

## NONLINEAR FIRST-ORDER SEMIPOSITONE PROBLEMS OF IMPULSIVE DYNAMIC EQUATIONS ON TIME SCALES

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**ABSTRACT.** By using the well-known Guo-Krasnoselskii fixed point theorem, in this paper, some results of one positive solution to a class of nonlinear first-order semipositone problems of impulsive dynamic equations on time scales are obtained. One example is given to illustrate the main results in this paper.

**AMS (MOS) Subject Classification.** 39A10, 34B15.

### 1. INTRODUCTION

Let  $\mathbf{T}$  be a time scale, i.e.,  $\mathbf{T}$  is a nonempty closed subset of  $R$ . Let  $0, T$  be points in  $\mathbf{T}$ , an interval  $(0, T)_{\mathbf{T}}$  denoting time scales interval, that is,  $(0, T)_{\mathbf{T}} := (0, T) \cap \mathbf{T}$ . Other types of intervals are defined similarly.

The theory of impulsive differential equations is emerging as an important area of investigation, since it is a lot richer than the corresponding theory of differential equations without impulse effects. Moreover, such equations may exhibit several real world phenomena in physics, biology, engineering, etc. (see [3, 4, 20]). At the same time, the boundary value problems for impulsive differential equations and impulsive difference equations have received much attention [2, 10, 17, 18, 21–23, 25–28, 30, 32]. On the other hand, recently, the theory of dynamic equations on time scales has become a new important branch (see, for example, [1, 6, 7, 16, 19]). Naturally, some authors have focused their attention on the boundary value problems of impulsive dynamic equations on time scales [5, 8, 9, 12–15, 24, 33]. However, to the best of our knowledge, few papers concerning PBVPs of impulsive dynamic equations on time scales with semi-position condition.

In this paper, we are concerned with the existence of positive solutions for the following PBVPs of impulsive dynamic equations on time scales with semi-position

condition

$$(1.1) \quad \begin{cases} x^\Delta(t) + f(t, x(\sigma(t))) = 0, & t \in J := [0, T]_{\mathbf{T}}, \quad t \neq t_k, \quad k = 1, 2, \dots, m, \\ x(t_k^+) - x(t_k^-) = I_k(x(t_k^-)), & k = 1, 2, \dots, m, \\ x(0) = x(\sigma(T)), \end{cases}$$

where  $\mathbf{T}$  is an arbitrary time scale,  $T > 0$  is fixed,  $0, T \in \mathbf{T}$ ,  $f \in C(J \times [0, \infty), (-\infty, \infty))$ ,  $I_k \in C([0, \infty), [0, \infty))$ ,  $t_k \in (0, T)_{\mathbf{T}}$ ,  $0 < t_1 < \dots < t_m < T$ , and for each  $k = 1, 2, \dots, m$ ,  $x(t_k^+) = \lim_{h \rightarrow 0^+} x(t_k + h)$  and  $x(t_k^-) = \lim_{h \rightarrow 0^-} x(t_k + h)$  represent the right and left limits of  $x(t)$  at  $t = t_k$ . We always assume that following hypothesis holds (semi-position condition):

(H) There exists a positive number  $M > 0$  such that

$$Mx - f(t, x) \geq 0 \text{ for } x \in [0, \infty), \quad t \in [0, T]_{\mathbf{T}}.$$

By using the well-known Guo-Krasnoselskii fixed point theorem [11], some existence criteria of positive solution to problem (1.1) are established. We note that for the case  $\mathbf{T} = R$  and  $I_k(x) \equiv 0, k = 1, 2, \dots, m$ , problem (1.1) reduces to the problem studied by [29] and for the case  $I_k(x) \equiv 0, k = 1, 2, \dots, m$ , problem (1.1) reduces to the problem (in the one-dimension case) studied by [31].

In the remainder of this section, we state the Guo-Krasnoselskii fixed point theorem [11].

**Theorem 1.1** (Guo-Krasnoselskii). Let  $X$  be a Banach space and  $K \subset X$  be a cone in  $X$ . Assume  $\Omega_1, \Omega_2$  are bounded open subsets of  $X$  with  $0 \in \Omega_1 \subset \overline{\Omega}_1 \subset \Omega_2$  and  $\Phi : K \cap (\overline{\Omega}_2 \setminus \Omega_1) \rightarrow K$  is a completely continuous operator such that, either:

- (i)  $\|\Phi x\| \leq \|x\|, x \in K \cap \partial\Omega_1$ , and  $\|\Phi x\| \geq \|x\|, x \in K \cap \partial\Omega_2$ ; or
- (ii)  $\|\Phi x\| \geq \|x\|, x \in K \cap \partial\Omega_1$ , and  $\|\Phi x\| \leq \|x\|, x \in K \cap \partial\Omega_2$ .

Then  $\Phi$  has at least one fixed point in  $K \cap (\overline{\Omega}_2 \setminus \Omega_1)$ .

## 2. SOME RESULTS ON TIME SCALES

In this section, we state some fundamental definitions and results concerned time scales, so that the paper is self-contained. For more details, one can refer to [1, 6, 7, 16, 19].

**Definition 2.1.** Assume that  $x : \mathbf{T} \rightarrow R$  and fix  $t \in \mathbf{T}$  (if  $t = \sup \mathbf{T}$ , we assume  $t$  is not left-scattered). Then  $x$  is called differential at  $t \in \mathbf{T}$  if there exists a  $\theta \in R$  such that for any given  $\varepsilon > 0$ , there is an open neighborhood  $U$  of  $t$  such that

$$|x(\sigma(t)) - x(s) - \theta |\sigma(t) - s|| \leq \varepsilon |\sigma(t) - s|, \quad s \in U.$$

In this case,  $\theta$  is called the delta derivative of  $x$  at  $t \in \mathbf{T}$  and denote it by  $\theta = x^\Delta(t)$ .

If  $F^\Delta(t) = f(t)$ , then we define the delta integral by

$$\int_a^t f(s)\Delta s = F(t) - F(a).$$

**Lemma 2.1.** If  $f \in C_{rd}$  and  $t \in \mathbf{T}^k$ , then

$$\int_t^{\sigma(t)} f(s)\Delta s = \mu(t)f(t),$$

where  $\mu(t) = \sigma(t) - t$  is the graininess function.

**Lemma 2.2.** If  $f^\Delta \geq 0$ , then  $f$  is increasing.

**Lemma 2.3.** Assume that  $f, g : \mathbf{T} \rightarrow R$  are delta derivative at  $t$ , then

$$(fg)^\Delta(t) = f^\Delta(t)g(t) + f(\sigma(t))g^\Delta(t) = f(t)g^\Delta(t) + f^\Delta(t)g(\sigma(t)).$$

**Definition 2.2.** A function  $p : \mathbf{T} \rightarrow R$  is regressive provided

$$1 + \mu(t)p(t) \neq 0 \text{ for all } t \in \mathbf{T}^k.$$

The set of all regressive and rd-continuous functions will be denoted by  $\mathcal{R}$ .

**Definition 2.3.** We define the set  $\mathcal{R}^+$  of all positively regressive elements of  $\mathcal{R}$  by

$$\mathcal{R}^+ = \{p \in \mathcal{R} : 1 + \mu(t)p(t) > 0 \text{ for all } t \in \mathbf{T}\}.$$

**Definition 2.4.** If  $p \in \mathcal{R}$ , then the delta exponential function is given by

$$e_p(t, s) = \begin{cases} \exp\left(\int_s^t p(\tau)\Delta\tau\right) & \text{if } \mu(\tau) = 0, \\ \exp\left(\int_s^t \frac{1}{\mu(\tau)} \text{Log}(1 + p(\tau)\mu(\tau))\Delta\tau\right) & \text{if } \mu(\tau) \neq 0, \end{cases}$$

where  $\text{Log}$  is the principal logarithm.

**Lemma 2.4.** If  $p \in \mathcal{R}$ , then

- (1)  $e_p(t, t) \equiv 1$ ;
- (2)  $e_p(t, s) = \frac{1}{e_p(s, t)}$ ;
- (3)  $e_p(t, u)e_p(u, s) = e_p(t, s)$ ;
- (4)  $e_p^\Delta(t, t_0) = p(t)e_p(t, t_0)$ , for  $t \in \mathbf{T}^k$  and  $t_0 \in \mathbf{T}$ .

**Lemma 2.5.** If  $p \in \mathcal{R}^+$  and  $t_0 \in \mathbf{T}$ , then

$$e_p(t, t_0) > 0 \text{ for all } t \in \mathbf{T}.$$

## 3. PRELIMINARIES

Throughout the rest of this paper, we always assume that the points of impulse  $t_k$  are right-dense for each  $k = 1, 2, \dots, m$ .

We define

$$PC = \{x \in [0, \sigma(T)]_{\mathbf{T}} \rightarrow R : x_k \in C(J_k, R), k = 1, 2, \dots, m \text{ and there exist } x(t_k^+) \text{ and } x(t_k^-) \text{ with } x(t_k^-) = x(t_k), k = 1, 2, \dots, m\},$$

where  $x_k$  is the restriction of  $x$  to  $J_k = (t_k, t_{k+1}]_{\mathbf{T}} \subset (0, \sigma(T)]_{\mathbf{T}}$ ,  $k = 1, 2, \dots, m$  and  $J_0 = [0, t_1]_{\mathbf{T}}$ ,  $J_{m+1} = \{\sigma(T)\}$ .

Let

$$X = \{x : x \in PC, x(0) = x(\sigma(T))\}$$

with the norm  $\|x\| = \sup_{t \in [0, \sigma(T)]_{\mathbf{T}}} |x(t)|$ . Then  $X$  is a Banach space.

**Lemma 3.1.** Suppose  $M > 0$  and  $h : [0, T]_{\mathbf{T}} \rightarrow R$  is  $rd$ -continuous, then  $x$  is a solution of

$$x(t) = \int_0^{\sigma(T)} G(t, s)h(s)\Delta s + \sum_{k=1}^m G(t, t_k)I_k(x(t_k)), t \in [0, \sigma(T)]_{\mathbf{T}},$$

where  $G(t, s) = \begin{cases} \frac{e_M(s, t)e_M(\sigma(T), 0)}{e_M(\sigma(T), 0) - 1}, & 0 \leq s \leq t \leq \sigma(T), \\ \frac{e_M(s, t)}{e_M(\sigma(T), 0) - 1}, & 0 \leq t < s \leq \sigma(T), \end{cases}$  if and only if  $x$  is a solution of the boundary value problem

$$\begin{cases} x^\Delta(t) + Mx(\sigma(t)) = h(t), t \in J := [0, T]_{\mathbf{T}}, t \neq t_k, k = 1, 2, \dots, m, \\ x(t_k^+) - x(t_k^-) = I_k(x(t_k^-)), k = 1, 2, \dots, m, \\ x(0) = x(\sigma(T)). \end{cases}$$

**Proof.** Since the proof similar to that of [Lemma 3.1, 33], we omit it here.

**Lemma 3.2.** Let  $G(t, s)$  be defined as Lemma 3.1, then

$$\frac{1}{e_M(\sigma(T), 0) - 1} \leq G(t, s) \leq \frac{e_M(\sigma(T), 0)}{e_M(\sigma(T), 0) - 1} \text{ for all } t, s \in [0, \sigma(T)]_{\mathbf{T}}.$$

**Proof.** It is obviously, so we omit it here.

**Remark 3.1.** Let  $G(t, s)$  be defined as Lemma 3.1, then  $\int_0^{\sigma(T)} G(t, s)\Delta s = \frac{1}{M}$ .

For  $u \in X$ , we consider the following problem:

$$(3.1) \begin{cases} x^\Delta(t) + Mx(\sigma(t)) = Mu(\sigma(t)) - f(t, u(\sigma(t))), t \in [0, T]_{\mathbf{T}}, t \neq t_k, k = 1, 2, \dots, m, \\ x(t_k^+) - x(t_k^-) = I_k(x(t_k^-)), k = 1, 2, \dots, m, \\ x(0) = x(\sigma(T)). \end{cases}$$

It follows from Lemma 3.1 that problem (3.1) has a unique solution:

$$x(t) = \int_0^{\sigma(T)} G(t, s)h_u(s)\Delta s + \sum_{k=1}^m G(t, t_k)I_k(x(t_k)), t \in [0, \sigma(T)]_{\mathbf{T}},$$

where  $h_u(s) = Mu(\sigma(s)) - f(s, u(\sigma(s)))$ .

We define an operator  $\Phi : X \rightarrow X$  by

$$\Phi(u)(t) = \int_0^{\sigma(T)} G(t, s)h_u(s)\Delta s + \sum_{k=1}^m G(t, t_k)I_k(u(t_k)), \quad t \in [0, \sigma(T)]_{\mathbf{T}}.$$

**Lemma 3.3.**  $\Phi : X \rightarrow X$  is completely continuous.

**Proof.** The proof is divided into three steps.

**Step 1:** To show that  $\Phi : X \rightarrow X$  is continuous.

Let  $\{u_n\}_{n=1}^{\infty}$  be a sequence such that  $u_n \rightarrow u$  ( $n \rightarrow \infty$ ) in  $X$ . Since  $f(t, u)$  and  $I_k(u)$  are continuous in  $x$ , we have

$$\begin{aligned} |h_{u_n}(t) - h_u(t)| &= |M(u_n - u) - (f(t, u_n) - f(t, u))| \rightarrow 0 \quad (n \rightarrow \infty), \\ |I_k(u_n(t_k)) - I_k(u(t_k))| &\rightarrow 0 \quad (n \rightarrow \infty). \end{aligned}$$

So

$$\begin{aligned} &|\Phi(u_n)(t) - \Phi(u)(t)| \\ &= \left| \int_0^{\sigma(T)} G(t, s) [h_{u_n}(s) - h_u(s)] \Delta s + \sum_{k=1}^m G(t, t_k) [I_k(u_n(t_k)) - I_k(u(t_k))] \right| \\ &\leq \frac{e_M(\sigma(T), 0)}{e_M(\sigma(T), 0) - 1} \left[ \int_0^{\sigma(T)} |h_{u_n}(t) - h_u(t)| \Delta s + \sum_{k=1}^m |I_k(u_n(t_k)) - I_k(u(t_k))| \right] \\ &\rightarrow 0 \quad (n \rightarrow \infty), \end{aligned}$$

which lead to  $\|\Phi u_n - \Phi u\| \rightarrow 0$  ( $n \rightarrow \infty$ ). That is,  $\Phi : X \rightarrow X$  is continuous.

**Step 2:** To show that  $\Phi$  maps bounded sets into bounded sets in  $X$ .

Let  $B \subset X$  be a bounded set, that is,  $\exists r > 0$  such that  $\forall u \in B$  we have  $\|u\| \leq r$ . Then, for any  $u \in B$ , in virtue of the continuity of  $f(t, u)$  and  $I_k(u)$ , there exist  $c > 0, c_k > 0$  such that

$$|f(t, u)| \leq c, \quad |I_k(u)| \leq c_k, \quad k = 1, 2, \dots, m.$$

We get

$$\begin{aligned} |\Phi(u)(t)| &= \left| \int_0^{\sigma(T)} G(t, s)h_u(s)\Delta s + \sum_{k=1}^m G(t, t_k)I_k(u(t_k)) \right| \\ &\leq \int_0^{\sigma(T)} G(t, s) |h_u(s)| \Delta s + \sum_{k=1}^m G(t, t_k) |I_k(u(t_k))| \\ &\leq \frac{e_M(\sigma(T), 0)}{e_M(\sigma(T), 0) - 1} \left[ \sigma(T) (Mr + c) + \sum_{k=1}^m c_k \right]. \end{aligned}$$

Then we can conclude that  $\Phi u$  is bounded uniformly, and so  $\Phi(B)$  is a bounded set.

**Step 3:** To show that  $\Phi$  maps bounded sets into equicontinuous sets of  $X$ .

Let  $t_1, t_2 \in [0, \sigma(T)]_{\mathbf{T}}$ ,  $u \in B$ , then

$$\begin{aligned} & |\Phi(u)(t_1) - \Phi(u)(t_2)| \\ & \leq \int_0^{\sigma(T)} |G(t_1, s) - G(t_2, s)| |h_u(s)| \Delta s + \sum_{k=1}^m |G(t_1, t_k) - G(t_2, t_k)| |I_k(u(t_k))|. \end{aligned}$$

The right-hand side tends to uniformly zero as  $|t_1 - t_2| \rightarrow 0$ .

Consequently, Step 1-3 together with the Arzela-Ascoli Theorem show that  $\Phi : X \rightarrow X$  is completely continuous.

Let

$$K = \{u \in X : u(t) \geq \delta \|u\|, t \in [0, \sigma(T)]_{\mathbf{T}}\},$$

where  $\delta = \frac{1}{e_M(\sigma(T), 0)} \in (0, 1)$ . It is not difficult to verify that  $K$  is a cone in  $X$ .

From Lemma 3.2, it is easy to obtain following result:

**Lemma 3.4.**  $\Phi$  maps  $K$  into  $K$ .

#### 4. MAIN RESULTS

Let

$$\begin{aligned} f^0 &= \limsup_{u \rightarrow 0^+} \max_{t \in [0, T]_{\mathbf{T}}} \frac{f(t, u)}{u}, \quad f^\infty = \limsup_{u \rightarrow \infty} \max_{t \in [0, T]_{\mathbf{T}}} \frac{f(t, u)}{u}, \\ f_0 &= \liminf_{u \rightarrow 0^+} \min_{t \in [0, T]_{\mathbf{T}}} \frac{f(t, u)}{u}, \quad f_\infty = \liminf_{u \rightarrow \infty} \min_{t \in [0, T]_{\mathbf{T}}} \frac{f(t, u)}{u}, \end{aligned}$$

and

$$I_0 = \lim_{u \rightarrow 0^+} \frac{I_k(u)}{u}, \quad I_\infty = \lim_{u \rightarrow \infty} \frac{I_k(u)}{u}.$$

Now we state our main results.

**Theorem 4.1.** Suppose that

$$f_0 > 0, \quad f^\infty < \frac{\delta - 1}{\delta} M; \quad I_0 = 0, \quad \text{for any } k.$$

Then the problem (1.1) has at least one positive solutions.

**Proof.** From the hypotheses we know there exist  $\varepsilon > 0$  and  $L_1 > r_1 > 0$  such that

$$\begin{aligned} f(t, u) &\geq \varepsilon u, \quad I_k(u) \leq \frac{(e_M(\sigma(T), 0) - 1)\varepsilon}{Mme_M(\sigma(T), 0)} u, \quad \text{for any } k, \quad 0 < u \leq r_1; \\ f(t, u) &\leq \left( \frac{\delta - 1}{\delta} M - \varepsilon \right) u, \quad u \geq L_1. \end{aligned}$$

Let  $\Omega_1 = \{u \in X : \|u\| < r_1\}$ . It follows that for  $u \in K$  with  $\|u\| = r_1$ , we have

$$\begin{aligned} \Phi(u)(t) &= \int_0^{\sigma(T)} G(t, s) h_u(s) \Delta s + \sum_{k=1}^m G(t, t_k) I_k(u(t_k)) \\ &\leq \int_0^{\sigma(T)} G(t, s) (M - \varepsilon) u(\sigma(s)) \Delta s + \sum_{k=1}^m G(t, t_k) \frac{(e_M(\sigma(T), 0) - 1)\varepsilon}{Mme_M(\sigma(T), 0)} u(t_k) \end{aligned}$$

$$\begin{aligned} &\leq \frac{(M - \varepsilon)}{M} \|u\| + \frac{e_M(\sigma(T), 0)}{e_M(\sigma(T), 0) - 1} \sum_{k=1}^m \frac{(e_M(\sigma(T), 0) - 1)\varepsilon}{Mme_M(\sigma(T), 0)} \|u\| \\ &= \|u\|, \end{aligned}$$

which yields

$$(4.1) \quad \|\Phi u\| \leq \|u\|, \quad u \in K \cap \partial\Omega_1.$$

Set  $\Omega_2 = \{u \in X : \|u\| < \frac{L_1}{\delta}\}$ . Since  $u \in K \cap \partial\Omega_2$ , we have  $u(t) \geq \delta \|u\| = L_1$ . Hence for  $u \in K \cap \partial\Omega_2$ , we have

$$\begin{aligned} \Phi(u)(t) &= \int_0^{\sigma(T)} G(t, s)h_u(s)\Delta s + \sum_{k=1}^m G(t, t_k)I_k(u(t_k)) \\ &\geq \int_0^{\sigma(T)} G(t, s)h_u(s)\Delta s \\ &\geq \int_0^{\sigma(T)} G(t, s) \left( M + \frac{1 - \delta}{\delta}M + \varepsilon \right) u(\sigma(s))\Delta s \\ &\geq \frac{1}{M} \left( \frac{1}{\delta}M + \varepsilon \right) \delta \|u\| \\ &\geq \|u\|, \end{aligned}$$

which implies

$$(4.2) \quad \|\Phi u\| \geq \|u\|, \quad x \in K \cap \partial\Omega_2.$$

Therefore, from (4.1), (4.2) and Theorem 1.1, it follows that  $\Phi$  has a fixed point in  $K \cap (\overline{\Omega_2} \setminus \Omega_1)$ , that is, the problem (1.1) has at least one positive solution.

**Theorem 4.2.** Suppose that

$$f_\infty > 0, \quad f^0 < \frac{\delta - 1}{\delta}M; \quad I_\infty = 0, \quad \text{for any } k.$$

Then the problem (1.1) has at least one positive solutions.

**Proof.** From the hypotheses we know there exist  $\varepsilon' > 0$  and  $L_2 > r_2 > 0$  such that

$$\begin{aligned} f(t, u) &\geq \varepsilon' u, \quad I_k(u) \leq \frac{(e_M(\sigma(T), 0) - 1)\varepsilon'}{Mme_M(\sigma(T), 0)} u, \quad \text{for any } k, \quad u \geq L_2; \\ f(t, u) &\leq \left( \frac{\delta - 1}{\delta}M - \varepsilon' \right) u, \quad 0 < u \leq r_2. \end{aligned}$$

Let  $\Omega_1 = \{u \in X : \|u\| < \frac{L_2}{\delta}\}$ . Since  $u \in K \cap \partial\Omega_1$ , we have  $u(t) \geq \delta \|u\| = L_2$ . Hence for  $u \in K \cap \partial\Omega_1$ , we have

$$\begin{aligned} \Phi(u)(t) &= \int_0^{\sigma(T)} G(t, s)h_u(s)\Delta s + \sum_{k=1}^m G(t, t_k)I_k(u(t_k)) \\ &\leq \int_0^{\sigma(T)} G(t, s) (M - \varepsilon') u(\sigma(s))\Delta s + \sum_{k=1}^m G(t, t_k) \frac{(e_M(\sigma(T), 0) - 1)\varepsilon'}{Mme_M(\sigma(T), 0)} u(t_k) \end{aligned}$$

$$\begin{aligned}
&\leq \frac{(M - \varepsilon')}{M} \|u\| + \frac{e_M(\sigma(T), 0)}{e_M(\sigma(T), 0) - 1} \sum_{k=1}^m \frac{(e_M(\sigma(T), 0) - 1)\varepsilon'}{M m e_M(\sigma(T), 0)} \|u\| \\
&= \|u\|,
\end{aligned}$$

which yields

$$(4.3) \quad \|\Phi u\| \leq \|u\|, \quad u \in K \cap \partial\Omega_1.$$

Set  $\Omega_2 = \{x \in X : \|u\| < r_2\}$ . It follows that for  $u \in K$  with  $\|u\| = r_2$ , we have

$$\begin{aligned}
\Phi(u)(t) &= \int_0^{\sigma(T)} G(t, s) h_u(s) \Delta s + \sum_{k=1}^m G(t, t_k) I_k(u(t_k)) \\
&\geq \int_0^{\sigma(T)} G(t, s) h_u(s) \Delta s \\
&\geq \int_0^{\sigma(T)} G(t, s) \left( M + \frac{1 - \delta}{\delta} M + \varepsilon' \right) u(\sigma(s)) \Delta s \\
&\geq \frac{1}{M} \left( \frac{1}{\delta} M + \varepsilon' \right) \delta \|u\| \\
&\geq \|u\|,
\end{aligned}$$

which implies

$$(4.4) \quad \|\Phi u\| \geq \|u\|, \quad u \in K \cap \partial\Omega_2.$$

Hence, from (4.3), (4.4) and Theorem 1.1, it follows that  $\Phi$  has a fixed point in  $K \cap (\overline{\Omega}_1 \setminus \Omega_2)$ , that is, the problem (1.1) has at least one positive solution.

## 5. EXAMPLE

**Example 5.1.** Let  $\mathbf{T} = [0, 1] \cup [2, 3]$ . We consider the following problem on  $\mathbf{T}$

$$(5.1) \quad \begin{cases} x^\Delta(t) + f(t, x(\sigma(t))) = 0, & t \in [0, 3]_{\mathbf{T}}, \quad t \neq \frac{1}{2}, \\ x\left(\frac{1}{2}^+\right) - x\left(\frac{1}{2}^-\right) = I(x(\frac{1}{2})), \\ x(0) = x(3), \end{cases}$$

where  $T = 3$ ,  $f(t, x) = x - (t + 1)x^2$ , and  $I(x) = x^2$ .

Let  $M = 1$ , then  $\delta = \frac{1}{2e^2}$ , it is easy to see that

$$Mx - f(t, x) = (t + 1)x^2 \geq 0 \text{ for } x \in [0, \infty), \quad t \in [0, 3]_{\mathbf{T}},$$

and

$$f_0 \geq 1, \quad f^\infty = -\infty, \quad \text{and } I_0 = 0.$$

Therefore, by Theorem 4.1, it follows that the problem (5.1) has at least one positive solution.



**Acknowledgment:** This work is supported by the Excellent Young Teacher Training Program of Lanzhou University of Technology (Q200907).

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