

## BACKWARD STOCHASTIC DIFFERENTIAL INCLUSIONS

MICHAŁ KISIELEWICZ

Faculty of Mathematics, Computer Sciences and Econometrics, University of  
Zielona Góra, Podgórna 50, 65-246 Zielona Góra, Poland

**ABSTRACT.** Existence of solutions to backward stochastic differential inclusions is considered. The paper contains the basic notions dealing with backward stochastic differential inclusions.

**AMS (MOS) Subject Classification.** 47H04, 49J53, 60H05.

### 1. INTRODUCTION

Given measurable set-valued mappings  $F : [0, T] \times \mathbb{R}^m \rightarrow Cl(\mathbb{R}^m)$  and  $H : \mathbb{R}^m \rightarrow Cl(\mathbb{R}^m)$  by a backward stochastic differential inclusion  $BSDI(F, H)$  we mean relations

$$(1.1) \quad \begin{cases} x_s \in E \left[ x_t + \int_s^t F(\tau, x_\tau) d\tau | \mathcal{F}_s \right] \\ x_T \in H(x_T) \end{cases}$$

that have to be satisfied a.s. for every  $0 \leq s \leq t \leq T$  by a càdlàg process  $x = (x_t)_{0 \leq t \leq T}$  defined on a complete filtered probability space  $\mathcal{P}_{\mathbb{F}} = (\Omega, \mathcal{F}, P, \mathbb{F})$  with a filtration  $\mathbb{F} = (\mathcal{F}_t)_{0 \leq t \leq T}$  satisfying the usual hypothesis (see [14]).  $E[x_t + \int_s^t F(\tau, x_\tau) d\tau | \mathcal{F}_s]$  denotes the set-valued conditional expectation (see [4], [5]) of the set-valued mapping  $\Omega \ni \omega \rightarrow x_t(\omega) + \int_s^t F(\tau, x_\tau(\omega)) d\tau \subset \mathbb{R}^m$  with respect to the sub- $\sigma$ -algebra  $\mathcal{F}_s \subset \mathcal{F}$ . If  $\mathcal{P}_{\mathbb{F}}$  is given then  $x$ , satisfying conditions presented above, is said to be a strong solution to  $BSDI(F, H)$ . In a general case we can look for systems  $(\mathcal{P}_{\mathbb{F}}, x)$  satisfying conditions (1). Such systems are said to be weak solutions to  $BSDI(F, H)$ . It is clear that if  $x$  is a strong solution to  $BSDI(F, H)$  on  $\mathcal{P}_{\mathbb{F}}$ , then a pair  $(\mathcal{P}_{\mathbb{F}}, x)$  is its weak solution. Backward stochastic differential inclusions can be treated as some generalizations of backward stochastic differential equations of the form

$$(1.2) \quad x_t = E \left[ h(x) + \int_t^T f(\tau, x_\tau, z_\tau) d\tau | \mathcal{F}_t \right] \quad a.s.$$

where the triplet  $(h, f, z)$  is called the data set of such equation (see [2], [3], [7], [13]). Usually, if we consider strong solutions to (1.2) apart from  $(h, f, z)$ , a probability space  $\mathcal{P} = (\Omega, \mathcal{F}, P)$  is also given and a filtration  $\mathbb{F}$  is defined by a process  $z$  by taking  $\mathbb{F}^z = (\mathcal{F}_t^z)_{0 \leq t \leq T}$ , where  $(\mathcal{F}_t^z)_{0 \leq t \leq T}$  is the smallest filtration satisfying the usual

conditions and such that  $z$  is  $\mathbb{F}^z$ -adapted. Process  $z$  is called the driving process. In practical applications the driving process  $z$  is taken as a  $d$ -dimensional Brownian motion or it is a strong solution to a forward stochastic differential equation. In the case of weak solutions to (1.2) apart from  $h$  and  $f$  a probability measure  $\mu$  on the space  $D(\mathbb{R}^d)$  of  $d$ -dimensional càdlàg functions on  $[0, T]$  is given and its weak solution with an initial distribution  $\mu$  is defined as a system  $(\mathcal{P}_{\mathbb{F}}, x, z)$  satisfying (1.2) and such that  $Pz^{-1} = \mu$  and every  $\mathbb{F}^z$ -martingale is also  $\mathbb{F}$ -martingale. Let us observe that in particular for a given weak solution  $(\mathcal{P}_{\mathbb{F}}, x)$  to  $BSDI(F, H)$  with  $H(x) = \{h(x)\}$  and  $F(t, x) = \{f(t, x, z) : z \in \mathcal{Z}\}$  for  $(t, x) \in [0, T] \times \mathbb{R}^m$ , where  $f$  and  $h$  are given measurable functions and  $\mathcal{Z}$  is a nonempty compact subset of the space  $D(\mathbb{R}^d)$ , there exists (see [8], Th. II.3.12) a measurable  $\mathbb{F}$ -adapted stochastic process  $(z_t)_{0 \leq t \leq T}$  with values in  $\mathcal{Z}$  such that

$$(1.3) \quad x_t = E \left[ h(x) + \int_t^T f(\tau, x_\tau, z_\tau) d\tau | \mathcal{F}_t \right] \quad \text{a.s.}$$

For given probability measures  $\mu_0$  and  $\mu_T$  on  $\mathbb{R}^m$ , we can look for a weak solution  $(\mathcal{P}_{\mathbb{F}}, x)$  to  $BSDI(F, H)$  such that  $Px_0^{-1} = \mu_0$  and  $Px_T^{-1} = \mu_T$ . If  $F$  and  $H$  are such as above then there exists a measurable and  $\mathbb{F}$ -adapted stochastic process  $(z_t)_{0 \leq t \leq T}$  such that (1.3) is satisfied and such that  $E[h(x) + \int_0^T f(\tau, x_\tau, z_\tau) d\tau] = \int_{\mathbb{R}^m} u d\mu_0$ . If  $f(t, x, z) = f(t, x) + g(z)$ , with  $g \in C(D(\mathbb{R}^d), \mathbb{R}^m)$ , then

$$\int_0^T \int_{D(\mathbb{R}^d)} g(v) d\lambda_\tau d\tau = \int_{\mathbb{R}^m} u d\mu_0 - \int_{\mathbb{R}^m} h(u) d\mu_T - E \int_0^T f(\tau, x_\tau) d\tau$$

where  $\lambda_t = Pz_t^{-1}$  for  $t \in [0, T]$ . In some special case weak solutions to  $BSDI(F, H)$  describe a class of recursive utilities under uncertainty (see [7]). To verify that suppose  $(\mathcal{P}_{\mathbb{F}}, x)$  is a weak solution to  $BSDI(F, H)$  with  $H(x) = \{h(x)\}$  and  $F(t, x) = \{f(t, x, c, z) : (c, z) \in \mathcal{C} \times \mathcal{Z}\}$ , where  $h$  and  $f$  are measurable functions and  $\mathcal{C}, \mathcal{Z}$  are nonempty compact subsets of  $C([0, T], \mathbb{R}^+)$  and  $D(\mathbb{R}^m)$ , respectively. Similarly as above we can select a pair of measurable  $\mathbb{F}$ -adapted stochastic processes  $(c_t)_{0 \leq t \leq T}$  and  $(z_t)_{0 \leq t \leq T}$  with values at  $\mathcal{C}$  and  $\mathcal{Z}$ , respectively and such that

$$(1.4) \quad x_t = E \left[ h(x) + \int_t^T f(\tau, x_\tau, c_\tau, z_\tau) d\tau | \mathcal{F}_t \right] \quad \text{a.s.}$$

for  $0 \leq t \leq T$ . In such a case (1.4) describes some class of recursive utilities under uncertainty, where  $(c_t(s, \cdot))_{0 \leq s \leq T}$  denotes for fixed  $t \in [0, T]$  the future consumption. Let us observe that in some special case a strong solution  $x$  to  $BSDI(F, H)$  on a filtered probability space  $\mathcal{P}_{\mathbb{F}}$  with the “constant” filtration  $\mathbb{F} = (\mathcal{F})$  is a solution to a backward random inclusion  $-x'_t \in \text{co}F(t, x_t)$  with a terminal condition  $x_T \in H(x_T)$  a.s. for a.e.  $t \in [0, T]$ . As usual  $\text{co}F(t, x_t)$  denotes the convex hull of the set  $F(t, x_t)$ . Throughout the paper we assume that  $\mathcal{P}_{\mathbb{F}} = (\Omega, \mathcal{F}, P, \mathbb{F})$  is a complete filtered probability space with a filtration  $\mathbb{F} = (\mathcal{F}_t)_{0 \leq t \leq T}$  satisfying the usual hypotheses. Given

$\mathcal{P}_{\mathbb{F}}$  we denote by  $\mathbb{D}(\mathbb{F}, \mathbb{R}^m)$  the space of all  $m$ -dimensional  $\mathbb{F}$ -adapted càdlàg processes on  $\mathcal{P}_{\mathbb{F}}$  and by  $\mathcal{S}^2(\mathbb{F}, \mathbb{R}^m)$  the set of all  $m$ -dimensional  $\mathbb{F}$ -semimartingales  $x$  such that  $\|x\|_{\mathcal{S}^2} = E[\sup_{s \in [0, T]} |x_s|^2] < \infty$ . We have  $\mathcal{S}^2(\mathbb{F}, \mathbb{R}^m) \subset \mathbb{D}(\mathbb{F}, \mathbb{R}^m)$ . It can be proved (see [14], Th. IV.2.1, Th. V.2.2) that  $(\mathcal{S}^2(\mathbb{F}, \mathbb{R}^m), \|\cdot\|_{\mathcal{S}^2})$  is a Banach space. The present paper is mainly devoted to properties of solutions set of weak continuous solutions to  $BSDI(F, H)$ . It is organized as follows. Section 2 contains some properties of the set-valued conditional expectations of set-valued integrals. In Section 3 some measurable selection theorems are given. Existence theorems to  $BSDI(F, H)$  are given in Section 4 and Section 5. Finally, in Section 6 a weak compactness of the set  $\mathcal{X}(F, H)$  of all continuous weak solutions to  $BSDI(F, H)$  is proved.

## 2. CONDITIONAL EXPECTATION OF SET-VALUED INTEGRALS

Let  $(\Omega, \mathcal{F}, P)$  be a probability space and let  $\mathcal{G}$  be a sub- $\sigma$ -algebra of  $\mathcal{F}$ . Given an  $\mathcal{F}$ -measurable set-valued mapping  $\Phi : \Omega \rightarrow Cl(\mathbb{R}^m)$  with a nonempty set  $S(\Phi)$  of all its  $\mathcal{F}$ -measurable and integrable selectors there exists (see [4]) an unique (in the a.s. sense)  $\mathcal{G}$ -measurable set-valued mapping  $E[\Phi|\mathcal{G}]$  satisfying

$$(2.1) \quad S(E[\Phi|\mathcal{G}]) = cl_L\{E[\varphi|\mathcal{G}] : \varphi \in S(\Phi)\}$$

where  $cl_L$  denotes the closure operation in  $L(\Omega, \mathcal{G}, \mathbb{R}^m)$ . We call  $E[\Phi|\mathcal{G}]$  the multivalued conditional expectation of  $\Phi$  relative to  $\mathcal{G}$ . This conditional expectation has properties similar to those of the usual ones. For example, we have  $\int_A E[\Phi|\mathcal{G}]dP = \int_A \Phi dP$  for every  $A \in \mathcal{G}$ , where integrals are understood in the Aumann's sense (see [5], Prop. 6.8). It can be proved (see [5], Prop. 6.2) that for given measurable and integrably bounded set-valued mappings  $\Phi, \Psi : [0, T] \times \Omega \rightarrow Cl(\mathbb{R}^m)$  one has  $Eh(E[\Phi|\mathcal{G}], E[\Psi|\mathcal{G}]) \leq Eh(\Phi, \Psi)$ , where  $h$  is the Hausdorff metric on  $Cl(\mathbb{R}^m)$ . Let  $G : [0, T] \times \Omega \rightarrow Cl(\mathbb{R}^m)$  be measurable and integrably bounded, i.e. there is  $m \in L([0, T] \times \Omega, \mathbb{R}_+)$  such that  $\|G(t, \omega)\| \leq m(t, \omega)$ , a.e., where  $\mathbb{R}_+ = [0, \infty)$  and  $\|G(t, \omega)\| = \sup\{|g| : g \in G(t, \omega)\}$ . As usual we denote by  $S(G)$  a set of all integrable selectors for  $G$ . We have  $S(G) = \{g \in L([0, T] \times \Omega, \mathbb{R}^m) : g(t, \omega) \in G(t, \omega) \text{ a.e.}\}$ . It is easy to verify (see [8]) that  $S(G)$  is nonempty and decomposable, i.e. that for every  $f, g \in S(G)$  and  $E \in \beta_T \otimes \mathcal{F}$  one has  $\mathbb{1}_E f + \mathbb{1}_{E^c} g \in S(G)$ , where  $\beta_T$  denotes the Borel  $\sigma$ -algebra of  $[0, T]$  and  $E^c$  is the complement of  $E$ . In particular, if  $G(t, \omega)$  are convex subsets of  $\mathbb{R}^m$  for  $(t, \omega) \in [0, T] \times \Omega$ , the set  $S(G)$  is a convex weakly compact subset of  $L([0, T] \times \Omega, \mathbb{R}^m)$ . Then it is also a closed subset of this space. For the given above  $G$  we can define an Aumann integral  $\Phi(\omega) = \int_0^T G(t, \omega)dt$  depending on a parameter  $\omega \in \Omega$ . By Aumann's theorem (see [8], Th. II.3.20)  $\int_0^T G(t, \omega)dt$  is a nonempty, convex compact subset of  $\mathbb{R}^m$  for every  $\omega \in \Omega$ . Furthermore,  $\int_0^T G(t, \omega)dt = \int_0^T co G(t, \omega)dt$  for  $\omega \in \Omega$ . Hence and ([8], Th. II.3.21) we obtain the following result.

**Proposition 2.1.** *Let  $G : [0, T] \times \Omega \rightarrow Cl(\mathbb{R}^m)$  be measurable and integrably bounded. Then a set-valued mapping  $\Phi : \Omega \rightarrow \text{Conv}(\mathbb{R}^m)$  defined by  $\Phi(\omega) = \int_0^T G(t, \omega) dt$  for  $\omega \in \Omega$  is measurable.*

*Proof.* By virtue of ([8], Th. II.3.8) it is enough only to verify that the function  $\Omega \ni \omega \rightarrow s(p, \Phi(\omega)) \in \mathbb{R}$  is measurable for every  $p \in \mathbb{R}^n$ , where  $s(\cdot, A)$  denotes a support function of  $A \in Cl(\mathbb{R}^m)$ . By the measurability of  $G$  and its integrably boundedness a function  $[0, T] \times \Omega \ni (t, \omega) \rightarrow s(p, G(t, \omega)) \in \mathbb{R}$  is measurable for every  $p \in \mathbb{R}^m$  (see [8], Remark II.3.5). By virtue of ([8], Th. II.3.21) for every  $p \in \mathbb{R}^m$  one has  $s(p, \Phi(\omega)) = \int_0^T s(p, G(t, \omega)) dt$  for  $\omega \in \Omega$ . Hence the measurability of the function  $\Omega \ni \omega \rightarrow s(p, \Phi(\omega)) \in \mathbb{R}$  follows for every  $p \in \mathbb{R}^m$ . Therefore  $\Phi$  is  $\mathcal{F}$ -measurable.  $\square$

**Proposition 2.2.** *Let  $G : [0, T] \times \Omega \rightarrow Cl(\mathbb{R}^m)$  be measurable and integrably bounded and let  $\Phi(\omega) = \int_0^T G(t, \omega) dt$  for  $\omega \in \Omega$ . Then  $S(\Phi)$  is a nonempty convex weakly compact subset of  $L(\Omega, \mathcal{F}, \mathbb{R}^m)$ . Furthermore,  $\varphi \in S(\Phi)$  if and only if there is  $g \in S(\text{co } G)$  such that  $\varphi(\omega) = \int_0^T g(t, \omega) dt$  for a.e.  $\omega \in \Omega$ .*

*Proof.* By Proposition 2.1,  $\Phi$  is  $\mathcal{F}$ -measurable. It is also integrably bounded, because  $\|\Phi(\omega)\| \leq \int_0^T m(t, \omega) dt$  for a.e.  $\omega \in \Omega$ . Therefore (see [8], Th. III.2.3)  $S(\Phi)$  is a nonempty convex weakly compact subset of  $L(\Omega, \mathcal{F}, \mathbb{R}^m)$ . For every  $g \in S(\text{co } G)$  a function  $\varphi(\omega) = \int_0^T g(t, \omega) dt$  is a measurable selector for  $\Phi$ , because of ([8], Th. II.3.20) we have  $\Phi(\omega) = \int_0^T \text{co } G(t, \omega) dt$  for  $\omega \in \Omega$ . It is also integrably bounded, because  $|\varphi(\omega)| \leq \int_0^T m(t, \omega) dt$  for a.e.  $\omega \in \Omega$ . Then  $\varphi \in S(\Phi)$  for every  $g \in S(\text{co } G)$ . Assume now  $\varphi \in S(\Phi)$ . Then for every  $A \in \mathcal{F}$  one has  $E_A \varphi \in E_A \Phi$ , where  $E_A \varphi = \int_A \varphi dP$  and  $E_A \Phi = \int_A \Phi dP$ . Let  $\varepsilon > 0$  be given and select a measurable partition  $(A_n^\varepsilon)_{n=1}^{N_\varepsilon}$  of  $\Omega$  such that  $E_{A_n^\varepsilon} \int_0^T m(t, \cdot) dt < \varepsilon/2^{n+1}$ . For every  $n = 1, \dots, N_\varepsilon$  there is a  $g_n^\varepsilon \in S(G)$  such that  $E_{A_n^\varepsilon} \varphi = E_{A_n^\varepsilon} \int_0^T g_n^\varepsilon(t, \cdot) dt$ . Let  $g^\varepsilon = \sum_{n=1}^{N_\varepsilon} \mathbb{1}_{A_n^\varepsilon} g_n^\varepsilon$ . By the decomposability of  $S(G)$  one has  $g^\varepsilon \in S(G)$ . We have  $g^\varepsilon \in S(\text{co } G)$  because  $S(G) \subset S(\text{co } G)$ . Taking a sequence  $(\varepsilon_k)_{k=1}^\infty$  of positive numbers  $\varepsilon_k > 0$  such that  $\varepsilon_k \rightarrow 0$  as  $k \rightarrow \infty$  we can select  $g \in S(\text{co } G)$  and a subsequence, denoted again by  $(g^{\varepsilon_k})_{k=1}^\infty$ , of  $(g^{\varepsilon_k})_{k=1}^\infty$  weakly converging to  $g$  in  $L([0, T] \times \Omega, \mathbb{R}^n)$ , because  $S(\text{co } G)$  is a weakly compact subset of  $L([0, T] \times \Omega, \mathbb{R}^n)$ . For every  $A \in \mathcal{F}$  and  $k = 1, 2, \dots$  there is a subset  $\{n_1, \dots, n_p\}$  of  $\{1, \dots, N_{\varepsilon_k}\}$  such that  $A \cap A_{n_i}^{\varepsilon_k} \neq \emptyset$  for  $i = 1, 2, \dots, p$  and  $A \cap A_r = \emptyset$  for  $r \in \{1, 2, \dots, N_{\varepsilon_k}\} \setminus \{n_1, \dots, n_p\}$ . Therefore

$$\begin{aligned} \left| E_A \varphi - E_A \int_0^T g^{\varepsilon_k}(t, \cdot) dt \right| &\leq \sum_{n=1}^{N_{\varepsilon_k}} \left| E_{A \cap A_n^{\varepsilon_k}} \varphi - E_{A \cap A_n^{\varepsilon_k}} \int_0^T g_n^{\varepsilon_k}(t, \cdot) dt \right| \\ &= \sum_{i=1}^p \left| E_{A \cap A_{n_i}^{\varepsilon_k}} \varphi - E_{A \cap A_{n_i}^{\varepsilon_k}} \int_0^T g_{n_i}^{\varepsilon_k}(t, \cdot) dt \right| \\ &\leq 2 \sum_{i=1}^p E_{A_{n_i}^{\varepsilon_k}} \int_0^T m(t, \cdot) dt \leq \varepsilon_k \end{aligned}$$

for every  $k = 1, 2, \dots$ . On the other hand for every  $A \in \mathcal{F}$  we also have

$$\begin{aligned} & \left| E_A \varphi - E_A \int_0^T g(t, \cdot) dt \right| \leq \\ & \leq \left| E_A \varphi - E_A \int_0^T g^{\varepsilon_k}(t, \cdot) dt \right| + \left| E_A \int_0^T g^{\varepsilon_k}(t, \cdot) dt - E_A \int_0^T g(t, \cdot) dt \right| \\ & \leq \varepsilon_k + \left| E_A \int_0^T g^{\varepsilon_k}(t, \cdot) dt - E_A \int_0^T g(t, \cdot) dt \right| \end{aligned}$$

for  $k = 1, 2, \dots$ . Hence it follows that  $E_A \varphi = E_A \int_0^T g(t, \cdot) dt$  for every  $A \in \mathcal{F}$ , because  $\varepsilon_k \rightarrow 0$  and  $|E_A \int_0^T g^{\varepsilon_k}(t, \cdot) dt - E_A \int_0^T g(t, \cdot) dt| \rightarrow 0$  as  $k \rightarrow \infty$ . Therefore  $\varphi(\omega) = \int_0^T g(t, \cdot) dt$  for a.e.  $\omega \in \Omega$ .  $\square$

**Corollary 2.3.** *If  $G : [0, T] \times \Omega \rightarrow Cl(\mathbb{R}^m)$  is measurable and integrably bounded then*

$$S\left(\int_0^T G(t, \cdot) dt\right) = \left\{ \int_0^T g(t, \cdot) dt : g \in S(co G) \right\}.$$

**Corollary 2.4.** *If  $G : [0, T] \times \Omega \rightarrow Cl(\mathbb{R}^m)$  is measurable and integrably bounded and  $\mathcal{G}$  is a sub- $\sigma$ -algebra of  $\mathcal{F}$  then*

$$S\left(E\left[\int_0^T G(t, \cdot) dt \middle| \mathcal{G}\right]\right) = \left\{ E\left[\int_0^T g(t, \cdot) dt \middle| \mathcal{G}\right] : g \in S(co G) \right\}.$$

*Proof.* It is enough only to see that the set  $\mathcal{H} = \{E[\int_0^T g(t, \cdot) dt | \mathcal{G}] : g \in S(co G)\}$  is a closed subset of  $L(\Omega, \mathcal{G}, \mathbb{R}^m)$ . By the properties of conditional expectations and the properties of the set  $S(co G)$  it follows that  $\mathcal{H}$  is a convex weakly compact subset of  $L(\Omega, \mathcal{G}, \mathbb{R}^m)$ . Therefore  $\mathcal{H}$  is a closed subset of  $L(\Omega, \mathcal{G}, \mathbb{R}^m)$ .  $\square$

### 3. MEASURABLE SELECTION THEOREMS

Let  $x = (x_t)_{0 \leq t \leq T}$  be an  $\mathbb{F}$ -adapted  $m$ -dimensional càdlàg process on  $\mathcal{P}_{\mathbb{F}}$ . Given a measurable and uniformly integrably bounded multivalued mapping  $F : [0, T] \times \mathbb{R}^m \rightarrow Cl(\mathbb{R}^m)$  we denote by  $F \circ x$  a set-valued mapping defined on  $[0, T] \times \Omega$  by setting  $(F \circ x)(t, \omega) = F(t, x_t(\omega))$  for  $(t, \omega) \in [0, T] \times \Omega$ . It is clear that  $F \circ x$  is measurable and  $\mathbb{F}$ -adapted, i.e., it is  $\beta_T \otimes \mathcal{F}$ -measurable and such that for every fixed  $t \in [0, T]$  a mapping  $\Omega \ni \omega \rightarrow (F \circ x)(t, \omega) \subset \mathbb{R}^m$  is  $\mathcal{F}_t$ -measurable. In what follows we shall denote by  $S_{\mathbb{F}}(F \circ x)$  a set of all measurable and  $\mathbb{F}$ -adapted selectors for  $F \circ x$ . Let us observe that  $F \circ x$  is measurable and  $\mathbb{F}$ -adapted if and only if it is  $\Sigma_{\mathbb{F}}$ -measurable, where  $\Sigma_{\mathbb{F}} = \{A \in \beta_T \otimes \mathcal{F} : A_t \in \mathcal{F}_t \text{ for } 0 \leq t \leq T\}$  and  $A_t$  denotes a section of a set  $A \in \beta_T \otimes \mathcal{F}$  at  $t \in [0, T]$ . Therefore, immediately from Kuratowski and Ryll-Nardzewski measurable selection theorem (see [8], Th. II.3.10) it follows that for the given above  $F$  and  $x$  the set  $S_{\mathbb{F}}(F \circ x)$  is nonempty. In the general case we shall also denote by  $S_{\mathbb{F}}(G)$  the set of all measurable and  $\mathbb{F}$ -adapted selectors for a given

measurable  $\mathbb{F}$ -adapted and integrably bounded set-valued mapping  $G : [0, T] \times \Omega \rightarrow Cl(\mathbb{R}^m)$ . Similarly as above we can verify that  $S_{\mathbb{F}}(co G)$  is a nonempty convex and weakly compact subset of  $L([0, T] \times \Omega, \Sigma_{\mathbb{F}}, \mathbb{R}^m)$ . We shall prove the following measurable selection theorem.

**Theorem 3.1.** *Let  $G : [0, T] \times \Omega \rightarrow Cl(\mathbb{R}^m)$  be a measurable  $\mathbb{F}$ -adapted and integrably bounded set-valued mapping. Assume  $x = (x_t)_{0 \leq t \leq T}$  is an  $m$ -dimensional measurable process on  $\mathcal{P}_{\mathbb{F}}$  such that  $E|x_T| < \infty$ . Then*

$$(3.1) \quad x_s \in E \left[ x_t + \int_s^t G(\tau, \cdot) d\tau \middle| \mathcal{F}_s \right] \quad \text{a.s.}$$

for every  $0 \leq s \leq t \leq T$  if and only if there is  $g \in S_{\mathbb{F}}(co G)$  such that

$$(3.2) \quad x_t = E \left[ x_T + \int_t^T g(\tau, \cdot) d\tau \middle| \mathcal{F}_t \right] \quad \text{a.s.}$$

for every  $0 \leq t \leq T$ .

*Proof.* Suppose there is  $g \in S_{\mathbb{F}}(co G)$  such that (3.2) is satisfied. Then for every  $0 \leq s \leq t \leq T$  one has

$$\begin{aligned} x_s &= E \left[ x_T + \int_s^T g(\tau, \cdot) d\tau \middle| \mathcal{F}_s \right] = E \left[ \int_s^t g(\tau, \cdot) d\tau \middle| \mathcal{F}_s \right] \\ &\quad + E \left[ x_T + \int_t^T g(\tau, \cdot) d\tau \middle| \mathcal{F}_s \right] \end{aligned}$$

and

$$E[x_t | \mathcal{F}_s] = E \left[ x_T + \int_t^T g(\tau, \cdot) d\tau \middle| \mathcal{F}_s \right] \quad \text{a.s.}$$

Therefore

$$x_s = E \left[ x_t + \int_s^t g(\tau, \cdot) d\tau \middle| \mathcal{F}_s \right] \quad \text{a.s.}$$

for  $0 \leq s \leq t \leq T$ . Hence by Corollary 2.4 it follows that

$$x_s \in S \left( E \left[ x_t + \int_s^t G(\tau, \cdot) d\tau \middle| \mathcal{F}_s \right] \right)$$

for  $0 \leq s \leq t \leq T$ . Therefore, (3.1) is satisfied a.s. for  $0 \leq s \leq t \leq T$ . Assume that (3.1) is satisfied for every  $0 \leq s \leq t \leq T$  a.s. and let  $m \in L([0, T] \times \Omega, \mathbb{R}_+)$  be such that  $\|G(t, \omega)\| \leq m(t, \omega)$  for a.e.  $(t, \omega) \in [0, T] \times \Omega$ . For every  $0 \leq t \leq T$  one has  $E|x_t| \leq E|x_T| + E \int_0^T m(t, \cdot) dt < \infty$ . By virtue of Corollary 2.4  $x$  is  $\mathbb{F}$ -adapted. Let  $\eta > 0$  be arbitrarily fixed and select  $\delta > 0$  such that  $\delta < T$  and  $\sup_{0 \leq t \leq T-\delta} E \int_t^{t+\delta} m(\tau, \cdot) d\tau < \eta/2$ . For fixed  $t \in [0, T-\delta]$  and  $t \leq \tau \leq t+\delta$  we have  $x_t \in E[x_\tau + \int_t^\tau G(s, \cdot) ds | \mathcal{F}_t]$  a.s. Therefore, for every  $A \in \mathcal{F}_t$  we get  $E_A(x_t - x_\tau) \in E_A \int_t^\tau G(s, \cdot) ds$ . Then  $|E_A(x_t - x_\tau)| \leq E_A \int_t^\tau \|G(s, \cdot)\| ds \leq E \int_t^{t+\delta} m(s, \cdot) ds < \eta/2$  for every  $0 \leq t \leq T-\delta$  and  $A \in \mathcal{F}_t$ . Therefore,  $\sup_{t \leq \tau \leq t+\delta} |E_A(x_t - x_\tau)| \leq \eta/2$  for every  $A \in \mathcal{F}_t$  and fixed  $0 \leq t \leq T-\delta$ . Let  $\tau_0 = 0, \tau_1 = \delta, \dots, \tau_{N-1} = (N-1)\delta < T \leq N\delta$ .

Immediately from (3.1) and Corollary 2.4 it follows that for every  $i = 1, 2, \dots, N - 1$  there is  $g_i^\eta \in S_{\mathbb{F}}(\text{co } G)$  such that

$$E \left| x_{\tau_{i-1}} - E \left[ x_{\tau_i} + \int_{\tau_{i-1}}^{\tau_i} g_i^\eta(s, \cdot) ds \middle| \mathcal{F}_{\tau_{i-1}} \right] \right| = 0.$$

Furthermore, there is  $g_N^\eta \in S_{\mathbb{F}}(\text{co } G)$  such that

$$E \left| x_{\tau_{N-1}} - E \left[ x_T + \int_{\tau_{N-1}}^T g_N^\eta(s, \cdot) ds \middle| \mathcal{F}_{\tau_{N-1}} \right] \right| = 0.$$

Define  $g^\eta = \sum_{i=1}^{N-1} \mathbb{1}_{[\tau_{i-1}, \tau_i)} g_i^\eta + \mathbb{1}_{[\tau_{N-1}, T]} g_N^\eta$ . By the decomposability of  $S_{\mathbb{F}}(\text{co } G)$  we have  $g^\eta \in S_{\mathbb{F}}(\text{co } G)$ . For fixed  $t \in [0, T]$  there is  $p \in \{1, 2, \dots, N - 1\}$  or  $p = N$  such that  $t \in [\tau_{p-1}, \tau_p)$  or  $t \in [\tau_{N-1}, T]$ . Let  $t \in [\tau_{p-1}, \tau_p)$  with  $1 \leq p \leq N - 1$ . For every  $A \in \mathcal{F}_t$  one has

$$\begin{aligned} & \left| E_A \left( x_t - E \left[ x_T + \int_t^T g^\eta(s, \cdot) ds \middle| \mathcal{F}_t \right] \right) \right| \leq \\ & \leq |E_A(x_t - x_{\tau_p})| + E \left| x_{\tau_p} - E \left[ x_{\tau_{p+1}} + \int_{\tau_p}^{\tau_{p+1}} g^\eta(s, \cdot) d\tau \middle| \mathcal{F}_{\tau_p} \right] \right| \\ & + |E_A(E[x_{\tau_{p+1}} | \mathcal{F}_{\tau_p}] - x_{\tau_{p+1}})| + E \left| \int_t^{\tau_p} g^\eta(s, \cdot) ds \right| + \\ & + \left| E_A \left( E \left[ \int_{\tau_p}^{\tau_{p+1}} g^\eta(s, \cdot) ds \middle| \mathcal{F}_{\tau_p} \right] - E \left[ \int_{\tau_p}^{\tau_{p+1}} g^\eta(s, \cdot) d\tau \middle| \mathcal{F}_t \right] \right) \right| + \dots + \\ & + E \left| x_{\tau_{N-1}} - E \left[ x_T + \int_{\tau_{N-1}}^T g^\eta(s, \cdot) d\tau \middle| \mathcal{F}_{\tau_{N-1}} \right] \right| \\ & + |E_A(E[x_{\tau_{N-1}} | \mathcal{F}_{\tau_{N-1}}] - x_{\tau_{N-1}})| + E_A \left( E \left[ \int_{\tau_{N-1}}^T g^\eta(s, \cdot) ds \middle| \mathcal{F}_{\tau_{N-1}} \right] - \right. \\ & \left. - E \left[ \int_{\tau_{N-1}}^T g^\eta(s, \cdot) ds \middle| \mathcal{F}_t \right] \right) \Big| \leq \sup_{t \leq \tau \leq t+\delta} |E_A(x_t - x_\tau)| + E \int_t^{t+\delta} m(s, \cdot) ds + \\ & + \sum_{i=p}^{N-2} E \left| x_{\tau_i} - E \left[ x_{\tau_{i+1}} + \int_{\tau_i}^{\tau_{i+1}} g^\eta(s, \cdot) ds \middle| \mathcal{F}_{\tau_i} \right] \right| \\ & + E \left| x_{\tau_{N-1}} - E \left[ x_T + \int_{\tau_{N-1}}^T g^\eta(s, \cdot) d\tau \middle| \mathcal{F}_{\tau_{N-1}} \right] \right| \\ & + \sum_{i=p}^{N-2} |E_A(E[x_{\tau_{i+1}} | \mathcal{F}_{\tau_i}] - x_{\tau_{i+1}})| + \sum_{i=p}^{N-2} \left| E_A \left( E \left[ \int_{\tau_i}^{\tau_{i+1}} g^\eta(s, \cdot) ds \middle| \mathcal{F}_{\tau_i} \right] - \right. \right. \\ & \left. \left. - E \left[ \int_{\tau_i}^{\tau_{i+1}} g^\eta(s, \cdot) ds \middle| \mathcal{F}_t \right] \right) \right| \\ & + \left| E_A \left( E \left[ \int_{\tau_{N-1}}^T g^\eta(s, \cdot) ds \middle| \mathcal{F}_{\tau_{N-1}} \right] - E \left[ \int_{\tau_{N-1}}^T g^\eta(s, \cdot) ds \middle| \mathcal{F}_t \right] \right) \right|. \end{aligned}$$

But  $\mathcal{F}_t \subset \mathcal{F}_{\tau_i}$  for  $i = p, p+1, \dots, N-1$ . Then for  $A \in \mathcal{F}_t$  one has

$$\sum_{i=p}^{N-2} |E_A(E[x_{\tau_{i+1}}|\mathcal{F}_{\tau_i}] - x_{\tau_{i+1}})| = 0,$$

$$\sum_{i=p}^{N-2} \left| E_A \left( E \left[ \int_{\tau_i}^{\tau_{i+1}} g^\eta(s, \cdot) ds | \mathcal{F}_{\tau_i} \right] - E \left[ \int_{\tau_i}^{\tau_{i+1}} g^\eta(s, \cdot) ds | \mathcal{F}_t \right] \right) \right| = 0$$

and

$$\left| E_A \left( E \left[ \int_{\tau_{N-1}}^T g^\eta(s, \cdot) ds | \mathcal{F}_{\tau_{N-1}} \right] - E \left[ \int_{\tau_{N-1}}^T g^\eta(s, \cdot) ds | \mathcal{F}_t \right] \right) \right| = 0.$$

Hence it follows

$$\left| E_A \left( x_t - E \left[ x_T + \int_t^T g^\eta(s, \cdot) ds | \mathcal{F}_t \right] \right) \right| \leq \eta$$

for fixed  $0 \leq t \leq T$  and  $A \in \mathcal{F}_t$ . Let  $(\eta_j)_{j=1}^\infty$  be a sequence of positive numbers converging to zero. For every  $j = 1, 2, \dots$  we can select  $g^{\eta_j} \in S_{\mathbb{F}}(\text{co } G)$  such that (3.2) is satisfied with  $\eta = \eta_j$ . By the weak compactness of  $S_{\mathbb{F}}(\text{co } G)$  there are  $g \in S_{\mathbb{F}}(\text{co } G)$  and a subsequence  $(g^{\eta_k})_{k=1}^\infty$  of  $(g^{\eta_j})_{j=1}^\infty$  weakly converging to  $g$  in  $L([0, T] \times \Omega, \Sigma_{\mathbb{F}}, \mathbb{R})$ . Then for every  $A \in \mathcal{F}_t \subset \mathcal{F}$  one has  $\lim_{k \rightarrow \infty} E_A \int_t^T g^{\eta_k}(s, \cdot) ds = E_A \int_t^T g(s, \cdot) ds$ . On the other hand for every fixed  $t \in [0, T]$  and  $A \in \mathcal{F}_t$  we have

$$\begin{aligned} & \left| E_A \left( x_t - E \left[ x_T + \int_t^T g(s, \cdot) ds | \mathcal{F}_t \right] \right) \right| \leq \\ & \leq \left| E_A \left( x_t - E \left[ x_T + \int_t^T g^{\eta_k}(s, \cdot) ds | \mathcal{F}_t \right] \right) \right| + \\ & + \left| E_A \left( E \left[ \int_t^T g^{\eta_k}(s, \cdot) ds | \mathcal{F}_t \right] - E \left[ \int_t^T g(s, \cdot) ds | \mathcal{F}_t \right] \right) \right| \leq \\ & \leq \eta_k + \left| E_A \int_t^T g^{\eta_k}(s, \cdot) ds - E_A \int_t^T g(s, \cdot) ds \right| \end{aligned}$$

for  $k = 1, 2, \dots$ . Therefore

$$E_A \left( x_t - E \left[ x_T + \int_t^T g(s, \cdot) ds | \mathcal{F}_t \right] \right) = 0$$

for every  $A \in \mathcal{F}_t$  and fixed  $0 \leq t \leq T$ . But  $x_t$  and  $E[x_T + \int_t^T g(s, \cdot) ds | \mathcal{F}_t]$  are  $\mathcal{F}_t$ -measurable. Then  $x_t = E[x_T + \int_t^T g(s, \cdot) ds | \mathcal{F}_t]$  for  $0 \leq t \leq T$  with (P.1).  $\square$

**Corollary 3.2.** *Let  $G : [0, T] \times \Omega \rightarrow Cl(\mathbb{R}^m)$  be measurable  $\mathbb{F}$ -adapted and square integrably bounded. If  $x = (x_t)_{0 \leq t \leq T}$  is measurable, satisfies (3.1) a.s. for every  $0 \leq s \leq t \leq T$  and  $E|x_T|^2 < \infty$  then  $x \in \mathcal{S}^2(\mathbb{F}, \mathbb{R}^m)$  and  $x_t = x_0 + M_t + A_t$ , where  $M_t = E[x_T + \int_0^T g_\tau d\tau | \mathcal{F}_t] - E[x_T + \int_0^T g_\tau d\tau | \mathcal{F}_0]$  and  $A_t = -\int_0^t g_\tau d\tau$  for  $0 \leq t \leq T$  with  $g \in S_{\mathbb{F}}(\text{co } G)$  such that  $x_t = E[x_T + \int_t^T g_\tau d\tau | \mathcal{F}_t]$  a.s. for  $0 \leq t \leq T$ .*



*Proof.* The result follows immediately from the representation  $x_t = E[x_T + \int_t^T g_\tau d\tau | \mathcal{F}_t]$  given in Theorem 3.1 (see [3], Lemma 1.1).  $\square$

In what follows we shall assume that  $F : [0, T] \times \mathbb{R}^m \rightarrow Cl(\mathbb{R}^m)$  and  $H : \mathbb{R}^m \rightarrow Cl(\mathbb{R}^m)$  satisfy the following conditions (A):

- (i)  $F$  is measurable and uniformly square integrably bounded by a function  $m \in L^2([0, T], \mathbb{R}_+)$ ,
- (ii)  $H$  is measurable and bounded by a number  $L > 0$ ,
- (iii)  $F(t, \cdot)$  is Lipschitz continuous, i.e. there is  $k \in L^2([0, T], \mathbb{R}_+)$  such that  $h(F(t, x_1), F(t, x_2)) \leq k(t)|x_1 - x_2|$  for a.e.  $t \in [0, T]$  and  $x_1, x_2 \in \mathbb{R}^m$ , where  $h$  is the Hausdorff metric on  $Cl(\mathbb{R}^m)$ ,
- (iv) there is a random variable  $\xi \in L^2(\Omega, \mathcal{F}_T, \mathbb{R}^m)$  such that  $\xi \in H(\xi)$  a.s.

We shall prove now that conditions (A) imply the existence of some special sequence of successive approximations for BSDI(F, H).

**Theorem 3.3.** *Let  $F : [0, T] \times \mathbb{R}^m \rightarrow Cl(\mathbb{R}^m)$  and  $H : \mathbb{R}^m \rightarrow Cl(\mathbb{R}^m)$  satisfy conditions (A). There exists a sequence  $(x^n)_{n=1}^\infty$  of  $\mathcal{S}^2(\mathbb{F}, \mathbb{R}^m)$  defined by  $x_t^n = E[\xi + \int_t^T f_\tau^{n-1} d\tau | \mathcal{F}_t]$  a.s. with  $f^{n-1} \in S_{\mathbb{F}}(F \circ x^{n-1})$  for  $n = 1, 2, \dots$  and  $0 \leq t \leq T$  such that  $x_s^n \in E[x_t^n + \int_s^t F(\tau, x_\tau^{n-1}) d\tau | \mathcal{F}_s]$  a.s. and  $E \sup_{t \leq u \leq T} |x_u^{n+1} - x_u^n|^2 \leq 4E(\int_t^T k(\tau) \sup_{\tau \leq s \leq T} |x_s^n - x_s^{n-1}| d\tau)^2$  for  $n = 1, 2, \dots$  and  $0 \leq s \leq t \leq T$ .*

*Proof.* Let us observe (see [8], Th. II.3.13) that for every  $m$ -dimensional measurable and  $\mathbb{F}$ -adapted processes  $x$  and  $y$  on  $\mathcal{P}_{\mathbb{F}}$  and every  $f^x \in S_{\mathbb{F}}(F \circ x)$  there is  $f^y \in S_{\mathbb{F}}(F \circ y)$  such that  $|f_t^x(\omega) - f_t^y(\omega)| = \text{dist}(f_t^x(\omega), F(t, y_t(\omega))) \leq h(F(t, x_t(\omega)), F(t, y_t(\omega))) \leq k(t)|x_t(\omega) - y_t(\omega)|$  for a.e.  $t \in [0, T]$  and  $\omega \in \Omega$ . Furthermore, by properties of  $H$  there is  $\xi \in L^2(\Omega, \mathcal{F}_T, \mathbb{R}^m)$  such that  $\xi \in H(\xi)$  a.s. Let  $(x_t^0)_{0 \leq t \leq T}$  be an  $m$ -dimensional measurable  $\mathbb{F}$ -adapted process on  $\mathcal{P}_{\mathbb{F}}$  such that  $x_T^0 = \xi$  a.s. and let  $f^0 \in S_{\mathbb{F}}(F \circ x^0)$ . Define  $x_t^1 = E[\xi + \int_t^T f_\tau^0 d\tau | \mathcal{F}_t]$  a.s. for  $0 \leq t \leq T$ . By Corollary 3.2 we have  $x^1 \in \mathcal{S}^2(\mathbb{F}, \mathbb{R}^m)$ . Select now  $f^1 \in S_{\mathbb{F}}(F \circ x^1)$  such that  $|f_t^1 - f_t^0| = \text{dist}(f_t^1, F(t, x_t^0))$  for a.e.  $0 \leq t \leq T$  with (P.1). Then  $|f_t^1 - f_t^0| \leq k(t)|x_t^1 - x_t^0|$  a.s. for a.e.  $0 \leq t \leq T$ . Define  $x_t^2 = E[\xi + \int_t^T f_\tau^1 d\tau | \mathcal{F}_t]$  a.s. for  $0 \leq t \leq T$ . We have  $x^2 \in \mathcal{S}^2(\mathbb{F}, \mathbb{R}^m)$ . Continuing the above procedure we can define  $x_t^{n+1} = E[\xi + \int_t^T f_\tau^n d\tau | \mathcal{F}_t]$  a.s. for  $0 \leq t \leq T$  with  $f^n \in S_{\mathbb{F}}(F \circ x^n)$  such that  $|f_t^n - f_t^{n-1}| \leq k(t)|x_t^n - x_t^{n-1}|$  a.s. for a.e.  $0 \leq t \leq T$  and  $n = 2, 3, \dots$ . By Corollary 3.2 we also have  $x^n \in \mathcal{S}^2(\mathbb{F}, \mathbb{R}^m)$ . Hence it follows

$$\begin{aligned} |x_t^{n+1} - x_t^n| &\leq E \left[ \int_t^T |f_\tau^n - f_\tau^{n-1}| d\tau | \mathcal{F}_t \right] \\ &\leq E \left[ \int_t^T k(\tau) \sup_{\tau \leq s \leq T} |x_s^n - x_s^{n-1}| | \mathcal{F}_t \right] \end{aligned}$$

a.s. for  $0 \leq t \leq T$ . Therefore,

$$\begin{aligned} & \sup_{t \leq u \leq T} |x_u^{n+1} - x_u^n| \\ & \leq \sup_{t \leq u \leq T} E \left[ \int_u^T k(\tau) \sup_{\tau \leq s \leq T} |x_s^n - x_s^{n-1}| d\tau | \mathcal{F}_u \right] \leq \\ & \leq \sup_{t \leq u \leq T} E \left[ \int_t^T k(\tau) \sup_{\tau \leq s \leq T} |x_s^n - x_s^{n-1}| d\tau | \mathcal{F}_u \right] \end{aligned}$$

a.s. for  $0 \leq t \leq T$  and  $n = 1, 2, \dots$ . By Doob's inequality, we obtain

$$\begin{aligned} & E \left( \sup_{t \leq u \leq T} E \left[ \int_t^T k(\tau) \sup_{\tau \leq s \leq T} |x_s^n - x_s^{n-1}| d\tau | \mathcal{F}_u \right] \right)^2 \leq \\ & \leq 4E \left( \int_t^T k(\tau) \sup_{\tau \leq s \leq T} |x_s^n - x_s^{n-1}| d\tau \right)^2 \end{aligned}$$

for  $0 \leq t \leq T$ . Therefore, for every  $n = 1, 2, \dots$  and  $0 \leq t \leq T$  we have

$$E \sup_{t \leq u \leq T} |x_u^{n+1} - x_u^n|^2 \leq 4E \left( \int_t^T k(\tau) \sup_{\tau \leq t \leq T} |x_s^n - x_s^{n-1}| d\tau \right)^2.$$

□

#### 4. EXISTENCE OF STRONG SOLUTIONS

We shall prove that if  $F$  and  $H$  satisfy conditions (A) then BSDI(F,H) possesses at least one strong solution. Let us observe that immediately from Corollary 3.2 it follows that every strong solution to BSDI(F,H) on  $\mathcal{P}_{\mathbb{F}}$  belongs to  $\mathcal{S}^2(\mathbb{F}, \mathbb{R}^m)$ . Immediately from the properties of multivalued conditional expectations (see [5], Prop. 6.2.) the following result follows.

**Proposition 4.1.** *Let  $F$  satisfies conditions (A). Then for every  $x, y \in \mathcal{S}^2(\mathbb{F}, \mathbb{R}^m)$  one has*

$$Eh \left( E \left[ \int_s^t F(\tau, x_\tau) d\tau | \mathcal{F}_s \right], E \left[ \int_s^t F(\tau, y_\tau) d\tau | \mathcal{F}_s \right] \right) \leq \int_s^t k(\tau) E |x_\tau - y_\tau| d\tau$$

for every  $0 \leq s \leq t \leq T$ , where  $h$  is the Hausdorff metric on  $Cl(\mathbb{R}^m)$ .

We can prove now the following existence theorem.

**Theorem 4.2.** *Let  $\mathcal{P}_{\mathbb{F}}$  be given. If  $F : [0, T] \times \mathbb{R}^n \rightarrow Cl(\mathbb{R}^n)$  and  $H : \mathbb{R}^m \rightarrow Cl(\mathbb{R}^m)$  satisfy conditions (A) then BSDI(F, H) possesses a strong solution on  $\mathcal{P}_{\mathbb{F}}$ .*

*Proof.* By virtue Theorem 3.3 there is a sequence  $(x^n)_{n=1}^\infty$  of  $\mathcal{S}^2(\mathbb{F}, \mathbb{R}^m)$  such that  $x_T^n = \xi$ ,  $x_s^n \in E[x_t^n + \int_s^t F(\tau, x_\tau^{n-1}) d\tau | \mathcal{F}_t]$  a.s. for  $0 \leq s \leq t \leq T$  and

$$E \sup_{t \leq u \leq T} |x_u^{n+1} - x_u^n|^2 \leq 4E \left( \int_t^T k(\tau) \sup_{\tau \leq s \leq T} |x_s^n - x_s^{n-1}| d\tau \right)^2,$$

where  $\xi \in L^2(\Omega, \mathcal{F}_T, \mathbb{R}^m)$  is such that  $\xi \in H(\xi)$  a.s. Hence it follows

$$E \sup_{t \leq u \leq T} |x_u^{n+1} - x_u^n|^2 \leq 4T \int_t^T k^2(\tau) E \sup_{\tau \leq u \leq T} |x_u^n - x_u^{n-1}|^2 d\tau$$

for  $n = 1, 2, \dots$  and  $0 \leq t \leq T$ . By the properties of  $F$  and  $H$  one has  $E \sup_{t \leq u \leq T} |x_u^1 - x_u^0|^2 \leq \mathbb{L}$ , where  $\mathbb{L} = 4(E|\xi|^2 + \int_0^T m^2(\tau) d\tau) + 2E \sup_{0 \leq t \leq T} |x_t^0|^2$ . Therefore,

$$E \sup_{t \leq u \leq T} |x_u^2 - x_u^1|^2 \leq 4T\mathbb{L} \int_t^T k^2(\tau) d\tau.$$

Hence it follows

$$\begin{aligned} E \sup_{t \leq u \leq T} |x_u^3 - x_u^2|^2 &\leq (4T)^2 \mathbb{L} \int_t^T \left( k^2(\tau) \int_\tau^T k^2(s) ds \right) d\tau \\ &= \frac{(4T)^2 \mathbb{L}}{2} \left( \int_t^T k^2(\tau) d\tau \right)^2. \end{aligned}$$

By the induction procedure for every  $n = 1, 2, \dots$  and  $0 \leq t \leq T$  we get

$$E \sup_{t \leq u \leq T} |x_u^{n+1} - x_u^n|^2 \leq \frac{(4T)^n \mathbb{L}^{n-1}}{n!} \left( \int_t^T k^2(\tau) d\tau \right)^n.$$

Then  $E \sup_{0 \leq t \leq T} |x_t^n - x_t^m|^2 \rightarrow 0$  as  $n, m \rightarrow \infty$ . Therefore, there is a process  $(x_t)_{0 \leq t \leq T} \in \mathcal{S}^2(\mathbb{F}, \mathbb{R}^m)$  such that  $E \sup_{0 \leq t \leq T} |x_t^n - x_t|^2 \rightarrow 0$  as  $n \rightarrow \infty$ . Hence and Proposition 4.1 it follows

$$\begin{aligned} &E \text{dist} \left( x_s, E \left[ x_t + \int_s^t F(\tau, x_\tau) d\tau | \mathcal{F}_s \right] \right) \\ &\leq E|x_s - x_s^n| + E \text{dist} \left( x_s^n, E \left[ x_t^n + \int_s^t F(\tau, x_\tau^{n-1}) d\tau | \mathcal{F}_s \right] \right) + \\ &+ E h \left( E \left[ x_t^n + \int_s^t F(\tau, x_\tau^{n-1}) d\tau | \mathcal{F}_s \right], E \left[ x_t + \int_s^t F(\tau, x_\tau) d\tau | \mathcal{F}_s \right] \right) \\ &\leq E|x_s^n - x_s| + E|x_t^n - x_t| + \int_s^t k(\tau) E|x_\tau^{n-1} - x_\tau| d\tau \\ &\leq 2\|x^n - x\|_{S^2} + \left( \int_0^T k^2(\tau) d\tau \right)^{\frac{1}{2}} \|x^{n-1} - x\|_{S^2} \end{aligned}$$

for every  $0 \leq s \leq t \leq T$  and  $n = 1, 2, \dots$ . Therefore,  $\text{dist}(x_s, E[x_t + \int_s^t F(\tau, x_\tau) d\tau | \mathcal{F}_s]) = 0$  a.s. for every  $0 \leq s \leq t \leq T$ . Then  $x_s \in E[x_t + \int_s^t F(\tau, x_\tau) d\tau | \mathcal{F}_s]$  a.s. for every  $0 \leq s \leq t \leq T$ . By the definition of  $(x_t^n)_{0 \leq t \leq T}$  we have  $x_T^n = \xi \in H(\xi)$  a.s. for every  $n = 1, 2, \dots$ . Therefore, we also have  $x_T = \xi$  a.s. Then  $x_T \in H(x_T)$  a.s.  $\square$

## 5. EXISTENCE OF WEAK SOLUTIONS

Asume that  $F : [0, T] \times \mathbb{R}^m \rightarrow Cl(\mathbb{R}^m)$  and  $H : \mathbb{R}^m \rightarrow Cl(\mathbb{R}^m)$  satisfy the following conditions (B).

- (i)  $F$  is measurable and uniformly square integrably bounded by a function  $m \in L^2([0, T], \mathbb{R}_+)$ ,
- ii)  $H$  takes on convex values is measurable and bounded by a number  $L > 0$ ,
- (iii)  $F(t, \cdot)$  and  $H$  are lower semicontinuous for a.e. fixed  $0 \leq t \leq T$ .

We shall prove that for  $F$  and  $H$  satisfying conditions (B) there exists a continuous weak solution to BSDI(F,H), i.e. there exists a pair  $(\mathcal{P}_{\mathbb{F}}, x)$ , with  $x$  having a.a. continuous trajectories and satisfying BSDI(F,H). The result is obtained by the construction of the Tonelli's type approximations for a backward stochastic differential equation defined by some special selectors of  $F$  and  $H$  on a filtered probability space  $\mathcal{P}_{\mathbb{F}} = (\Omega, \mathcal{F}, P, \mathbb{F}^B)$  with  $(\Omega, \mathcal{F}, P)$  supporting an  $d$ -dimensional Brownian motion  $B$  and  $\mathbb{F}^B = (\mathcal{F}_t^B)_{0 \leq t \leq T}$  being a natural augmented filtration of  $B$ . The tightness of such approximation sequence will follow from the following extension of the classical tightness criterion (see [1], Th. 2.12.3).

**Theorem 5.1** ([9], Th. 3). *A sequence  $(x^n)_{n=1}^{\infty}$  of continuous  $m$ -dimensional stochastic processes  $x^n = (x^n(t))_{0 \leq t \leq T}$  on a probability space  $(\Omega, \mathcal{F}, P)$  is tight if for every  $\varepsilon > 0$  there is a number  $a > 0$  such that  $P(\{|x^n(0)| > a\}) \leq \varepsilon$  for  $n \geq 1$  and there are  $\gamma \geq 0$ , an integer  $\alpha > 1$  and a continuous nondecreasing bounded stochastic process  $(\Gamma(t))_{0 \leq t \leq T}$  on  $(\Omega, \mathcal{F}, P)$  such that*

$$P(\{|x^n(t) - x^n(s)| \geq \eta\}) \leq \frac{1}{\eta^\gamma} E |\Gamma(t) - \Gamma(s)|^\alpha$$

for every  $n \geq 1$ ,  $\eta > 0$  and  $s, t \in [0, T]$ .

We shall also need the following results.

**Proposition 5.2.** *Let  $F : [0, T] \times \mathbb{R}^m \rightarrow Cl(\mathbb{R}^m)$  and  $H : \mathbb{R}^m \rightarrow Cl(\mathbb{R}^m)$  be measurable and uniformly square integrably bounded and bounded, respectively. A pair  $(\mathcal{P}_{\mathbb{F}}, x)$  is a continuous weak solution to BSDI(F,H) if and only if there exist  $\xi \in S(H \circ x_T)$  and  $f \in S_{\mathbb{F}}(coF \circ x)$  such that  $x_t = E[\xi + \int_t^T f_\tau d\tau | \mathcal{F}_t]$  a.s. for  $0 \leq t \leq T$  and such that a martingale  $M = (M_t)_{0 \leq t \leq T}$  defined by  $M_t = E[\xi + \int_0^T f_\tau d\tau | \mathcal{F}_t] - E[\xi + \int_0^T f_\tau d\tau | \mathcal{F}_0]$  is continuous.*

*Proof.* By virtue of Theorem 3.1 a pair  $(\mathcal{P}_{\mathbb{F}}, x)$  is a weak solution to BSDI(F,H) if and only if there are  $\xi \in S(H \circ x_T)$  and  $f \in S_{\mathbb{F}}(coF \circ x)$  such that  $x_t = E[\xi + \int_t^T f_\tau d\tau | \mathcal{F}_t]$  a.s. for  $0 \leq t \leq T$ . By Corollary 3.2 we have  $x_t = x_0 + M_t - \int_0^t f_\tau d\tau$  a.s. for  $0 \leq t \leq T$ . Hence it follows that  $x$  is continuous if and only if  $M$  is continuous.  $\square$

**Proposition 5.3.** *Let  $F : [0, T] \times \mathbb{R}^m \rightarrow Cl(\mathbb{R}^m)$  and  $H : \mathbb{R}^m \rightarrow Cl(\mathbb{R}^m)$  be measurable and uniformly square integrably bounded and bounded, respectively. Assume  $F(t, \cdot)$  and  $H$  are continuous and let  $(x^n)_{n=1}^\infty$  be a sequence of continuous solutions to  $BSDI(F, H)$  on a filtered probability space  $\mathcal{P}_{\mathbb{F}}$ . Then  $(x^n)_{n=1}^\infty$  is tight.*

*Proof.* By virtue of Corollary 3.2 we have  $x_t^n = x_0^n + M_t^n - \int_0^t f_\tau^n d\tau$  a.s. for  $0 \leq t \leq T$ , where  $f^n \in S_{\mathbb{F}}(coF \circ x^n)$  and  $M^n$  is an  $\mathbb{F}$ -martingale defined above for  $n = 1, 2, \dots$ . By properties of  $F$  and Proposition 5.2,  $M^n$  is for every  $n = 1, 2, \dots$  a square integrable continuous martingale such that  $M_0^n = 0$  for  $n \geq 1$ . Furthermore  $|M_t^n| \leq 2\lambda$  a.s. for  $0 \leq t \leq T$ , where  $\lambda = L + \int_0^T m(t)dt$ . Denote by  $N_i^n$  for  $n \geq 1$  and  $i = 1, 2, \dots, m$  a real-valued  $\mathbb{F}$ -martingale such that  $M_t^n = (N_1^n(t), \dots, N_m^n(t))$  for  $0 \leq t \leq T$ . For every  $i = 1, \dots, m$  and every partition  $\Delta = \{0 = t_0 < t_1 < \dots < t_r = T\}$  of  $[0, T]$  one gets

$$\begin{aligned} \langle N_i^n \rangle_t^\Delta &\doteq \sum_{k=0}^{r-1} (N_i^n(t \wedge t_{k+1}) - N_i^n(t \wedge t_k))^2 \leq \\ &\leq \sum_{j=1}^{r-1} |N_i^n(t \wedge t_{j+1}) - N_i^n(t \wedge t_j)| \max_k |N_i^n(t \wedge t_{k+1}) - N_i^n(t \wedge t_k)| \\ &\leq |N_i^n(t)| \max_k |N_i^n(t \wedge t_{k+1}) - N_i^n(t \wedge t_k)| \leq 8\lambda^2 \end{aligned}$$

a.s. for  $0 \leq t \leq T$ . Moreover, by ([10], Th. 2.2.2) we have  $\sup_{0 \leq t \leq T} E |\langle N_i^n \rangle_t^{\Delta_r} - \langle N_i^n \rangle_t|^2 \rightarrow 0$  as  $|\Delta_r| \rightarrow 0$ , where  $|\Delta_r| = \max_{0 \leq k \leq r-1} (t_{k+1} - t_k)$ . Then there is a subsequence  $(\Delta_{r_j})_{j=1}^\infty$  of  $(\Delta_r)_{r=1}^\infty$  such that  $\sup_{0 \leq t \leq T} |\langle N_i^n \rangle_t^{\Delta_{r_j}} - \langle N_i^n \rangle_t| \rightarrow 0$  a.s. as  $j \rightarrow \infty$ . Hence it follows

$$\begin{aligned} \sup_{0 \leq t \leq T} |\langle N_i^n \rangle_t| &\leq \sup_{0 \leq t \leq T} \left| \langle N_i^n \rangle_t - \langle N_i^n \rangle_t^{\Delta_{r_j}} \right| + \left| \langle N_i^n \rangle_t^{\Delta_{r_j}} \right| \\ &\leq \sup_{0 \leq t \leq T} \left| \langle N_i^n \rangle_t - \langle N_i^n \rangle_t^{\Delta_{r_j}} \right| + 8\lambda^2 \end{aligned}$$

a.s. for every  $n \geq 1$  and  $i = 1, \dots, m$ . Then  $\sup_{0 \leq t \leq T} |\langle N_i^n \rangle_t| \leq 8\lambda^2$  a.s. for every  $n \geq 1$  and  $i = 1, \dots, m$ . Let us observe that quadratic variational process  $(\langle N_i^n \rangle_t)_{0 \leq t \leq T}$  is increasing in  $t$  a.s. for every  $n \geq 1$  and  $i = 1, \dots, m$ . Then for every  $n \geq 1$ ,  $i = 1, \dots, m$  and  $P$ -a.e.  $\omega \in \Omega$  it generates a measure  $\mu_i^n(\omega)$  on  $\beta_T = \beta([0, T])$  such that  $\mu_i^n(\omega)((s, t]) = \langle N_i^n \rangle_t - \langle N_i^n \rangle_s$  and  $\mu_i^n(\omega)(\{0\}) = 0$ . Let  $\mu^n(\omega)(A) = \max_{0 \leq i \leq m} \mu_i^n(\omega)(A)$  and  $\mu(\omega)(A) = \sup_{n \geq 1} \mu^n(\omega)(A)$  for  $A \in \beta_T$  and  $P$ -a.e.  $\omega \in \Omega$ . Similarly as in the proof of ([5], Prop. 8.5.17) it can be verified that  $\mu(\omega)$  is a measure on  $\beta_T$  for  $P$ -a.e.  $\omega \in \Omega$ . It can be also verified that for every  $A \in \beta_T$  a mapping  $\Omega \ni \omega \rightarrow \mu(\omega)(A) \in \mathbb{R}^+$  is a random variable such that  $\mu(\omega)((0, T]) \leq 8\lambda^2$  for  $P$ -a.e.  $\omega \in \Omega$ . By Itô's formula and Doob's inequality one obtains

$$E (N_i^n(t) - N_i^n(s))^{2k} =$$

$$\begin{aligned}
E \left( \int_s^t dN_i^n(u) \right)^{2k} &= k(k-1) E \int_s^t \left( \int_s^\tau dN_i^n(u) \right)^{2(k-1)} d\langle N_i^n \rangle_\tau \\
&\leq k(k-1) \left[ E \sup_{s \leq \tau \leq t} \left( \int_s^\tau dN_i^n(u) \right)^{4(k-1)} \right]^{\frac{1}{2}} \left[ E \left( \int_s^t d\langle N_i^n \rangle_\tau \right)^2 \right]^{\frac{1}{2}} \leq \\
&\leq C_k \left[ E \left( \int_s^t dN_i^n(u) \right)^{4(k-1)} \right]^{\frac{1}{2}} \left[ E \left( \int_s^t d\langle N_i^n \rangle_\tau \right)^2 \right]^{\frac{1}{2}},
\end{aligned}$$

where  $C_k = k(k-1) \left( \frac{4(k-1)}{4k-3} \right)^{4(k-1)}$  for  $0 \leq s < t \leq T$ ,  $n \geq 1$  and  $i = 1, \dots, m$ . Hence, in particular for  $k = 2$  it follows

$$\begin{aligned}
&E \left( \mathbf{1}_{A_i^n(s,t)} (N_i^n(t) - N_i^n(s))^4 \right) = \\
&\leq C_2 \left[ E \left( \mathbf{1}_{A_i^n(s,t)} (N_i^n(t) - N_i^n(s))^4 \right) \right]^{\frac{1}{2}} \left[ E \left( \int_s^t d\mu \right)^2 \right]^{\frac{1}{2}},
\end{aligned}$$

where  $A_i^n(s, t) = \{\omega \in \Omega : N_i^n(t) - N_i^n(s) > 0\}$  for fixed  $0 \leq s < t \leq T$ ,  $n \geq 1$  and  $i = 1, \dots, m$ . Then

$$\left[ E \mathbf{1}_{A_i^n(s,t)} (N_i^n(t) - N_i^n(s))^4 \right]^{\frac{1}{2}} \leq C_2 \left[ E \left( \int_s^t d\mu \right)^2 \right]^{\frac{1}{2}},$$

which implies that

$$E (N_i^n(t) - N_i^n(s))^4 \leq C_2^2 E \left( \int_s^t d\mu \right)^2$$

for  $0 \leq s < t \leq T$ ,  $n \geq 1$  and  $i = 1, \dots, m$ . Hence it follows

$$\begin{aligned}
E |M_t^n - M_s^n|^4 &= E \left( \sum_{i=1}^m |N_i^n(t) - N_i^n(s)| \right)^4 \leq \\
&C_m \sum_{i=1}^m E (N_i^n(t) - N_i^n(s))^4 \leq C_m m C_2^2 E \left( \int_s^t d\mu \right)^2
\end{aligned}$$

for  $0 \leq s < t \leq T$  and  $n \geq 1$ , where  $C_m$  is a positive number depending on  $m$ . Finally, there is a positive number  $C = \int_0^T m^2(t) dt$  such that

$$\begin{aligned}
E |x_t^n - x_s^n|^4 &\leq 4E |M_t^n - M_s^n|^4 + 4E \left| \int_s^t f_\tau^n d\tau \right|^4 \\
&\leq 4C_m m C_2^2 E \left( \int_s^t d\mu \right)^2 + 4C^2 (t-s)^2 \leq E \left[ 2C_2 \sqrt{mC_m} \int_s^t d\mu + 2C(t-s) \right]^2 \\
&= E |\Gamma(t) - \Gamma(s)|^2,
\end{aligned}$$

for  $0 \leq s < t \leq T$  and  $n \geq 1$ , where  $\Gamma(t) = 2C_2 \sqrt{mC_m} \int_0^t d\mu + 2Ct$ . Hence, by Doob's inequality it follows

$$P(\{|x_t^n - x_s^n| \geq \eta\}) \leq \frac{1}{\eta^4} E |x_t^n - x_s^n|^4 \leq \frac{1}{\eta^4} E |\Gamma(t) - \Gamma(s)|^2$$

for  $\eta > 0$ ,  $0 \leq s < t \leq T$  and  $n \geq 1$ . Finally, let us recall that  $|x_t^n| \leq \lambda$  a.s. for  $0 \leq t \leq T$  and  $n \geq 1$  with  $\lambda = L + \int_0^T m(t)dt$ . Therefore, for every  $N \geq 1$  one has  $P(\{|x_0^n| > N\}) \leq \lambda/N$  for  $n \geq 1$ . Then  $\sup_{n \geq 1} P(\{|x_0^n| > N\}) \rightarrow 0$  as  $N \rightarrow \infty$ . Therefore, for every  $\varepsilon > 0$  there is  $a > 0$  such that  $P(\{|x_0^n| > a\}) \leq \varepsilon$  for  $n \geq 1$ . Then by virtue of Theorem 5.1 a sequence  $(x^n)_{n=1}^\infty$  is tight.  $\square$

We can prove now the existence of continuous weak solutions to BSDI(F,H).

**Theorem 5.4.** *Let  $F : [0, T] \times \mathbb{R}^m \rightarrow Cl(\mathbb{R}^m)$  and  $H : \mathbb{R}^m \rightarrow Cl(\mathbb{R}^m)$  satisfy conditions (B). Then BSDI(F,H) possesses a continuous weak solution.*

*Proof.* By Michael’s and Rybinski’s continuous selection theorems (see [8], Th. II.4.1 and [15], Th. 2) there exist a continuous selector  $h$  of  $H$  and a Carathéodory type selector  $f : [0, T] \times \mathbb{R}^m \rightarrow \mathbb{R}^m$  of  $coF$ . Let  $\mathcal{P} = (\Omega, \mathcal{F}, P)$  be a probability space such that there is a  $d$ -dimensional Brownian motion  $B$  defined on this space. Let  $\mathbb{F} = (\mathcal{F}_t)_{t \geq 0}$  be a natural augmented filtration of  $B$ . Let  $\xi \in \mathcal{B}_\lambda$  be a fixed point of  $h$ , where  $\mathcal{B}_\lambda$  is a closed ball of  $\mathbb{R}^m$  centered at the origin with the radius  $\lambda = L + \int_0^T m(t)dt$ . Define on  $\mathcal{P}_\mathbb{F} = (\Omega, \mathcal{F}, P, \mathbb{F})$  a sequence  $(x^n)_{n=1}^\infty$  of stochastic processes  $x^n = (x_t^n)_{0 \leq t \leq 2T}$  such that  $x_t^n = \xi$  a.s. for  $t \in [T, 2T]$  and  $x_t^n = E[h(\xi) + \int_t^T f(\tau, x_{\tau+T/n}^n d\tau | \mathcal{F}_t)]$  a.s. for  $0 \leq t \leq T$  and  $n = 1, 2, \dots$ . Let us observe that for every  $n \geq 1$  a process  $x^n$  is defined step by step beginning with the interval  $[T - T/n, T]$ . For example, for  $t \in [T - T/n, T]$  we have  $x_t^n = E[h(\xi) + \int_t^T f(\tau, \xi) d\tau | \mathcal{F}_t]$  a.s. For  $t \in [T - 2T/n, T - T/n]$  we have  $x_t^n = E[h(\xi) + \int_t^T f(\tau, \tilde{x}_{\tau+T/n}^n d\tau | \mathcal{F}_t)]$  a.s. with  $\tilde{x}_{\tau+T/n}^n = E[h(\xi) + \int_{\tau+T/n}^T f(u, \xi) du | \mathcal{F}_{\tau+T/n}]$  because  $\tau + T/n \in [T - T/n, T]$ . Let us observe that  $x^n$  is for every  $n \geq 1$  a continuous process because of ([14], Corollary IV.1) a process  $M^n = (M_t^n)_{0 \leq t \leq T}$  defined by

$$M_t^n = E \left[ h(\xi) + \int_0^T f(\tau, x_{\tau+T/n}^n d\tau | \mathcal{F}_t \right] - E \left[ h(\xi) + \int_0^T f(\tau, x_{\tau+T/n}^n d\tau | \mathcal{F}_0 \right]$$

is a continuous  $\mathbb{F}$ -martingale for every  $n \geq 1$ . Similarly as in the proof of Proposition 5.3 we can verify that the sequence  $(x^n)_{n=1}^\infty$  is tight. Then by ([6], Th. I.2.7) there are a probability space  $(\tilde{\Omega}, \tilde{\mathcal{F}}, \tilde{P})$ , a sequence  $(\tilde{x}^{nk})_{k=1}^\infty$  of continuous  $m$ -dimensional stochastic processes  $(\tilde{x}_t^{nk})_{0 \leq t \leq 2T}$  and a continuous stochastic process  $\tilde{x} = (\tilde{x}_t)_{0 \leq t \leq 2T}$  such that  $P(x^{nk})^{-1} = P(\tilde{x}^{nk})^{-1}$  for  $k \geq 1$  and  $\sup_{0 \leq t \leq 2T} |\tilde{x}_t^{nk} - \tilde{x}_t| \rightarrow 0$  a.s. as  $k \rightarrow \infty$ . Let  $\tilde{\mathcal{F}}_t = \bigcap_{\varepsilon > 0} \sigma[\tilde{x}_u : u \leq t + \varepsilon]$  and let  $\phi : C_T \rightarrow \mathbb{R}$  be a continuous and bounded function such that  $\phi$  is  $\beta_s(C_T)$ -measurable, where  $\beta_s(C_T) = \rho_s^{-1}(\beta(C_T))$  with  $\rho_s(x) = x(s \wedge u)$  for  $x \in C_T$  and  $u \in [0, T]$ . Similarly as in the proof of Proposition 5.3 we can verify that  $|x_t^n| \leq \lambda$  a.s. for  $0 \leq t \leq T$  and  $n \geq 1$ , where  $\lambda = L + \int_0^T m(t)dt$ . Hence by the properties of  $\tilde{x}^n$  we also have  $|\tilde{x}_t^n| \leq \lambda$  a.s. for  $0 \leq t \leq T$  and  $n \geq 1$ . Let  $\mathcal{B}_\lambda$  be a closed ball of  $\mathbb{R}^m$  such as above and let  $g : \mathbb{R}^m \rightarrow \mathbb{R}^m$  be a continuous extension of a mapping  $I : \mathcal{B}_\lambda \rightarrow \mathbb{R}^m$  defined by  $I(x) = x$  for  $x \in \mathcal{B}_\lambda$ . We have

$|g(x)| \leq \lambda$  for  $x \in \mathbb{R}^m$ ,  $g(x_t^n) = x_t^n$  and  $g(\tilde{x}_t^n) = \tilde{x}_t^n$  a.s. for  $0 \leq t \leq T$  and  $n \geq 1$ . Therefore,

$$\begin{aligned}
0 &= E \left\{ \phi(x^n) \left( x_s^n - E[x_t^n + \int_s^t f(\tau, x_{\tau+T/n}^n) d\tau | \mathcal{F}_s] \right) \right\} \\
&= E \left\{ E[\phi(x^n) \left( x_s^n - x_t^n - \int_s^t f(\tau, x_{\tau+T/n}^n) d\tau | \mathcal{F}_s \right)] \right\} \\
&= E \left\{ \phi(x^n) \left( g(x_s^n) - g(x_t^n) - \int_s^t f(\tau, x_{\tau+T/n}^n) d\tau \right) \right\} \\
&= \tilde{E} \left\{ \phi(\tilde{x}^n) \left( g(\tilde{x}_s^n) - g(\tilde{x}_t^n) - \int_s^t f(\tau, \tilde{x}_{\tau+T/n}^n) d\tau \right) \right\} \\
&= \tilde{E} \left\{ \phi(\tilde{x}^n) \left( \tilde{x}_s^n - \tilde{x}_t^n - \int_s^t f(\tau, \tilde{x}_{\tau+T/n}^n) d\tau \right) \right\}
\end{aligned}$$

for  $0 \leq s \leq t \leq T$  and  $n \geq 1$ . Hence, it follows

$$\begin{aligned}
&\tilde{E} \left\{ \phi(\tilde{x}) \left( \tilde{x}_s - \tilde{x}_t - \int_s^t f(\tau, \tilde{x}_\tau) d\tau \right) \right\} \\
&= \lim_{n \rightarrow \infty} \tilde{E} \left\{ \phi(\tilde{x}) \int_s^t [f(\tau, \tilde{x}_\tau) - f(\tau, \tilde{x}_{\tau+T/n}^n)] d\tau \right\} \\
&\quad + \lim_{n \rightarrow \infty} \tilde{E} \left\{ \phi(\tilde{x}) [(\tilde{x}_t - \tilde{x}_t^n) - ((\tilde{x}_s - \tilde{x}_s^n))] \right\} + \\
&\lim_{n \rightarrow \infty} \tilde{E} \left\{ \phi(\tilde{x}) \left( \int_s^t [f(\tau, \tilde{x}_{\tau+T/n}^n) - f(\tau, \tilde{x}_{\tau+T/n}^n)] d\tau \right) \right\} \\
&\quad + \lim_{n \rightarrow \infty} \tilde{E} \left\{ (\phi(\tilde{x}) - \phi(\tilde{x}^n)) \left( \tilde{x}_s^n - \tilde{x}_t^n - \int_s^t f(\tau, \tilde{x}_{\tau+T/n}^n) d\tau \right) \right\} = 0
\end{aligned}$$

for  $0 \leq s \leq t \leq T$ , because  $\sup_{0 \leq t \leq T} |\tilde{x}_t^n - \tilde{x}_t| \rightarrow 0$  a.s. as  $n \rightarrow \infty$ ,  $\phi$  and a mapping  $C_T \ni x \rightarrow \int_s^t f(\tau, x_\tau) d\tau \in \mathbb{R}^m$  are continuous on  $C_T$  and  $|\tilde{x}_s^n - \tilde{x}_t^n - \int_s^t f(\tau, \tilde{x}_{\tau+T/n}^n) d\tau| \leq 2\lambda + \int_0^T m(t) dt < \infty$  a.s. By the Monotone Class Theorem ([14], Th. I.1.8) it follows that

$$\tilde{E} \left\{ \psi(\tilde{x}) \left( \tilde{E}[\tilde{x}_s - \tilde{x}_t - \int_s^t f(\tau, \tilde{x}_\tau) d\tau | \tilde{\mathcal{F}}_s] \right) \right\} = 0$$

for  $0 \leq s \leq t \leq T$  and every  $\mathcal{F}_s$ -measurable bounded function  $\psi$  on  $C_T$ , which implies that  $\tilde{E}[\tilde{x}_s - \tilde{x}_t - \int_s^t f(\tau, \tilde{x}_\tau) d\tau | \tilde{\mathcal{F}}_s] = 0$  a.s. for every  $0 \leq s \leq t \leq T$ . Hence by the properties of  $f$ , it follows that  $\tilde{x}_s \in \tilde{E}[\tilde{x}_t + \int_s^t F(\tau, \tilde{x}_\tau) d\tau | \tilde{\mathcal{F}}_s]$  a.s. for  $0 \leq s \leq t \leq T$ . Finally, let us observe that  $\text{dist}(g(x_T^n), H(x_T^n)) = 0$  a.s. for  $n \geq 1$  and a function  $\mathbb{R}^m \ni x \rightarrow \text{dist}(g(x), H(x)) \in \mathbb{R}$  is continuous. Therefore, we also have  $\text{dist}(g(\tilde{x}_T^n), H(\tilde{x}_T^n)) = 0$  a.s. for  $n \geq 1$ , which implies that  $\tilde{x}_T \in H(\tilde{x}_T)$  a.s.  $\square$



## 6. WEAK COMPACTNESS OF SOLUTIONS SET

We shall consider here measurable set-valued mappings  $F$  and  $H$  satisfying conditions (B) and such that  $H$  and  $F(t, \cdot)$  are continuous for a.e. fixed  $t \in [0, T]$ . In what follows we shall say that such  $F$  and  $H$  satisfy conditions (C). Denote by  $\mathcal{X}(F, H)$  the set of all continuous weak solutions to BSDI(F,H). We shall show that if  $F$  and  $H$  satisfy conditions (C) then the set  $\mathcal{X}(F, H)$  is weakly compact with respect to the Prohorov's topology. We begin with the following result.

**Proposition 6.1.** *If  $F$  and  $H$  satisfy conditions (C) and  $\{(\mathcal{P}_{\mathbb{F}^n}^n, x^n)\}_{n=1}^\infty$  is a sequence of  $\mathcal{X}(F, H)$  then there are a complete probability space  $(\tilde{\Omega}, \tilde{\mathcal{F}}, \tilde{P})$  and a sequence  $(\tilde{x}^n)_{n=1}^\infty$  of  $m$ -dimensional continuous stochastic processes  $\tilde{x}^n = (\tilde{x}_t^n)_{0 \leq t \leq T}$  on  $(\tilde{\Omega}, \tilde{\mathcal{F}}, \tilde{P})$  such that  $P^n(x^n)^{-1} = \tilde{P}(\tilde{x}^n)^{-1}$  and such that*

$$\begin{cases} \tilde{x}_s^n \in \tilde{E} \left[ \tilde{x}_t^n + \int_s^t F(\tau, \tilde{x}_\tau^n) d\tau \mid \tilde{\mathcal{F}}_s^n \right] \\ \tilde{x}_T^n \in H(\tilde{x}_T^n) \end{cases}$$

for  $n \geq 1$ , where  $\tilde{\mathcal{F}}_t^n = \bigcap_{\varepsilon > 0} \sigma[\tilde{x}_u^n : u \leq t + \varepsilon]$  for  $n \geq 1$  and  $t \in [0, T]$ .

*Proof.* Similarly as in the proof of ([6], Th. I.2.7) we define  $(\tilde{\Omega}, \tilde{\mathcal{F}}, \tilde{P})$  by taking  $\tilde{\Omega} = [0, 1)$ ,  $\tilde{\mathcal{F}} = \beta([0, 1))$  and  $\tilde{P} = \mu$ , where  $\mu$  is a Lebesgue's measure on  $\tilde{\mathcal{F}}$ . Similarly, we define a sequence  $(\tilde{x}^n)_{n=1}^\infty$  of random variables  $\tilde{x}^n : \tilde{\Omega} \rightarrow C_T$  such that  $P^n(x^n)^{-1} = \tilde{P}(\tilde{x}^n)^{-1}$  for  $n \geq 1$ . By virtue of Theorem 3.1 for every  $n \geq 1$  there are  $f^n \in S_{\mathbb{F}^n}(coF \circ x^n)$  and  $\xi^n \in S(H \circ x_T^n)$  such that  $x_t^n = E^n[\xi^n + \int_t^T f_\tau^n d\tau \mid \mathcal{F}_t^n]$  a.s. for  $0 \leq t \leq T$ . Hence it follows that  $|x_t^n| \leq \lambda$  a.s. for  $n \geq 1$  and  $0 \leq t \leq T$ , where  $\lambda$  is such as above. Let  $g$  and  $\phi$  be such as in the proof of Theorem 5.4. Hence and the properties of Aumann's integral (see [8], Th. II.3.20) we obtain

$$\begin{aligned} E^n \sigma(p, \phi(x^n)g(x_s^n)) &\leq E^n \left\{ \sigma \left( p, E^n[\phi(x^n)(g(x_t^n) + \int_s^t F(\tau, x_\tau^n) d\tau \mid \mathcal{F}_s^n)] \right) \right\} \\ &= E^n \left\{ \sigma \left( p, \phi(x^n)(g(x_t^n) + \int_s^t F(\tau, x_\tau^n) d\tau) \right) \right\} \end{aligned}$$

for  $p \in \mathbb{R}^m$ ,  $n \geq 1$  and  $0 \leq s \leq t \leq T$ , where  $\sigma(p, \cdot)$  is a support function on  $\mathbb{R}^m$ . But  $x^n$  and  $\tilde{x}^n$  have the same distributions and a function defined by superpositions of  $\sigma(p, \cdot)$ ,  $\phi$ ,  $g$  and  $F(t, \cdot)$  is continuous and bounded on  $C_T$ . Then the last inequality implies

$$\tilde{E} \sigma(p, \phi(\tilde{x}^n)g(\tilde{x}_s^n)) \leq \tilde{E} \left\{ \sigma \left( p, \phi(\tilde{x}^n)(g(\tilde{x}_t^n) + \int_s^t F(\tau, \tilde{x}_\tau^n) d\tau) \right) \right\}$$

for  $p \in \mathbb{R}^m$ ,  $n \geq 1$  and  $0 \leq s \leq t \leq T$ . Therefore, for  $n \geq 1$  and  $0 \leq s \leq t \leq T$  one has  $\tilde{E}[\Phi(\tilde{x}^n)\tilde{x}_s^n] \in \tilde{E} \left\{ \Phi(\tilde{x}^n) \left( \tilde{E}[\tilde{x}_t^n + \int_s^t F(\tau, \tilde{x}_\tau^n) d\tau] \right) \right\}$ . Let  $\tilde{f}^n \in S_{\mathbb{F}^n}(coF \circ \tilde{x}^n)$  be such that

$$\tilde{E} \left\{ \phi(\tilde{x}^n) \left( \tilde{x}_s^n - \tilde{x}_t^n - \int_s^t \tilde{f}_\tau^n d\tau \right) \right\} = 0$$

for  $n \geq 1$  and  $0 \leq s \leq t \leq T$ . Hence, similarly as in the proof of Theorem 5.4, it follows that  $\tilde{x}_s^n = \tilde{E}[\tilde{x}_t^n + \int_s^t \tilde{f}_\tau^n d\tau | \tilde{\mathcal{F}}_s^n]$  for  $n \geq 1$  and  $0 \leq s \leq t \leq T$ . Therefore  $\tilde{x}^n$  satisfies the first condition of (9). Similarly as in the proof of Theorem 5.4 we also get  $\tilde{x}_T^n \in H(\tilde{x}_T^n)$  a.s. for  $n \geq 1$ .  $\square$

We can prove now the main result of the section.

**Theorem 6.2.** *If  $F$  and  $H$  satisfy conditions (C) then  $\mathcal{X}(F, H)$  is nonempty weakly compact with respect to the convergence in distributions.*

*Proof.* By virtue of Theorem 5.4 we have  $\mathcal{X}(F, H) \neq \emptyset$ . By virtue of Proposition 6.1 for every sequence  $\{(\mathcal{P}_{\mathbb{F}^n}^n, x^n)\}_{n=1}^\infty$  of  $\mathcal{X}(F, H)$  there are a complete probability space  $(\tilde{\Omega}, \tilde{\mathcal{F}}, \tilde{P})$  and a sequence  $(\tilde{x}^n)_{n=1}^\infty$  of  $m$ -dimensional continuous stochastic processes  $\tilde{x}^n = (\tilde{x}_t^n)_{0 \leq t \leq T}$  on  $(\tilde{\Omega}, \tilde{\mathcal{F}}, \tilde{P})$  such that  $P^n(x^n)^{-1} = \tilde{P}(\tilde{x}^n)^{-1}$  and such that conditions (9) are satisfied. By virtue of Proposition 5.3 a sequence  $(\tilde{x}^n)_{n=1}^\infty$  is tight, which implies the tightness of a given sequence  $(x^n)_{n=1}^\infty$ . Then there is a subsequence  $(x^{n_k})_{k=1}^\infty$  converging in distributions to a probability measure  $\mathcal{P}$  on  $\beta(C_T)$  as  $k \rightarrow \infty$ . By virtue of ([6], Th. I.2.7) there are a complete probability space, denoted again by  $(\tilde{\Omega}, \tilde{\mathcal{F}}, \tilde{P})$  and a sequence  $(\tilde{x}^{n_k})_{k=1}^\infty$  of  $m$ -dimensional continuous stochastic processes  $\tilde{x}^{n_k} = (\tilde{x}_t^{n_k})_{0 \leq t \leq T}$  and a continuous process  $\tilde{x} = (\tilde{x}_t)_{0 \leq t \leq T}$  on  $(\tilde{\Omega}, \tilde{\mathcal{F}}, \tilde{P})$  such that  $P(x^{n_k})^{-1} = P(\tilde{x}^{n_k})^{-1}$  for  $k \geq 1$ ,  $P(\tilde{x})^{-1} = \mathcal{P}$  and  $\sup_{0 \leq t \leq T} |\tilde{x}_t^{n_k} - \tilde{x}_t| \rightarrow 0$  a.s. as  $k \rightarrow \infty$ . Let  $\tilde{\mathcal{F}}_t = \bigcap_{\varepsilon > 0} \sigma[\tilde{x}_u : u \leq t + \varepsilon]$  and let  $\phi : C_T \rightarrow \mathbb{R}$  be a continuous and bounded function such that  $\phi$  is  $\beta_s(C_T)$ -measurable, where  $\beta_s(C_T)$  is such as above. Similarly as in the proofs of Theorem 5.4 and Proposition 6.1 we get

$$\tilde{E}(\phi(\tilde{x})\tilde{x}_s) \in \tilde{E} \left( \phi(\tilde{x})\tilde{E}[\tilde{x}_t + \int_s^t F(\tau, \tilde{x}_\tau)d\tau | \tilde{\mathcal{F}}_s] \right)$$

for  $0 \leq s \leq t \leq T$ . Hence by virtue of Theorem 3.1 there is  $\tilde{f} \in S_{\tilde{\mathbb{F}}}(coF \circ \tilde{x})$  such that

$$\tilde{E} \left( \tilde{E} \left[ \phi(\tilde{x}) \left( \tilde{x}_s - \tilde{x}_t - \int_s^t \tilde{f}_\tau d\tau \right) | \tilde{\mathcal{F}}_s \right] \right) = 0$$

for  $0 \leq s \leq t \leq T$ , which implies that

$$\tilde{E} \left( \phi(\tilde{x}) \left( \tilde{x}_s - \tilde{x}_t - \int_s^t \tilde{f}_\tau d\tau \right) \right) = 0$$

for  $0 \leq s \leq t \leq T$ . Hence, similarly as in the proof of Theorem 5.4 it follows that  $\tilde{x}_s = \tilde{E}[\tilde{x}_t + \int_s^t \tilde{f}_\tau d\tau | \tilde{\mathcal{F}}_s]$  a.s. for every  $0 \leq s \leq t \leq T$ . Then  $\tilde{x}_s \in \tilde{E}[\tilde{x}_t + \int_s^t F(\tau, \tilde{x}_\tau)d\tau | \tilde{\mathcal{F}}_s]$  a.s. for  $0 \leq s \leq t \leq T$ . Similarly as in the proof of Proposition 5.3 we also get  $\tilde{x}_T \in H(\tilde{x}_T)$  a.s. Then there is a subsequence  $(x^{n_k})_{k=1}^\infty$  of a sequence  $(x^n)_{n=1}^\infty$  converging in distributions to a solution  $\tilde{x}$  to BSDI(F,H) on a complete filtered probability space  $\mathcal{P}_{\tilde{\mathbb{F}}} = (\tilde{\Omega}, \tilde{\mathcal{F}}, \tilde{P}, \tilde{\mathbb{F}})$  with a filtration  $\tilde{\mathbb{F}} = (\tilde{\mathcal{F}}_t)_{0 \leq t \leq T}$ . Thus  $\mathcal{X}(F, H)$  is weakly compact with respect to the convergence in distributions.  $\square$

## REFERENCES

- [1] P. Billingsley, *Convergence of Probability Measures*, J. Wiley and Sons, New York Toronto, 1976.
- [2] J.M. Bismut, Conjugate convex functions in optimal stochastic control, *J. Math. Anal. Appl.*, 44: 384–404, 1973.
- [3] R. Buckdahn, H.J. Engelbert and A. Răşcanu, On weak solutions of backward stochastic differential equations, *Theory Probab. Appl.*, 49: 16–50, 2000.
- [4] F. Hiai and H. Umegaki, Integrals, conditional expectations and martingale of multivalued functions, *J. Math. Anal.*, 7:149–182, 1977.
- [5] Sh. Hu and N.S. Papageorgiou, *Handbook of Multivalued Analysis I*, Kluwer Acad. Publ. Dordrecht-Boston, 1997.
- [6] N. Ikeda and S. Watanabe, *Stochastic Differential Equations and Diffusion Processes*, North Holland Publ., Amsterdam, 1981.
- [7] N.E. Kaoui, S. Peng and M.C. Quenez, Backward stochastic differential equations in finance, *Math. Finance*, 7(1):1–71, 1977.
- [8] M. Kisielewicz, *Differential Inclusions and Optimal Control*, Kluwer Acad. Publ., New York, 1991.
- [9] M. Kisielewicz, Tightness of continuous stochastic processes, *Disc. Math. Probability and Statistics*, 27(1), 2007(in press).
- [10] H. Kunita, *Stochastic Flows and Stochastic Differential Equations*, Cambridge Univ. Press, New York, 1990
- [11] K. Kuratowski and C. Ryll-Nardzewski, A general theorem on selectors, *Bull. Polon. Acad. Sci.*, 13:397–403, 1965.
- [12] E. Michael, Continuous selections I, *Ann. Math.*, 63:361 – 382, 1956.
- [13] E. Pardoux and S. Peng, Adapted solutions of a backward stochastic differential equation, *System Control Lett.*, 14:55–61, 1990.
- [14] P.H. Protter, *Stochastic Integration and Differential Equations*, Springer-Verlag, Berlin Heidelberg, 1990.
- [15] L. Rybiński, On Carathéodory type selections, *Fund. Math.*, 125:187–193, 1985.