

**A NOTE ON THE EXPONENTIATED  
EXPONENTIAL–POISSON SOFTWARE RELIABILITY MODEL**

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**ABSTRACT:** In this paper we consider an application to the debugging theory of a class of cumulative exponentiated exponential–Poisson distribution functions introduced by Ramos, Dey, Louzada and Lachos.

By this family of cumulative distribution functions we study the Hausdorff approximation of the shifted Heaviside step function.

Numerical examples, illustrating our results using the programming environment Mathematica are presented.

As application in the field of debugging and test theory are given examples with real data including compatibility modifications, operating system upgrade and signaling message processing from year 2000 using the new software reliability model.

**AMS Subject Classification:** 68N30, 41A46

**Key Words:** exponentiated exponential–Poisson cumulative distribution function (EEPcdf), Heaviside function, Hausdorff approximation, upper and lower bounds

**Received:** July 4, 2018;      **Accepted:** September 26, 2018;

**Published:** October 3, 2018      **doi:** 10.12732/npsc.v26i3.3

Dynamic Publishers, Inc., Acad. Publishers, Ltd.

<https://acadsol.eu/npsc>

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## 1. INTRODUCTION

Some extensions of the well-known Poisson, Poisson–exponential, Chen, Exponentiated Chen, modified Weibull and Burr distributions can be found in [1]–[8].

A software reliability model that uses the "Gompertz-type correction" is the Exponentiated Exponential-Poisson cumulative distribution function (EEPcdf) introduced by Ramos, Dey, Louzada and Lachos in [9]:

$$M(t; \lambda; \theta) = \left( \frac{e^{\lambda \frac{1-e^{-\theta t}}{1-e^{-\theta}} - 1}}{e^\lambda - 1} \right)^\alpha \quad (1)$$

where  $\theta > 0$ ;  $\lambda > 0$ ;  $\alpha > 0$ .

For other software reliability models see [10]–[29].

Without loss of generality we consider the following class of the family (1) with application to the debugging theory:

$$M_1(t) = \left( \frac{e^{\lambda \frac{1-e^{-\theta t}}{1-e^{-\theta}} - 1}}{e^\lambda - 1} \right)^\alpha \quad (2)$$

with

$$t_0 = -\frac{1}{\theta} \ln \left( 1 - \frac{1 - e^{-\theta}}{\lambda} \ln \left( 1 + \frac{e^\lambda - 1}{2^{\frac{1}{\alpha}}} \right) \right); \quad M_1(t_0) = \frac{1}{2}. \quad (3)$$

In this note we study the Hausdorff approximation of the *shifted Heaviside step function*

$$h_{t_0}(t) = \begin{cases} 0, & \text{if } t < t_0, \\ [0, 1], & \text{if } t = t_0, \\ 1, & \text{if } t > t_0, \end{cases}$$

by the family (2)–(3).

Hausdorff approximation of some modeling functions can be found in [30]–[35].

Furthermore, we propose a software module (intellectual property) within the programming environment CAS Mathematica for the analysis. Numerical examples, illustrating our results are presented.

As application in the field of debugging and test theory we give also real examples with data provided in [36] using the new software reliability model. The dataset includes [37] Year 2000 compatibility modifications, operating system upgrade and signaling message processing.

## 2. HAUSDORFF APPROXIMATION OF THE SHIFTED HEAVISIDE STEP FUNCTION

**Definition 1.** [38] The Hausdorff distance (the H-distance)  $\rho(f, g)$  between two interval functions  $f, g$  on  $\Omega \subseteq \mathbb{R}$ , is the distance between their completed graphs  $F(f)$

and  $F(g)$  considered as closed subsets of  $\Omega \times \mathbb{R}$ . More precisely,

$$\rho(f, g) = \max\left\{ \sup_{A \in F(f)} \inf_{B \in F(g)} \|A - B\|, \sup_{B \in F(g)} \inf_{A \in F(f)} \|A - B\| \right\},$$

wherein  $\|\cdot\|$  is any norm in  $\mathbb{R}^2$ , e. g. the maximum norm  $\|(t, x)\| = \max\{|t|, |x|\}$ ; hence the distance between the points  $A = (t_A, x_A)$ ,  $B = (t_B, x_B)$  in  $\mathbb{R}^2$  is  $\|A - B\| = \max\{|t_A - t_B|, |x_A - x_B|\}$ .

The one-sided Hausdorff distance  $d$  between the function  $h_{t_0}(t)$  and the function (2)–(3) satisfies the relation

$$M_1(t_0 + d) = 1 - d. \tag{4}$$

The following theorem gives upper and lower bounds for  $d$ .

**Theorem 2.** *Let*

$$p = -\frac{1}{2},$$

$$q = 1 + \frac{\alpha\theta\lambda \left(1 + \frac{e^\lambda - 1}{2^{\frac{1}{\alpha}}}\right)}{2^{\frac{\alpha-1}{\alpha}}(1 - e^{-\theta})(e^\lambda - 1)} \left(1 - \frac{1 - e^{-\theta}}{\lambda} \ln \left(1 + \frac{e^\lambda - 1}{2^{\frac{1}{\alpha}}}\right)\right),$$

$$r = 2.1q$$

For the one-sided Hausdorff distance  $d$  between  $h_{t_0}(t)$  and the function (2)–(3) for

$$q > \frac{e^{1.05}}{2.1}$$

the following inequalities hold:

$$d_l = \frac{1}{r} < d < \frac{\ln r}{r} = d_r. \tag{5}$$

**Proof.** Let us examine the function:

$$F(d) = M_1(t_0 + d) - 1 + d. \tag{6}$$

From  $F'(d) > 0$  we conclude that the function  $F$  is increasing.

Consider the function

$$G(d) = p + qd. \tag{7}$$

From the Taylor expansion we obtain  $G(d) - F(d) = O(d^2)$ .

Hence  $G(d)$  approximates  $F(d)$  with  $d \rightarrow 0$  as  $O(d^2)$  (see Fig. 1).

In addition  $G'(d) > 0$ .

Further, for  $q > \frac{e^{1.05}}{2.1}$  we have  $G(d_l) < 0$  and  $G(d_r) > 0$ .

This completes the proof of the theorem. □

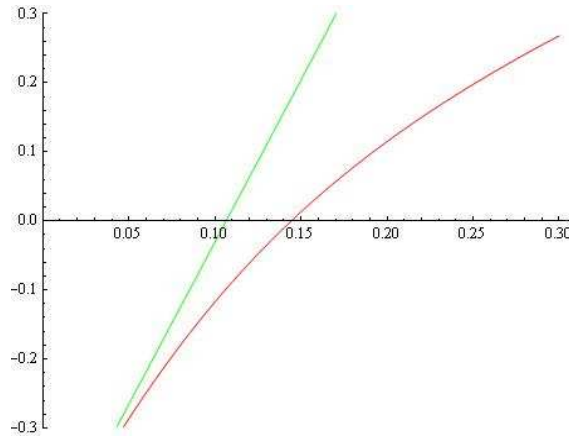


Figure 1: The functions  $F(d)$  and  $G(d)$  for  $\theta = 10$ ;  $\lambda = 0.5$ ;  $\alpha = 3.5$ .

The model (2)–(3) for  $\theta = 10$ ,  $\lambda = 0.5$ ,  $\alpha = 3.5$ ,  $t_0 = 0.191957$  is visualized on Fig. 2. From the nonlinear equation (4) and inequalities (5) we have:  $d = 0.14436$ ,  $d_l = 0.101423$ ,  $d_r = 0.232102$ .

The model (2)–(3) for  $\theta = 10$ ,  $\lambda = 0.05$ ,  $\alpha = 0.5$ ,  $t_0 = 0.0293988$  is visualized on Fig. 3. From the nonlinear equation (4) and inequalities (5) we have:  $d = 0.120798$ ,  $d_l = 0.0569498$ ,  $d_r = 0.163195$ .

From the above examples, it can be seen that the proven estimates in Theorem 2 for the value of the Hausdorff approximation are reliable when assessing the important characteristic - "saturation". This characteristic has its equal participation together with the other two characteristics - "confidence intervals" and "confidence bounds" in the area of the software reliability theory.

We propose a software module (intellectual property) within the programming environment *CAS Mathematica* for the analysis of the considered family  $M_1(t)$ .

The module offers the following possibilities:

- generation of the function under user defined values of the parameters  $\lambda$ ,  $\alpha$  and  $\theta$ ;
- calculation of the H-distance  $d$  between the function  $h_{t_0}(t)$  and the function  $M_1(t)$ ;
- software tools for animation and visualization.

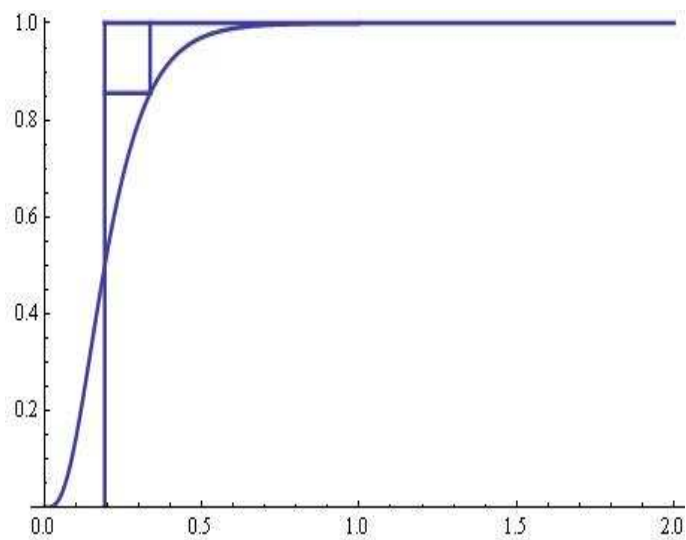


Figure 2: The model (2)–(3) for  $\theta = 8$ ,  $\lambda = 0.5$ ,  $t_0 = 0.103098$ ; H-distance  $d = 0.155378$ ,  $d_l = 0.103958$ ,  $d_r = 0.235337$ .

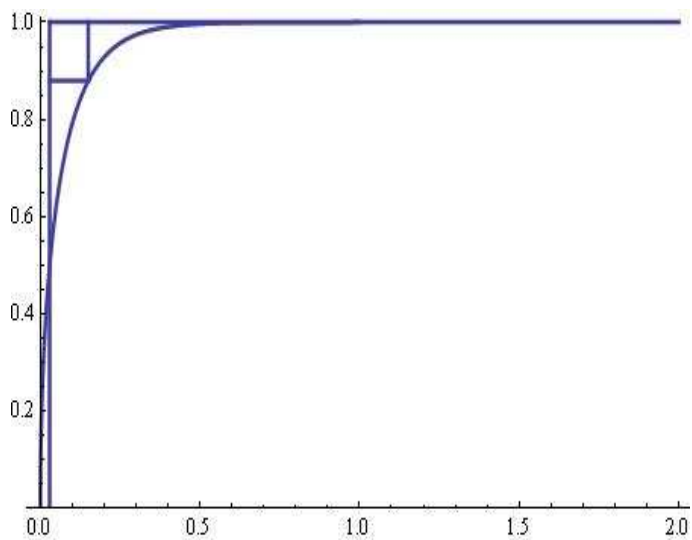


Figure 3: The model (2)–(3) for  $\beta = 15$ ,  $\lambda = 0.01$ ,  $t_0 = 0.0463767$ ; H-distance  $d = 0.104496$ ,  $d_l = 0.0561458$ ,  $d_r = 0.161689$ .

### 3. APPLICATION IN THE FIELD OF DEBUGGING AND TEST THEORY

We give real examples with data provided in [36].

The operating time of the software is 167,900 days. 115 failures are detected for these days which contain 71 unique failures.

Table 1 shows the failures data which are united for each of the 13 months.

The dataset includes [37] Year 2000 compatibility modifications, operating system upgrade and signaling message processing.

Month In- dex	System Days (Days)	System Days (Cu- mulative)	Failures	Cumulative Failures
1	961	961	7	7
2	4170	5131	3	10
3	8789	13,920	14	24
4	11,858	25,778	8	32
5	13,110	38,888	11	43
6	14,198	53,086	8	51
7	14,265	67,351	7	58
8	15,175	82,526	19	77
9	15,376	97,902	17	94
10	15,704	113,606	6	100
11	18,182	131,788	11	111
12	17,760	149,548	4	115
13	18,352	167,900	0	115

Table 1. Field failure data [36].

The fitted model

$$M_1(t) = \omega \left( \frac{e^{\lambda \frac{1-e^{-\theta t}}{1-e^{-\theta}} - 1}}{e^\lambda - 1} \right)^\alpha$$

based on the data of Table 1 for the estimated parameters:

$$\omega = 402; \theta = 0.23822; \lambda = 0.830748; \alpha = 19.0736$$

is plotted on Fig. 4.

We hope that the results will be useful for a lot of specialists in this scientific area.

**Remark 3.** In [29] the authors developed the following new software reliability model

$$M(t) = \omega \left( \frac{e^{\lambda \frac{1-e^{-\theta t}}{1-e^{-\theta}} - 1}}{e^\lambda - 1} \right)$$

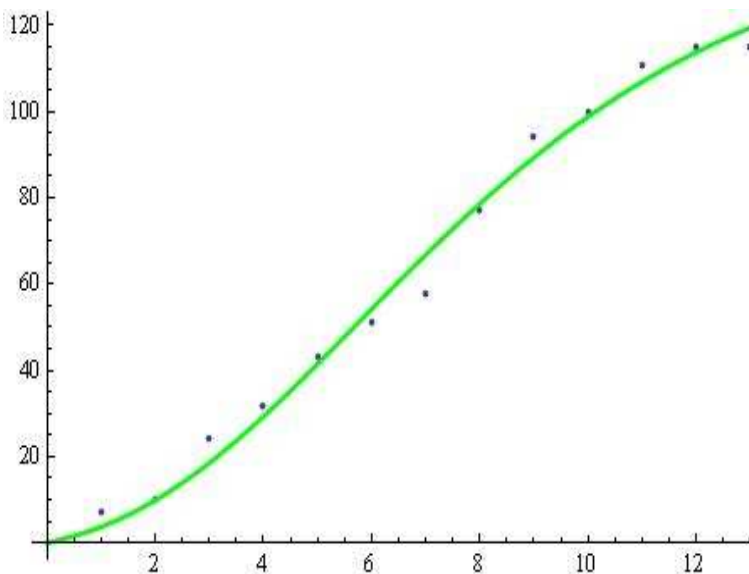


Figure 4: The fitted model  $M_1(t)$ .

The model for

$$\omega = 7; \theta = 0.142302; \lambda = 0.317432$$

is plotted on Fig. 5.

We will explicitly note that in some cases the software reliability model  $M_1(t)$  provides better results than other much more sophisticated models.

### ACKNOWLEDGMENTS

This work has been supported by project FP17-FMI-008 of Department for Scientific Research, Paisii Hilendarski University of Plovdiv.

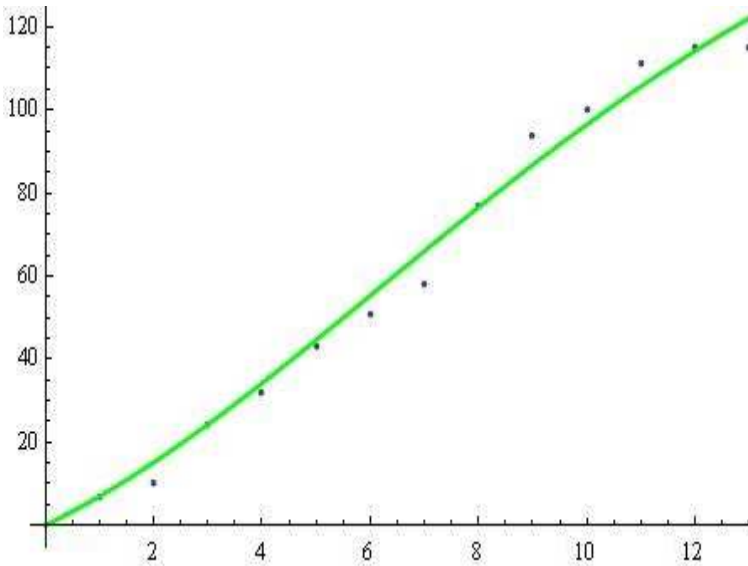


Figure 5: The fitted model  $M(t)$ .

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