b) f(u) \phi(x) dx.$$

We have

$$\int_0^L u_t(x,t) \phi(x) dx = \frac{d}{dt} \int_0^L u(x,t) \phi(x) dx = \frac{dw}{dt},$$
$$\int_0^L \alpha \delta(x-b) f(u) \phi(x) dx = \alpha \phi(b) f(u(b,t)).$$

By using integration by parts, it follows from (1.2) and (2.2) that

$$\begin{split} \int_{0}^{L} u_{xx}\left(x,t\right)\phi\left(x\right)dx &= \phi\left(L\right)u_{x}\left(L,t\right) - \phi\left(0\right)u_{x}\left(0,t\right) - \int_{0}^{L}\phi'\left(x\right)u_{x}\left(x,t\right)dx \\ &= -\left[\phi'\left(L\right)u\left(L,t\right) - \phi'\left(0\right)u\left(0,t\right)\right] + \int_{0}^{L}\phi''\left(x\right)u\left(x,t\right) dx \\ &= -\lambda_{1}\int_{0}^{L}\phi\left(x\right)u\left(x,t\right) dx \\ &= -\lambda_{1}w\left(t\right). \end{split}$$

Thus,

(2.8)
$$\frac{dw}{dt} + \lambda_1 w = \alpha \ \phi(b) f(u(b,t)).$$

From Theorem 1.1(d), (2.1), and (2.3), we obtain

(2.9)
$$w(t) \le \int_0^L \phi(x) u(b,t) \, dx = u(b,t) \, .$$

It follows from (2.8), (2.9), and f being an increasing function that

$$\frac{dw}{dt} = \alpha \ \phi(b) \ f(u(b,t)) - \lambda_1 w(t)$$

$$\geq \alpha \ \phi(b) \ f(w(t)) - \lambda_1 w(t)$$

$$= f(w(t)) \left[\alpha \ \phi(b) - \lambda_1 \frac{w(t)}{f(w(t))} \right]$$

$$\geq f(w(t)) \left[\alpha \ \phi(b) - \lambda_1 \sup_{0 < w < c} \left(\frac{w(t)}{f(w(t))} \right) \right].$$

Using (2.6) and f(w(t)) being positive, we have

(2.10)
$$\frac{1}{\alpha \ \phi(b) - \lambda_1 \sup_{0 < w < c} \left(\frac{w(t)}{f(w(t))}\right)} \cdot \frac{dw}{f(w(t))} \ge dt.$$

Integrating (2.10), we obtain

$$\frac{1}{\alpha \ \phi\left(b\right) - \lambda_{1} \sup_{0 < w < c} \left(\frac{w(t)}{f(w(t))}\right)} \int_{w(0)}^{w(t_{q})} \frac{dw}{f\left(w\left(t\right)\right)} \ge \int_{0}^{t_{q}} dt = t_{q}.$$

Since

$$w(0) = \int_0^L \phi(x) u(x,0) dx = 0$$
, and $\lim_{t \to t_q^-} w(t) \le c$,

we have (2.7).

3. QUENCHING TIME

To compute the quenching time t_q , we use Mathematica version 9. From Theorem 1.1(d), it is sufficient to consider (1.3) at x = b in order to determine the quenching time t_q . We consider

$$M(t) = u(b,t) = \frac{2\alpha}{L} \int_0^t \sum_{n=1}^\infty \left(\cos \frac{(2n-1)\pi b}{2L} \right)^2 \exp\left(-\frac{(2n-1)^2 \pi^2 (t-\tau)}{4L^2}\right) f(M(\tau)) d\tau.$$

We give below the steps to compute t_q :

Step 1. We input the function f(u) and c.

Step 2. We input the tolerances δ and ϵ to be defined later, and the upper limit Q (instead of ∞) in the summation.

Step 3. We compute λ_1 from (2.4), and $\phi(b)$ from (2.5).

Step 4. Let $t_l^{(n)}$ and $t_u^{(n)}$ denote the (n+1)th estimates of the lower and upper bounds of t_q respectively, and $t_q^{(n)} = \left(t_l^{(n)} + t_u^{(n)}\right)/2$ be the (n+1)th approximation of t_q . Initially, we let its lower bound $t_l^{(0)}$ be zero, and we compute its upper bound $t_u^{(0)}$ by using the right-hand side of the inequality (2.7). We remark that (2.7) is satisfied if $t_u^{(0)}$ can be computed.

Step 5. Let $h = t_q^{(n)}/m$, where *m* denotes the number of subdivisions. For $k = 1, 2, 3, \ldots$, we use the finite sum,

$$M^{(k)}(rh)$$

$$=\frac{2\alpha}{L}\int_{0}^{rh}\sum_{n=1}^{Q}\left(\cos\frac{(2n-1)\pi b}{2L}\right)^{2}\exp\left(-\frac{(2n-1)^{2}\pi^{2}(rh-\tau)}{4L^{2}}\right)f\left(M^{(k-1)}(\tau)\right)d\tau,$$

where r = 1, 2, 3, ..., m in the iterative process with $M^{(0)}(\tau) = 0$, and $M^{(k)}(0) = 0$. To compute $M^{(k+1)}(rh)$, we use the interpolation to approximate $M^{(k)}(\tau)$.

Step 6. At the *k*th iteration, if for some r, $M^{(k)}(rh) \geq c$, then $t_l^{(n+1)} = t_l^{(n)}$, and $t_u^{(n+1)} = t_q^{(n)}$. We go to Steps 4 and 5. If $\max_{r=0,1,2,\dots,m} |M^{(k)}(rh) - M^{(k-1)}(rh)| < \delta$ which is a given tolerance, then the sequence $\{M^{(k)}(t)\}$ converges; in this case, let $t_l^{(n+1)} = t_q^{(n)}, t_u^{(n+1)} = t_u^{(n)}$, and go to Steps 4 and 5. We use the interpolation to approximate $M^{(k)}(\tau)$ if $\max_{r=0,1,2,\dots,m} |M^{(k)}(rh) - M^{(k-1)}(rh)| \geq \delta$, and continue the iterative process for the (k+1)th iteration to obtain an upper bound and a lower bound before going to Steps 4 and 5.

Step 7. If $\left|t_{u}^{(n)}-t_{l}^{(n)}\right| < \epsilon$ for a given tolerance ϵ , then $t_{q}^{(n)} = \left(t_{l}^{(n)}+t_{u}^{(n)}\right)/2$ is accepted as the final estimate of t_{q} .

For illustrations of the above computational scheme, let f(u) = 1/(1-u). Then, c = 1. By a direct computation, we have $\sup_{0 \le w \le c} (w/f(w)) = 1/4$. From (2.4) and (2.5),

$$\lambda_1 = \frac{\pi^2}{4L^2}$$
, and $\phi(b) = \frac{\pi}{2L} \cos\left(\frac{\pi b}{2L}\right)$.

Since $t_l^{(0)} = 0$, it follows from the right-hand side of the inequality (2.7) that

$$t_u^{(0)} = \frac{1}{\alpha \ \phi (b) - \frac{1}{4}\lambda_1} \int_0^1 (1 - w) \, dw = \frac{2}{4 \ \alpha \ \phi (b) - \lambda_1}$$

Using Steps 1 to 7 with $\epsilon = 10^{-4}$, $\delta = 10^{-6}$, Q = 10, and m = 40, and the quenching criteria given by Chan and Tragoonsirisak [3], we obtain the following tables for t_q (to four significant figures).

First, we fix L and b, and would like to study the effect of α on the quenching time. Let L = 1, and b = 1/2. From Theorems 3.1 and 2.5 of Chan and Tragoonsirisak

[3], u quenches in a finite time for

$$\alpha > \frac{1}{L-b} \sup_{0 < w < c} \left(\frac{w}{f(w)} \right),$$

that is $\alpha > 1/2$. We obtain the following table:

α	$t_u^{(0)}$	t_q
.8000	1.840	.7245
.9000	1.306	.5532
1.000	1.012	.4427

We note that the quenching time t_q is a decreasing function of α . Physically, this means that the larger the source, the smaller the quenching time.

Next, we fix α and L, and study the effect of b on the quenching time. From Corollaries 3.2 and 3.3 of Chan and Tragoonsirisak [3], if

$$L > \frac{1}{\alpha} \sup_{0 < w < c} \left(\frac{w}{f(w)} \right)$$

and $b \in (0, b^*)$, where

$$b^* = L - \frac{1}{\alpha} \sup_{0 < w < c} \left(\frac{w}{f(w)} \right),$$

then u quenches in a finite time. Let $\alpha = 1$, and L = 1. Then for u to quench in a finite time, the above conditions give L > 1/4, and $b^* = 3/4$. We obtain the following table:

b	$t_u^{(0)}$	t_q
.5000	1.012	.4427
.6000	1.632	.6013
.7000	5.193	1.335

We see that when b is closer to L, the quenching time t_q is larger. Physically, this means that the closer the nonlinear concentrated source to the boundary x = L where u = 0, the larger the quenching time.

Lastly, we fix α and b, and study the effect of L on the quenching time. From Theorem 3.1(ii) of Chan and Tragoonsirisak [3], if

$$L > b + \frac{1}{\alpha} \sup_{0 < w < c} \left(\frac{w}{f(w)} \right),$$

then u quenches in a finite time. Let $\alpha = 1$, and b = 1/2. Then for u to quench in a finite time, the above condition requires L > 3/4. We obtain the following table:

L	$t_u^{(0)}$	t_q
1.000	1.012	.4427
1.100	.8781	.4093
1.200	.8195	.3929

We observe that when L is further away from b, the quenching time t_q is smaller. Physically, this means that the further away the nonlinear concentrated source to the boundary x = L where u = 0, the smaller the quenching time.

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