

**A NEW IMPROVEMENT OF TEMBHURNE-SATHE
MODIFICATION OF EUCLIDEAN ALGORITHM FOR
GREATEST COMMON DIVISOR. IV**

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ABSTRACT: In this note we gave new interpretation of Tembhurne-Sathe modification of Euclidean algorithm for calculation of greatest common divisor (GCD). Our results are different optimized ways of approaches presented in [1]–[26], [44]–[68]. Our approach is about 9% and 69% faster than Tembhurne-Sathe algorithm in iterative and recursive implementations respectively. For computer implementation Visual C# 2017 programming environment is used.

AMS Subject Classification: 11A05, 68W01

Key Words: greatest common divisor, Euclid's algorithm, Tembhurne-Sathe' algorithm, improvement algorithm, 256-bit integers, 512-bit integers, reduced number of iterations

Received: October 17, 2018; **Revised:** January 9, 2019;
Published (online): January 19, 2019 **doi:** 10.12732/dsa.v28i1.8
Dynamic Publishers, Inc., Acad. Publishers, Ltd. <https://acadsol.eu/dsa>

1. INTRODUCTION

Our modifications are based on ideas in [27]–[43]. Here we will describe possible way of optimization of Tembhurne-Sathe' algorithm for GCD. In [68] the authors note that their ModEB algorithm is about 1.54 and 1.68 times faster than the Extended Euclidean and Binary GCD algorithm with 256-bit integers as well as it is about 1.54 and 1.64 times faster than the same algorithms with 512-bit integers. Our motivation here is to give more optimal organization of Tembhurne-Sathe' algorithm.

2. MAIN RESULTS

For testing we will use the following computer: processor - Intel(R) Core(TM) i7-6700HQ CPU 2.60GHz, 2592 Mhz, 4 Core(s), 8 Logical Processor(s), RAM 16 GB, Microsoft Windows 10 Enterprise x64.

Let $a > 0$ and $b > 0$ be natural numbers. Tembhurne-Sathe' algorithm [68] is well-known:

Algorithm 1.

```
static long Euclid(long a, long b)
{ long g = 1;
if (a == b) return a;
if ((a & 1) == 0 && (b & 1) == 0)
do { a >>= 1; b >>= 1; g <<= 1;
if (b == 1) return g; } while ((a & 1) == 0 && (b & 1) == 0);
while (b > 1) { a %= b; b = Math.Abs(b - a);
if (a < b) { long tmp = a; a = b; b = tmp; }
if ((a & 1) == 0) do { a >>= 1; if (a == 1) return g; }
while ((a & 1) == 0);
if ((b & 1) == 0) do { if (b == 0) break; b >>= 1; }
while ((b & 1) == 0); }
if (b == 1) return g; else return g * a; }
```

Its recursive implementation is:

Algorithm 2.

```
static long Euclid(long a, long b)
{ if (a == b) return a;
if ((a & 1) == 0 && (b & 1) == 0)
return Euclid(a >> 1, b >> 1) << 1;
a %= b; b = Math.Abs(b - a);
if (a > b) { if ((a & 1) == 0) { a >>= 1; if (a == 1) return 1; }
if ((b & 1) == 0) { if (b == 0) return a; b >>= 1; } }
else { if ((b & 1) == 0) { b >>= 1; if (b == 1) return 1; }
if ((a & 1) == 0) { if (a == 0) return b; a >>= 1; } }
return Euclid(a, b); }
```

We suggest the following optimized realization of Algorithm 1

Algorithm 3.

```
static long Euclid(long a, long b)
{ int k = 0, g = 1;
```

```

if ((a & 1) == 0 && (b & 1) == 0) do
{ a >>= 1; b >>= 1; k++; }
while ((a & 1) == 0 && (b & 1) == 0);
g <<= k;
do { if (a > b) { a %= b; b = b - a;
if ((b & 1) == 0) do { b >>= 1; if (b == 1) return g; }
while ((b & 1) == 0);
if ((a & 1) == 0) do { if (a == 0) return b << k; a >>= 1; }
while ((a & 1) == 0);
b %= a; a = a - b;
if ((a & 1) == 0) do { a >>= 1; if (a == 1) return g; }
while ((a & 1) == 0);
if ((b & 1) == 0) do { if (b == 0) return a << k; b >>= 1; }
while ((b & 1) == 0); }
else { b %= a; a = a - b;
if ((a & 1) == 0) do { a >>= 1; if (a == 1) return g; }
while ((a & 1) == 0);
if ((b & 1) == 0) do { if (b == 0) return a << k; b >>= 1; }
while ((b & 1) == 0);
a %= b; b = b - a;
if ((b & 1) == 0) do { b >>= 1; if (b == 1) return g; }
while ((b & 1) == 0);
if ((a & 1) == 0) do { if (a == 0) return b << k; a >>= 1; }
while ((a & 1) == 0); }
} while (true); }

```

and its recursive presentation

Algorithm 4.

```

static long Euclid(long a, long b)
{ if ((a & 1) == 0 && (b & 1) == 0)
return Euclid(a >> 1, b >> 1) << 1;
if (a > b) { a %= b; b = b - a;
if ((b & 1) == 0) { b >>= 1; if (b == 1) return 1; }
if ((a & 1) == 0) { if (a == 0) return b; a >>= 1; }
b %= a; a = a - b;
if ((a & 1) == 0) { a >>= 1; if (a == 1) return 1; }
if ((b & 1) == 0) { if (b == 0) return a; b >>= 1; } }
else { b %= a; a = a - b;
if ((a & 1) == 0) { a >>= 1; if (a == 1) return 1; }
if ((b & 1) == 0) { if (b == 0) return a; b >>= 1; } }
}

```

```

a %= b; b = b - a;
if ((b & 1) == 0) { b >>= 1; if (b == 1) return 1; }
if ((a & 1) == 0) { if (a == 0) return b; a >>= 1; } }
return Euclid(a, b); }

```

3. NUMERICAL EXPERIMENT

Part 1. This part is implemented for all Algorithms 1–4.

```

long a, b, gcd, d = 0;
for (int i = 1; i < 100000001; i++) { b = i; a = 200000002 - i;
//here is the calling of every of Algorithms 1–4
d += gcd; }
Console.WriteLine(d);

```

Part 2. This part is implemented for Algorithms 1 and 2 only! We will use the task from Part 1. where we swapped the values of ‘a’ and ‘b’.

Part 3. Average time of performance for Algorithms 1 and 2 only!

$EN = (\text{Part 1. Algorithm } N + \text{Part 2. Algorithm } N) / 2,$
where $N = 1$ to 2 denotes using of Algorithms 1 and 2.

Recursive and iterative implementation of algorithms 1 and 2 can be called by:
if ($a > b$) gcd = Euclid(a, b); else gcd = Euclid(b, a);

Recursive and iterative implementations of algorithms 3 and 4 can be called by:
gcd = Euclid(a, b);

The reader can see advantages of our new realizations Algorithm 4 and Algorithm 3 in both recursive (see Fig. 1) and iterative (see Fig. 2) implementations.

ACKNOWLEDGMENTS

This work has been supported by D01-205/23.11.2018 National Scientific Program ”Information and Communication Technologies for a Single Digital Market in Science, Education and Security (ICTinSES)”, financed by the Ministry of Education and Science, Bulgaria.

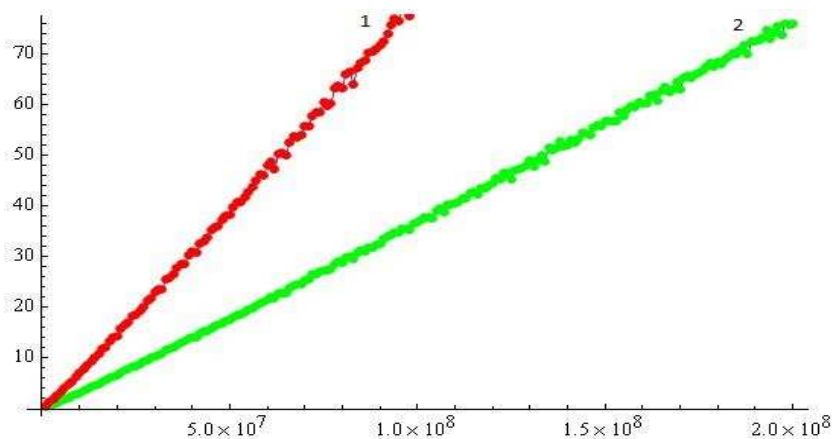


Figure 1: Algorithm 2 - Tembhurne-Sathe recursive (1 – red color), Algorithm 4 - Iliev–Kyurkchiev–Rahnev recursive (2 – green line)

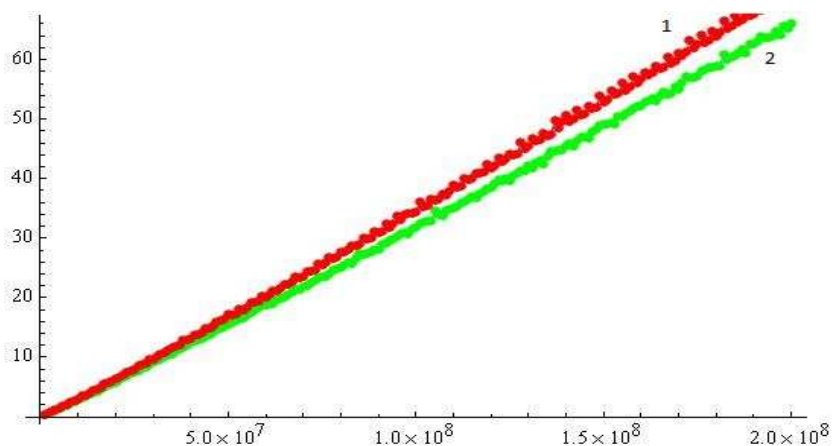


Figure 2: Algorithm 1 - Tembhurne-Sathe iterative (1 – red color), Algorithm 3 - Iliev–Kyurkchiev–Rahnev iterative (2 – green line)

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